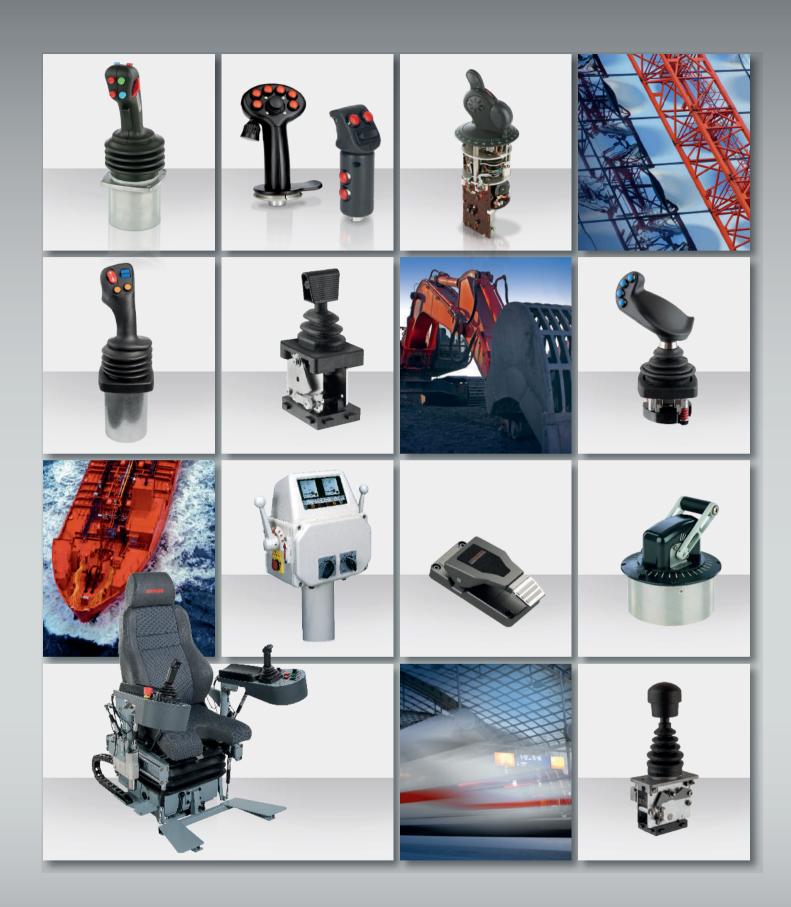
# **Industrial Controllers Catalog**









Joysticks with hallsensor-technology

Joysticks with contacts and potentiometer

Control-Switches

Steering Column Switch

**Opto-Electronic Encoders** 

Control Elements

Palm Grips

**Control Console** 

**Foot Pedals** 

Crane Control Units

Driver's Seats

Portable Control Units

**Industrial Controllers** 

Gear Limit Switches

Naval Cruise Controller

Control Pedestals for offshore

As of 2021

#### Tool for Designers, Engineers and Purchasing Agents

Your tool for finding industrial controllers for cranes, electro-hydraulic systems, floor conveyors, industrial applications, ships, rail vehicles, and construction machinery of any kind, joysticks and masterswitches with electronic interface adjustment for all machines matching our product portfolio. Take advantage of our fold-out order tool on this page and the detailed tables of contents at the beginning of each position.



#### **Product Portfolio**

Gessmann is an international market leader. Our success in the market is based upon our decisive focus on innovative product development and the highest possible standards when it comes to quality. Our product range includes:

- Joysticks (Multi-Axis Controller, Double-Handle Controller, Control Switch), Gear Limit Switch for hoisting, Electro-hydraulic Application, Material-handling technology and Remote Control
- Gear limit switch for joisting equipment
- Complete Crane Control Unit, Portable Control Unit, Pendant Control Unit, including wiring for all types of cranes, vehicles and industrial applications
- Operating Panels for construction machinery, industrial applications, vehicles and harvesting machines
- Control Pedestals, ship-operating transmitters, sensor units and actual-value transmitters for ship drives
- Pedal Controllers for welding machines, road and rail vehicles
- Master Controllers, panels and control stations for rail vehicles
- Displays for forklifts and construction machinery
- Proportional control electronics for solenoid valves
- Interface electronics with digital and analog outputs matching our controllers
- Interface electronics with Profibus interface or CAN-bus interface matching our controllers (input/output cards)
- DC controllers, selector switches (signal controllers) for high-voltage systems
- Customized solutions for operating devices and electronic units for any type of machinery and vehicles

Management certification:





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Inc	lustria	IJον	ysticks

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#### **General Terms and Conditions**



For our general conditions for sale and delivery please refer to our website at www.gessmann.com

#### Please also note:

The prices are ex-works in Leingarten excluding packaging. Packaging is charged at cost and cannot be returned. For orders below EURO 150.00 our gross prices are applicable. The minimum invoice amount is EURO 80.00, regardless of the value of the delivered goodp. Therefore, we recommend combining small orderp.

We are entitled to pass on any additional handling and production costs resulting from modifications to the order caused or requested by the customer (both technical modifications and non-compliance with deadlines).

Our periods of payment are: 30 days without a discount. These conditions of payment shall be deemed agreed and accepted upon receipt of our written confirmation of order.

All delivered goods shall remain our sole and absolute property until full payment is received.

The delivery period only commences upon clarification of all technical detailp. Unforeseen circumstances justify an appropriate extension of the delivery period. All documents, such as drawings, dimensional drawings, circuit diagrams, etc., are non-binding. We reserve the right to make any changes necessary, in particular changes which serve the technical advancement.

The exclusive place of jurisdiction is 74072 Heilbronn, Germany.



Certain parts of this electrical device carry hazardous voltages when in

Installation, maintenance, modification or retrofitting may only be carried out by qualified personnel in consideration of the appropriate safety precautionp.

Non-compliance may result in death, severe injuries or substantial property damage.

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**Commercial Register** Stuttgart HRB 100312

Managing Director: Alwin Ehrensperger





The V85/VV85 is a robust joystick commonly used in electro-hydraulic applications. Long life and high reliability is ensured by the latest contactless hall-technology. With many outputs and grip options the V85/VV85 series is flexible and customisable.

#### **Technical data**

Mechanical life V85 10 million operating cycles Mechanical life VV85 20 million operating cycles

Supply voltage See interface -40°C to +85°C Operation temperature Degree of protection up to IP67

PLd compatible (EN ISO 13849, complies Functional safety

SIL2 to DIN EN IEC 61508)



Example **VV85** S8 +R11 -B Т -Z80 -E... -S... -X **Basic unit** V85.1 1-axis V85 2-axis Reinforced version VV85.1 1-axis VV85 Control-handle extended Standard 160 mm\* S5 -20 mm S8 +20 mm \*Only available in combination with a handle! Gate Р Cross gate PXSpecial gate Grip / Palm Grip Knob (included in basic unit!) M Knob with mechanical zero interlock Т Dead man Н Signal button D Push button В.. Palm Grip B... (see page Palm Grip 154)



		VV85	S8	Р	Т	-Z80	+R11	-В	-E	-S	-X
A : 4	1.8 *- 9 (										
Z	/ Axis 2 (not applied for V/VV85.1)  Spring return										
R	Friction brake*										
IX.	Latching:*										
11	1-0-1										
22	2-0-2										
33	3-0-3										
44	4-0-4										
55	5-0-5										
08	end-position latching SR2 or SR4										
19	1-0-1 + end-position latching SR2 or SR4										
80	end-position latching SR1 or SR3										
91	1-0-1 + end-position latching SR1 or SR3										
88	end-position latching SR1 + SR2 or SR3 + SR4										
99	1-0-1 + end-position latching SR1 + SR2 or SR3 + SR4										
*Maxin	num deflection angle +/- 25°!										
Degree	e of protection										
	0 1 : " 1 1 1 : 1 : ::1)										
В	Cover housing (included in basic unit!)										
B B10	Joystick-main board sealed (IP67)										
		ıled, grip	with draii	n hole							
B10 B11	Joystick-main board sealed (IP67)		with draii	n hole							
B10 B11	Joystick-main board sealed (IP67)  Joystick-main board sealed (IP67) and grip function sea		with draiı	n hole							
B10 B11 For a so	Joystick-main board sealed (IP67)  Joystick-main board sealed (IP67) and grip function sea		with draiı	n hole							
B10 B11 For a so	Joystick-main board sealed (IP67)  Joystick-main board sealed (IP67) and grip function sea chematic description of the protection class, see page 121		with draiı	n hole							
B10 B11 For a so	Joystick-main board sealed (IP67)  Joystick-main board sealed (IP67) and grip function sea chematic description of the protection class, see page 121  ce (description see on the following pages)		with draiı	n hole							
B10 B11 For a so Interfa E0xx	Joystick-main board sealed (IP67)  Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages)  Switching output		with drain	n hole							
B10 B11 For a so Interfa E0xx E1xx	Joystick-main board sealed (IP67)  Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages)  Switching output  Voltage output		with drain	n hole							
B10 B11 For a so  Interfa E0xx E1xx E2xx	Joystick-main board sealed (IP67) Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages) Switching output Voltage output Current output		with drain	n hole							
B10 B11 For a so Interfa E0xx E1xx E2xx E3xx	Joystick-main board sealed (IP67) Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages) Switching output Voltage output Current output CAN-interface		with drain	n hole							
B10 B11 For a so  Interfa E0xx E1xx E2xx E3xx E4xx	Joystick-main board sealed (IP67) Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages) Switching output Voltage output Current output CAN-interface CANopen Safety interface		with drain	n hole							
B10 B11 For a so  Interfa E0xx E1xx E2xx E3xx E4xx E5xx	Joystick-main board sealed (IP67) Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages) Switching output Voltage output Current output CAN-interface CANopen Safety interface Profibus DP-interface		with drain	n hole							
B10 B11 For a so Interfa E0xx E1xx E2xx E3xx E4xx E5xx E6xx	Joystick-main board sealed (IP67) Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages) Switching output Voltage output Current output CAN-interface CANopen Safety interface Profibus DP-interface Profinet		with drain	n hole							
B10 B11 For a so  Interfa E0xx E1xx E2xx E3xx E4xx E5xx E6xx E6xx E7xx	Joystick-main board sealed (IP67) Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages) Switching output Voltage output Current output CAN-interface CANopen Safety interface Profibus DP-interface PROFIsafe		with drain	n hole							
B10 B11 For a so  Interfa E0xx E1xx E2xx E3xx E4xx E5xx E6xx E6xx E7xx	Joystick-main board sealed (IP67) Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages)  Switching output  Voltage output  Current output  CAN-interface  CANopen Safety interface  Profibus DP-interface  Profinet  PROFIsafe  PWM - Output		with drain	n hole							
B10 B11 For a so Interfa E0xx E1xx E2xx E3xx E4xx E5xx E6xx E7xx E8xx E9xx	Joystick-main board sealed (IP67) Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages)  Switching output  Voltage output  Current output  CAN-interface  CANopen Safety interface  Profibus DP-interface  Profinet  PROFIsafe  PWM - Output		with drain	n hole							
B10 B11 For a so Interfa E0xx E1xx E2xx E3xx E4xx E5xx E6xx E7xx E8xx E9xx	Joystick-main board sealed (IP67) Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages) Switching output Voltage output Current output CAN-interface CANopen Safety interface Profibus DP-interface Profinet PROFIsafe PWM - Output Other outputs		with drain	n hole							
B10 B11 For a so  Interfa E0xx E1xx E2xx E3xx E4xx E5xx E6xx E7xx E8xx E9xx	Joystick-main board sealed (IP67) Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages) Switching output Voltage output Current output CAN-interface CANopen Safety interface Profibus DP-interface Profinet PROFIsafe PWM - Output Other outputs		with drain	n hole							
B10 B11 For a so Interfa E0xx E1xx E2xx E3xx E4xx E5xx E6xx E7xx E8xx E9xx  Plug co	Joystick-main board sealed (IP67) Joystick-main board sealed (IP67) and grip function seachematic description of the protection class, see page 121  ce (description see on the following pages) Switching output Voltage output Current output CAN-interface CANopen Safety interface Profibus DP-interface Profinet PROFIsafe PWM - Output Other outputs		with drain	n hole							



#### Combination possibilities with our grips



Digital output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	72 mm (reduced mounting depth on request!)			
Wiring	1. cable $14 \times 0.25 \text{ mm}^2 500 \text{ mm}$ long without plu	g connector		
	2. cable $14 \times 0.25 \text{ mm}^2$ (optional for grip function	ı) 500 mm long without plug connector		
	Optional with plug connector (standard plug con	nectors see page 120)		S
2 Direction signals + 1 zero pos	ition signal (galvanically isolated) per axis			
		1 axis	E001 1	
		2 axis	2	

Voltage output (not stabilized	d)			
Supply voltage	4,75-5,25 V DC			
Current carrying capacity	Direction signal 8 mA			
Mounting depth A	72 mm (reduced mounting depth on request!)			
Wiring	1. cable $14 \times 0.25 \text{ mm}^2 500 \text{ mm}$ long without plu	g connector		
	2. cable $14 \times 0.25 \text{ mm}^2$ (optional for grip function	) 500 mm long without plug connector		
	Optional with plug connector (standard plug con	nectors see page 120)		S
0,52,54,5 V redundant + 2	direction signals per axis			
		1 axis	E104 1	
		2 axis	2	
		Output options		
		Characteristic:		
		Inverse dual		1
		Dual		2
		Inverse dual with dead zone +/- 3° (standard)		3
		Dual with dead zone +/- 3°		4





Supply voltage	9-32 V DC (*11,5-32)		
Current carrying capacity	Direction signal 150 mA		
	Zero position signal 500 mA		
lounting depth A	72 mm (reduced mounting depth	n on request!)	
ption	Input for capacitive sensor		
/iring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm l	long without plug connector	
J		for grip function) 500 mm long without plug conn	nector
		andard plug connectors see page 120)	
5 2 5 4 5 V redundant + 3	2 direction signals + 1 zero position sig		
52/5 1/5 V reduridant · 2	- direction signals + 1 zero position sig	1 axis	E1121
		2 axis	2
		3 axis*	3
		4 axis*	4
.510 V redundant + 2 dire	ection signals + 1 zero position signal	(galvanically isolated) per axis, supply voltage 11,	
		1 axis	E132 1
		2 axis	2
		3 axis*	3
		4 axis*	4
010 V + 2 direction sign	nals + 1 zero position signal (galvanica	ally isolated) per axis, supply voltage 11,5 - 32 V D	C,
nsor redundant with error r	monitoring and error signal		
		1 axis	E136 1
		2 axis	2
		3 axis*	3
		4 axis*	4
10010 V + 2 direction si	gnals + 1 zero position signal (galvani	cally isolated) per axis, supply voltage 11,5 - 32 V	DC,
edundant sensor with error r	monitoring		
		1 axis	E138 1
		1 axis 2 axis	E138 1
		2 axis	2
		2 axis 3 axis*	2
		2 axis 3 axis* 4 axis*	2
		2 axis 3 axis* 4 axis*  Output options	2
		2 axis 3 axis* 4 axis*  Output options Characteristic:	2 3 4
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1	2 3 4
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/- 3	2 3 4
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/- 3° *1	2 3 4 1 2 3° *1 (standard) 3 4
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/- 3	2 3 4 1 2 3° *1 (standard) 3 4
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/- 3 Dual with dead zone +/- 3° *1 *1 not combinable with output E	2 3 4 1 2 3° *1 (standard) 3 4
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/-: Dual with dead zone +/-: *1 not combinable with output E  Single *2	2 3 4 1 2 3° *1 (standard) 3 4 136X + E138X
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/- 3° *1 *1 not combinable with output E  Single *2 Single with dead zone *2 (standa	2 3 4 1 2 3° *1 (standard) 3 4 136X + E138X 5 ard) 6
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/-: Dual with dead zone +/-: *1 not combinable with output E  Single *2	2 3 4 1 2 3° *1 (standard) 3 4 136X + E138X 5 ard) 6
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/- 3 Dual with dead zone +/- 3° *1 *1 not combinable with output E  Single *2 Single with dead zone *2 (standa *2 not combinable with output E	2 3 4 1 2 3° *1 (standard) 3 4 136X + E138X 5 ard) 6
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/- 3 Dual with dead zone +/- 3° *1 *1 not combinable with output E  Single *2 Single with dead zone *2 (standa *2 not combinable with output E  Digital output signals:	2 3 4  1 2 3° *1 (standard) 3 4  136X + E138X  5 ard) 6
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/- 3° *1 *1 not combinable with output E  Single *2 Single with dead zone *2 (standa *2 not combinable with output E  Digital output signals: Output signals standard:	2 3 4  1 2 3° *1 (standard) 3 4  136X + E138X  5 ard) 6  112X and E132X
		2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/- 3 Dual with dead zone +/- 3° *1 *1 not combinable with output E  Single *2 Single with dead zone *2 (standa *2 not combinable with output E  Digital output signals:	2 3 4  1 2 3° *1 (standard) 3 4  136X + E138X  5 ard) 6  112X and E132X
uxis for arin functions inter-	face can vary depending upon actuati	2 axis 3 axis* 4 axis*  Output options Characteristic: Inverse dual *1 Dual *1 Inverse dual with dead zone +/- 3 Dual with dead zone +/- 3° *1 *1 not combinable with output E  Single *2 Single with dead zone *2 (standa *2 not combinable with output E  Digital output signals: Output signals standard: Direction signals and zero position	2 3 4  1 2 3° *1 (standard) 3 4  136X + E138X  5 ard) 6  112X and E132X



Current output				
Supply voltage	9-32 V DC			_
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	72 mm (reduced mounting depth on reques	t!)		
Option	Input for capacitive sensor			
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long witho	ut plug connector		
	2. cable 14 x 0,25 mm <sup>2</sup> (optional for grip fu		or	
	Optional with plug connector (standard plu			S
01020 mA + 2 direction si	gnals + 1 zero position signal (galvanically isolat	ed) per axis, sensor redundant		
with error monitoring and error	or signal			
		1 axis	E206 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
20020 mA + 2 direction si	gnals + 1 zero position signal (galvanically isolat	ed) per axis, sensor redundant		
with error monitoring and error				
		1 axis	E208 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
41220 mA + 2 direction si	gnals + 1 zero position signal (galvanically isolat			
with error monitoring and error				
, , , , , , , , , , , , , , , , , , ,		1 axis	E214 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
20420 mA + 2 direction si	gnals + 1 zero position signal (galvanically isolat	ed) per axis, sensor redundant		
with error monitoring and error				
-		1 axis	E216 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
+20020 mA + 2 direction	signals + 1 zero position signal (galvanically isol	ated) per axis, sensor redundant		
with error monitoring				
		1 axis	E226 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
		Output options		
		Single		5
		Single with dead zone +/- 3° (standard)		6
		Digital output signales		
		Digital output signals:		
		Output signals standard:	olo 1 FA 24 V DC	1
		Direction signals and zero position signal	115 1,5A 24 V DC	1
*Avia for aris for all the first		si .		
	ace can vary depending upon actuation elemen	u.		
Current output with other value	ue on request!			





CAN			
Supply voltage	9-32 V DC		
Idle current consumption	120 mA (24 V DC)		
Current carrying capacity	Direction signal 100 mA		
	Zero position signal 100 mA (potential-free)		
	External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs)		
	Digital switching output (potential-free) 100 mA		
Mounting depth A	E3091: 72 mm		
	E3091X: 85 mm		
	E3101X - E3103X: 85 mm		
	E3104X - E3105X: 105 mm		
	(reduced mounting depth on request!)		
Protocol	CANopen CiA DS 301 or SAE J1939 (based on)		
Baud rate	20 kBit/s to 1 Mbit/s (standard 250 kBit/s)		
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)		
	CAN (OUT) cable 300 mm with plug connector M12 (female)		
	External in-/outputs cable 300 mm long without plug connector		
	External in-/outputs cable 300 mm long without plug connector (additionally from 32 in-/outputs)		
	Optional with plug connector (standard plug connectors see page 120)		S
CAN expansion stage 1		E309 1	
- 7 analog joystick axis			
- 16 digital joystick functions			
- Input for capacitive sensor			
With additional external in-/out	tputs		
- 8 external LED-outputs (dimm	nable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs	2	
- 16 external LED-outputs (dim	mable optional), 1 switching output (potential-free, 100 mA), 16* external digital inputs	3	
*External LED-outputs can be u	used for LEDs in the grip		
*With the use of capacitive sen	sor, the external digital inputs are reduced by one input!		
CAN expansion stage 2		E310 1	
- 10 analog joystick axis			
- 16 digital joystick functions			
- 2 inputs for capacitive sensors	s		
With additional external in-/out	tputs		
- 8 external LED-outputs (dimm	nable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs	2	
- 16 external LED-outputs (dim	mable optional), 1 switching output (potential-free, 100 mA), 16 external digital inputs	3	
- 24 external LED-outputs (dim	mable optional), 1 switching output (potential-free, 100 mA), 24 external digital inputs	4	
- 32 external LED-outputs (dim	mable optional), 1 switching output (potential-free, 100 mA), 32* external digital inputs	5	
*External LED-outputs can be u	used for LEDs in the grip		
*With the use of two capacitive	e sensors, the external digital inputs are reduced by one input!		
Main-axis with additional digita	ıl-/analog outputs separately wired (not via CAN)		
- 2 direction signals + 1 zero po	sition signal (potential-free) per main-axis		3



CANopen Safety			
Supply voltage	9-32 V DC		
Idle current consumption	120 mA (24 V DC)		
Current carrying capacity	Direction signal 100 mA		
	Zero position signal 100 mA (potential-free)		
	External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs)		
	Digital switching output (potential-free) 100 mA		
Mounting depth A	E4091: 72 mm		
	E4091X: 85 mm		
	E4101X - E4103X: 85 mm		
	E4104X - E4105X: 105 mm		
	(reduced mounting depth on request!)		
Protocol	CANopen Safety EN50325-5		
Baud rate	20 kBit/s to 1 MBit/s (standard 250 kBit/s)		
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)		
	CAN (OUT) cable 300 mm with plug connector M12 (female)		
	External in-/outputs cable 300 mm long without plug connector		
	External in-/outputs cable 300 mm long without plug connector (additionally from 32 in-/outputs	s)	
	Optional with plug connector (standard plug connectors see page 120)		S
CANopen Safety expansion st	tage 1	E409 1	
- 7 analog joystick axis			_
- 16 digital joystick functions			_
- Input for capacitive sensor			_
			_
With additional external in-/out	tputs		
- 8 external LED-outputs (dimm	nable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs	2	_
- 16 external LED-outputs (dim	mable optional), 1 switching output (potential-free, 100 mA), 16* external digital inputs	3	_
*External LED-outputs can be u	used for LEDs in the grip		
*With the use of capacitive sen	nsor, the external digital inputs are reduced by one input!		
CANopen Safety expansion st	tage 2	E4101	-
- 10 analog joystick axis			_
- 16 digital joystick functions			_
- 2 inputs for capacitive sensor	s		
			_
With additional external in-/out	tputs		_
- 8 external LED-outputs (dimm	nable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs	2	
- 16 external LED-outputs (dim	mable optional), 1 switching output (potential-free, 100 mA), 16 external digital inputs	3	_
- 24 external LED-outputs (dim	mable optional), 1 switching output (potential-free, 100 mA), 24 external digital inputs	4	_
- 32 external LED-outputs (dim	mable optional), 1 switching output (potential-free, 100 mA), 32* external digital inputs	5	_
*External LED-outputs can be u	used for LEDs in the grip		
*With the use of two capacitive	e sensors, the external digital inputs are reduced by one input!		
	al outputs separately wired (not via CAN)		
	osition signal (potential-free) per main-axis		3
Additional analog outputs on re	equest!		



Profibus DP			
Supply voltage	18-30 V DC		
Baud rate	to 12 MBit/s		
Output value	0128255		
Mounting depth A	105 mm (reduced mounting depth on request!)		
Wiring	Profibus, cable 100 mm with plug connector D-Sub 9		
	Supply voltage (if applicable contact wiring) cable $12 \times 0.25 \text{ mm}^2 300 \text{ mm}$ long without plug contact wiring)	nector	
	External in-/outputs, cable 300 mm long without plug connector		
	Optional with plug connector (standard plug connectors see page 120)		S
Profibus DP		E501 1	•
- 4 analog joystick axis			•
- 16 digital joystick functions			•
- Input for capacitive sensor			•
With additional external in-/outp	puts		•
- 8 external LED-outputs, 8 exte	rnal digital inputs	2	•
- 16 external LED-outputs, 16 ex	xternal digital inputs	3	
*External LED-outputs can be us	sed for LEDs in the grip		•
Main-axis with additional contact	ct equipment separately wired (not via profibus)		
- 2 direction contacts + 1 zero po	osition contact (not potential-free) per main-axis		1
- 1 zero position contact (potent	tial-free) per main-axis		2

Profinet			
Supply voltage	18-30 V DC		
Baud rate	to 100 MBit/s		
Output value	05121023		
Mounting depth A	85 mm (reduced mounting depth on request!)		
Wiring	Profinet (1), cable 300 mm with M12 plug connector (female)		
	Profinet (2), cable 300 mm with M12 plug connector (female)		
	Supply voltage (if applicable contact wiring) cable $12 \times 0.25 \text{ mm}^2 300 \text{ mm}$ long without plug contact wiring)	nector	
	External in-/outputs, cable 300 mm long without plug connector		
	Optional with plug connector (standard plug connectors see page 120)		S
Profinet		E601 1	
- 4 analog joystick axis			
- 16 digital joystick functions			
- Input for capacitive sensor			
With with additional external in-	/outputs		
- 8 external LED-outputs, 8 exte	rnal digital inputs	2	
- 16 external LED-outputs, 16 ex	kternal digital inputs	3	
*External LED-outputs can be us	sed for LEDs in the grip		
Main-axis with additional signals	s separately wired (not via profinet)		
- 2 direction signals + zero posit	ion signal (potential-free) per main-axis		3



PROFIsafe							
Supply voltage	18-30 V DC						
Baud rate	to 100 MBit/s						
Output value	05121023						
Mounting depth A	85 mm (reduced mounting depth on request!)						
Wiring	Profinet (IN), cable 300 mm with M12 plug connector (female)						
	Profinet (OUT), cable 300 mm with M12 plug connector (female)						
	Supply voltage (if applicable contact wiring) cable 12 x 0,25 mm <sup>2</sup> 300 mm long without plug co	onnector					
	External in-/outputs, cable 300 mm long without plug connector	cternal in-/outputs, cable 300 mm long without plug connector					
	Optional with plug connector (standard plug connectors see page 120)		S				
- 4 analog joystick axis		E701 1					
- 16 digital joystick function	ns						
- Input for capacitive senso	ır						
With additional external in-	/outputs						
- 8 external LED-outputs, 8	external digital inputs	2					
- 16 external LED-outputs,	16 external digital inputs	3					
*External LED-outputs can	be used for LEDs in the grip						
Enternal LLD Gatpats carr							
Main-axis with additional si	ignals separately wired (not via profinet safe)	_					
Main-axis with additional si - 2 direction signals + zero p	ignals separately wired (not via profinet safe) position signal (potential-free) per main-axis		3				
Main-axis with additional si - 2 direction signals + zero p	position signal (potential-free) per main-axis		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage	position signal (potential-free) per main-axis 9-32V DC		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current	9-32V DC max. 3 A		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency	9-32V DC max. 3 A 1225 Hz		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency  Mounting depth A	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!)		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!) Creep speed per axis		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency  Mounting depth A	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!) Creep speed per axis 5 configurable switching outputs 2A		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency  Mounting depth A	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!) Creep speed per axis 5 configurable switching outputs 2A LED outputs for status indication		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency  Mounting depth A  Other features	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!) Creep speed per axis 5 configurable switching outputs 2A LED outputs for status indication Input for redundant deadman		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency  Mounting depth A	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!) Creep speed per axis 5 configurable switching outputs 2A LED outputs for status indication Input for redundant deadman Built-in socket Phoenix 2-pole (power supply)		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency  Mounting depth A  Other features	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!) Creep speed per axis 5 configurable switching outputs 2A LED outputs for status indication Input for redundant deadman Built-in socket Phoenix 2-pole (power supply) Cable 1 (PWM) 12 x 1mm² 300 mm long without plug		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency  Mounting depth A  Other features	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!) Creep speed per axis 5 configurable switching outputs 2A LED outputs for status indication Input for redundant deadman Built-in socket Phoenix 2-pole (power supply)		3				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency  Mounting depth A  Other features	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!) Creep speed per axis 5 configurable switching outputs 2A LED outputs for status indication Input for redundant deadman Built-in socket Phoenix 2-pole (power supply) Cable 1 (PWM) 12 x 1mm² 300 mm long without plug Cable 2 (switching output) 12 x 1mm² 300 mm long without plug		3 S				
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency  Mounting depth A  Other features  Wiring:	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!) Creep speed per axis 5 configurable switching outputs 2A LED outputs for status indication Input for redundant deadman Built-in socket Phoenix 2-pole (power supply) Cable 1 (PWM) 12 x 1mm² 300 mm long without plug Cable 2 (switching output) 12 x 1mm² 300 mm long without plug Cable 3 (creep speed / dead man) 14x0,25mm² 300mm long without plug	E8011					
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency  Mounting depth A  Other features  Wiring:	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!) Creep speed per axis 5 configurable switching outputs 2A LED outputs for status indication Input for redundant deadman Built-in socket Phoenix 2-pole (power supply) Cable 1 (PWM) 12 x 1mm² 300 mm long without plug Cable 2 (switching output) 12 x 1mm² 300 mm long without plug Cable 3 (creep speed / dead man) 14x0,25mm² 300mm long without plug Optional with plug connector (standard plug connectors see page 120)	E801 1					
Main-axis with additional si - 2 direction signals + zero p  PWM Outputs  Supply Voltage  Valve control current  PWM-frequency  Dither frequency  Mounting depth A  Other features  Wiring:	9-32V DC max. 3 A 1225 Hz 1250 Hz adjustable 85 mm (reduced mounting depth on request!) Creep speed per axis 5 configurable switching outputs 2A LED outputs for status indication Input for redundant deadman Built-in socket Phoenix 2-pole (power supply) Cable 1 (PWM) 12 x 1mm² 300 mm long without plug Cable 2 (switching output) 12 x 1mm² 300 mm long without plug Cable 3 (creep speed / dead man) 14x0,25mm² 300mm long without plug Optional with plug connector (standard plug connectors see page 120)						

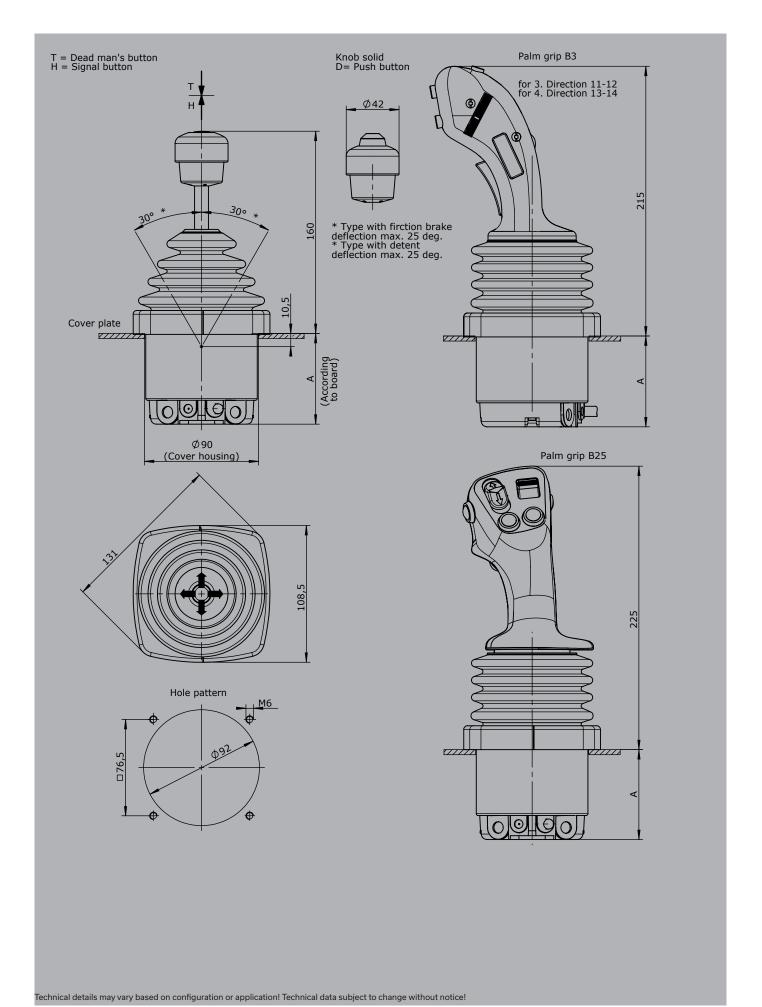




Other outputs							
Voltage output for PVG32 0,2	50,50,75Us, power supply 9-32 V DC						
Mounting depth A	72 mm (reduced mounting depth on request!)						
Option	Input for capacitive sensor						
Wiring	1. cable 14 x 0,25 mm² 300 mm long without plug connector						
	2. cable $14 \times 0.25 \; \text{mm}^2 \; 300 \; \text{mm}$ long without plug connector (optional for	grip function)					
	Optional with plug connector (standard plug connectors see page 120)			S			
		1 axis	E907 1				
		2 axis	2				
		3 axis	3				
		4 axis	4				
		5 axis	5				
		6 axis	6				
Main-axis with additional direc	tion signals and zero direction signals (potential-free) per main-axis		3				
8 Bit Gray-Code with direction	signals per main-axis, supply voltage 9-36 V DC						
Wiring:	1. cable 37 x 0,14 mm <sup>2</sup> 300 mm long without plug connector (axis 1+2)						
	2. cable 37 x 0,14 $\mbox{mm}^2$ 300 mm long without plug connector (optional for	axis 3+4)					
	Optional with plug connector (standard plug connectors see page 120)			S			
		1 axis	E903 1				
		2 axis	2				
		3 axis	3				
		4 axis	4				
8 Bit binary-Code with direction	n signals per main-axis, supply voltage 9-36 V DC						
Wiring:	1. cable 37 x 0,14 mm <sup>2</sup> 300 mm long without plug connector (axis 1+2)						
	2. cable $37 \times 0.14 \text{ mm}^2 300 \text{ mm}$ long without plug connector (optional for	axis 3+4)					
	Optional with plug connector (standard plug connectors see page 120)			S			
		1 axis	E904 1				
		2 axis	2				
		3 axis	3				
		4 axis	4				

Attachments		
Z01	Mating connector (CAN) M12 (male insert) with 2 m cable	20201140
Z02	Mating connector (CAN) M12 (female contact) with 2 m cable	20202298
Z03	Mating connector (Profibus) straight	22201440
Z04	Mating connector (Profibus) 90° angled	22201741
Z05	Mating connector (Profinet) M12 (male insert) with 2 m cable	5300000222









The V27 is a robust joystick commonly used in electro-hydraulic applications. The compact design allows for use in smallest installation spaces. It can be integrated with detents and a very robust friction brake. Long life and high reliability is ensured by the latest contactless hall-technology. With many outputs and grip options the V27 series is flexible and customisable.

#### Technical data

Mechanical life V27 10 million operating cycles

Supply voltage See interface Operation temperature  $-40^{\circ}\text{C to } +85^{\circ}\text{C}$  Degree of protection up to IP67

Functional safety

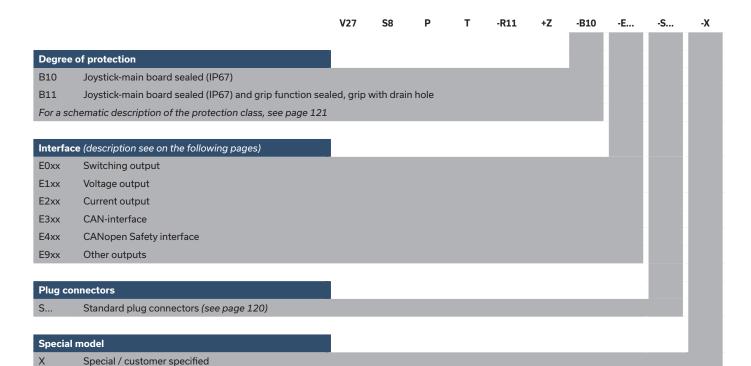
PLd compatible (EN ISO 13849, complies SIL2

to DIN EN IEC 61508)



		V27	S8	Р	Example <b>T</b>	e -R11	+Z	-B10	-E	-S	-X
Basic u											
V27.1	1-axis										
V27	2-axis										
Control	l-handle extended										
	Standard 95 mm*										
S8	+20 mm										
*Only a	vailable in combination with a handle!										
Gate											
Р	Cross gate										
PX	Special gate										
Grin / F	Palm Grip										
апр / г	Knob (included in basic unit!)										
M	Knob with mechanical zero interlock										
Т	Dead man										
Н	Signal button										
D	Push button										
В	Palm Grip B (see page Palm Grip 154)										
Axis 1	/ Axis 2 (not applied for V27.1)										
Z	Spring return										
R	Friction brake (possible with one axis!)										
	Latching: (possible with one axis!)										
11	1-0-1										
22	2-0-2										
33	3-0-3										
44	4-0-4										
80	end-position latching SR2 or SR4										
19	1-0-1 + end-position latching SR2 or SR4										
80	end-position latching SR1 or SR3										
91	1-0-1 + end-position latching SR1 or SR3										
88	end-position latching SR1 + SR2 or SR3 + SR4										
99	1-0-1 + end-position latching SR1 + SR2 or SR3 + SR4										





Combination pos	ssibilities with o	ur grips						
p. 199	p. 197	p. 194	p. 192	p. 188	p. 188	B9 p. 186	p. 184	B14 B15
p. 180	B22	p. 176	B24	B25	B26	B28	p. 166	B30
831	B32	B33	B34	B35				

Digital output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	45 mm			
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long without plu	g connector		
	2. cable 14 x 0,25 mm² (optional for grip function	) 500 mm long without plug connector		
	Optional with plug connector (standard plug con	nectors see page 120)		S
2 Direction signals + 1 zero pos	2 Direction signals + 1 zero position signal (galvanically isolated) per axis			
		1 axis	E001 1	
		2 axis	2	



Voltage output (not stabilized	)				
Supply voltage	4,75-5,25 V DC				
Current carrying capacity	Direction signal 8 mA				
Mounting depth A	45 mm				
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long without pl	ug connector			
	2. cable 14 x 0,25 mm² (grip function) 500 mm long without plug connector				
	Optional with plug connector (standard plug connectors see page 120)				
0,52,54,5 V redundant + 2 d	lirection signals per axis			•	
		1 axis	E104 1		
		2 axis	2	_	
		Output options		_	
		Characteristic:		_	
		Inverse dual		1	
		Dual		2	
		Inverse Dual with dead zone +/- 3° (standard)		3	
		Dual with dead zone +/- 3°		4	

Voltage output				
Supply voltage	9-32 V DC (*11,5-32)			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	45 mm (60 mm from 3 axis)			
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long without p	lug connector		
	2. cable 14 x 0,25 mm² (optional for grip function	on) 500 mm long without plug	connector	
	Optional with plug connector (standard plug co	nnectors see page 120)		S
0,52,54,5 V redundant + 2	2 direction signals + 1 zero position signal (galvanica	Illy isolated) per axis		
		1 axis	E1121	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
0510 V redundant + 2 dire	ection signals + 1 zero position signal (galvanically is	olated) per axis, supply voltag	ge 11,5 - 32 V DC	
		1 axis	E132 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
10010 V + 2 direction sign	nals + 1 zero position signal (galvanically isolated) pe	er axis, supply voltage 11,5 - 3	2 V DC,	
sensor redundant with error r	monitoring and error signal			
		1 axis	E136 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
		Output options		
		Characteristic:		
		Inverse dual *1		1
		Dual *1		2
		Inverse dual with dead zon	e +/- 3° *1 (standard)	3
		Dual with dead zone +/- 3°		4
		*1 not combinable with out	put E136X	
		Single *2		5
		Single with dead zone *2 (s	tandard)	6
		*2 not combinable with out	put E112X and E132X	
*Axis for grip functions, interf	face can vary depending upon actuation element!			
Voltage output with other val	ue on request!			
-				

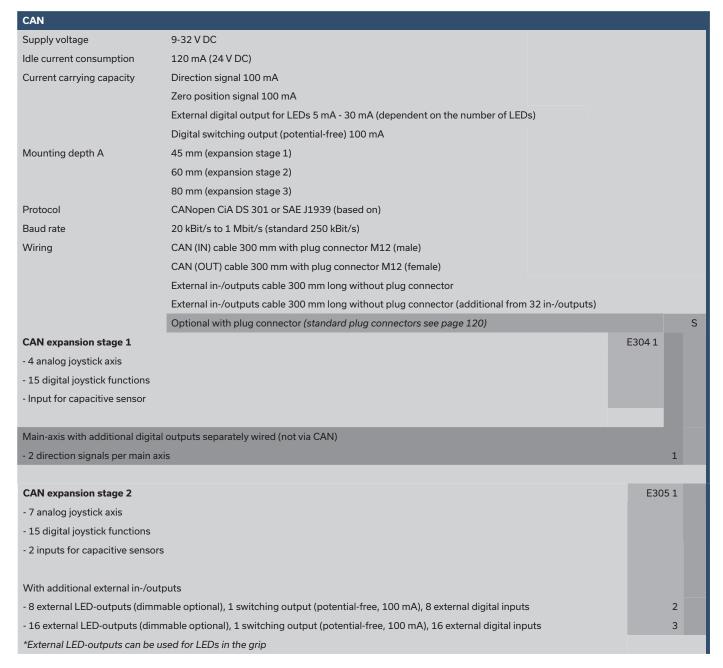


Current output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	45 mm (60 mm from 3 axis)			
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long without	plug connector		
	2. cable 14 x 0,25 mm² (optional for grip fund	tion) 500 mm long withou	ıt plug connector	
	Optional with plug connector (standard plug	connectors see page 120)	)	S
01020 mA + 2 direction sign	als + 1 zero position signal (galvanically isolated	d) per axis, sensor redund	ant	
with error monitoring and error	signal			
		1 axis	E206 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
20020 mA + 2 direction sign	als + 1 zero position signal (galvanically isolated	d) per axis, sensor redund	ant	
with error monitoring and error	signal			
		1 axis	E208 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
41220 mA + 2 direction sign	nals + 1 zero position signal (galvanically isolate	d) per axis, sensor redund	ant	
with error monitoring and error	signal			
		1 axis	E214 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
20420 mA + 2 direction sign	als + 1 zero position signal (galvanically isolate	d) per axis, sensor redund	ant	
with error monitoring and error	signal			
		1 axis	E216 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
		Output options		
		Single		5
		Single with dead zone +/	/- 3° (standard)	6
*Axis for grip functions, interfac	e can vary depending upon actuation element!			
Current output with other value	on request!			



#### Identification of the installation variants with switching directions:







CAN expansion stage 3	E306 1
- 10 analog joystick axis	_
- 15 digital joystick functions	_
- 2 inputs for capacitive sensors	_
	_
With additional external in-/outputs	_
- 8 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 8 external digital inputs	2
- 16 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 16 external digital inputs	3
- 24 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 24 external digital inputs	4
- 32 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 32 external digital inputs	5
*External LED-outputs can be used for LEDs in the grip	
Main-axis with additional digital outputs separately wired (not via CAN)	
- 2 direction signals + 1 zero position signal (potential-free) per axis	3
With additional analog outputs on request!	

CANopen Safety			
Supply voltage	9-32 V DC		
Idle current consumption	120 mA (24 V DC)		
Current carrying capacity	Direction signal 100 mA		
	Zero position signal 100 mA (potential-free)		
	External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs)		
	Digital switching output (potential-free) 100 mA		
Baud rate	20 kBit/s to 1 MBit/s (standard 250 kBit/s)		
Mounting depth	45 mm (expansion stage 1)		
	60 mm (expansion stage 2)		
	80 mm (expansion stage 3)		
Protocol	CANopen Safety EN50325-5		
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)		
	CAN (OUT) cable 300 mm with plug connector M12 (female)		
	External in-/outputs cable 300 mm long without plug connector		
	External in-/outputs cable 300 mm long without plug connector (additional from 32 in-/outputs)		
	Optional with plug connector (standard plug connectors see page 120)		S
<b>CANopen Safety expansion</b>	stage 1	E404 1	
- 4 analog joystick axis			
- 15 digital joystick functions			
- Input for capacitive sensor			
Main-axis with additional digi	tal outputs separately wired (not via CAN)		
- 2 direction signals per main	axis		1
CANopen Safety expansion	stage 2	E405 1	
- 7 analog joystick axis			
- 15 digital joystick functions			
- 2 inputs for capacitive senso	ors		
With additional external in-/o			
•	mable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs	2	
•	mmable optional), 1 switching output (potential-free, 100 mA), 16 external digital inputs	3	
*External LED-outputs can be	used for LEDs in the grip		

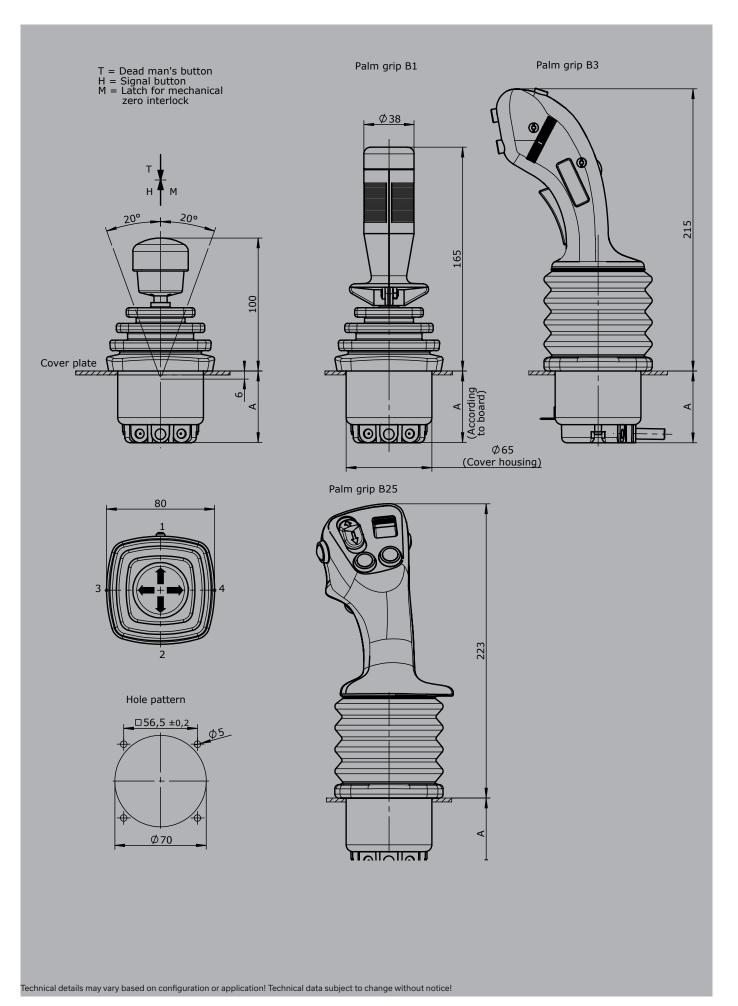


CANopen Safety expansion stage 3	E406 1	
- 10 analog joystick axis		
- 15 digital joystick functions		
- 2 inputs for capacitive sensor		
With additional external in-/outputs		
- 8 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100 mA), 8 external digital inputs	2	
- 16 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100 mA), 16 external digital inputs	3	
- 24 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100 mA), 24 external digital inputs	4	
- 32 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100 mA), 32 external digital inputs	5	
*External LED-outputs can be used for LEDs in the grip		
Main-axis with additional digital outputs separately wired (not via CAN)		
- 2 direction signals + 1 zero position signal (potential-free) per axis		3
With additional analog outputs on request!		

Other outputs				
Voltage output for PVG32	0,250,50,75Us, power supply 9-32 V DC			
Option	Input for capacitive sensor			
Mounting depth A	45 mm (60 mm from 3 axis)			
Wiring:	1. cable $14 \times 0.25 \text{ mm}^2$ 300 mm long without plug connector			
	2. cable $14 \times 0.25 \; \text{mm}^2$ 300 mm long without plug connector (optional	for grip function)		
	Optional with plug connector (standard plug connectors see page 120)			:
		1 axis	E907 1	
		2 axis	2	
		3 axis	3	
		4 axis	4	
Main-axis with additional	direction signals and zero direction signals (potential-free) per main-axis			3

Attachments		
Z01 Mating connector M12 male insert with 2 m cable	20201140	
Z02 Mating connector M12 female insert with 2 m cable	20202298	









The V26 is a robust joystick commonly used in electro-hydraulic applications. Long life and high reliability is ensured by the latest contactless hall-technology. With many outputs and grip options the V26 series is hugely customisable.

#### **Technical data**

Mechanical life V26 10 million operating cycles

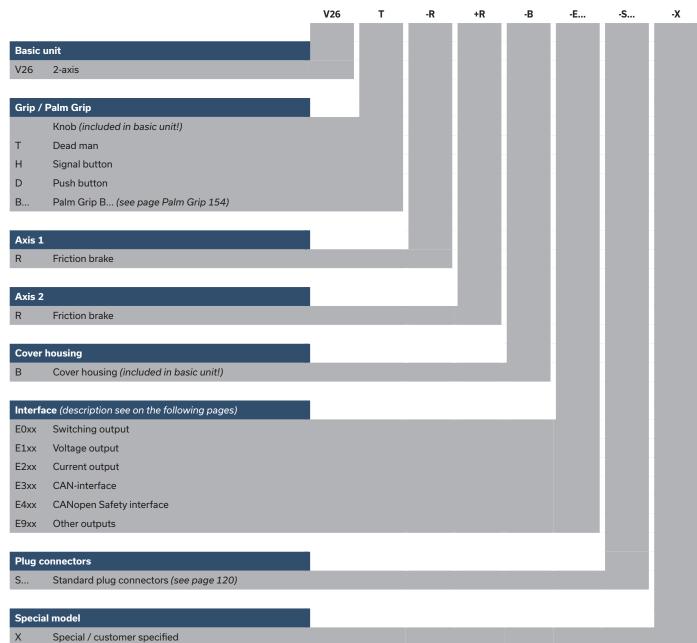
Supply voltage See interface -40°C to +85°C Operation temperature

IP22 Degree of protection

PLd compatible (EN ISO 13849, complies Functional safety

SIL2 to DIN EN IEC 61508)







Digital output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	105 mm			
Wiring	Cable 500 mm long without plug connector			
	Optional with plug connector (standard plug con	nectors see page 120)		S
2 direction signals + 1 zero pos	ition signal (galvanically isolated) per axis			
		2 axis	E002 2	

Voltage output (not stabilized	)				
Supply voltage	4,75-5,25 V DC				
Mounting depth A	105 mm				
Wiring	Cable 500 mm long without plug connector				
	Optional with plug connector (standard plug con	nectors see page 120)			S
0,52,54,5 V redundant per a	axis				
		2 Achsen		E103 2	
		Output options			
		Characteristic:			
		Inverse dual		1	4
		Dual		2	2
		Inverse dual with dead zon	e +/- 3° (standard)	3	3
		Dual with dead zone +/- 3°		4	ı.

Voltage output					
Supply voltage	9-32 V DC (*11,5-32)				
Mounting depth A	105 mm				
Option	Input for capacitive sensor				
Wiring	Cable 500 mm long without plug connector				
	Optional with plug connector (standard plug con	nectors see page 120)			S
0,52,54,5 V redundant per a	axis				
		2 axis	E111 2		
0510 V redundant per axis,	supply voltage 11,5 - 32 V DC				
		2 axis	E131 2		
		Output options			
		Characteristic:			
		Inverse dual		1	
		Dual		2	
		Inverse dual with dead zon	e +/- 3° (standard)	3	
		Dual with dead zone +/- 3°		4	
Voltage output with other value	e on request!				



Current output					
Supply voltage	9-32 V DC				
Mounting depth A	105 mm				
Option	Input for capacitive sensor				
Wiring	Cable 500 mm long without plug connector				
	Optional with plug connector (standard plug o	connectors see page 120)			S
01020 mA per axis, sensor re	dundant with error monitoring and error signal				
		2 axis	E203 2		
41220 mA per axis, sensor re	dundant with error monitoring and error signal				
		2 axis	E211 2		
		Output options			
		Single		5	
		Single with dead zone +	/- 3° (standard)	6	
Current output with other value of	on request!				

CAN				
Supply voltage	9-36 V DC			
Idle current consumption	120 mA			
	External digital output for LEDs 5-30 mA (dependent on the number of LEDs)			
	Digital switching output (potential-free) 100 mA			
Mounting depth A	E3091: 105 mm			
	E3091X: 130 mm			
	E3101X - E3103X: 130 mm			
	E3104X - E3105X: 160 mm			
Protocol	CANopen CiA DS 301 or SAE J 1939 (based on)			
Baud rate	125 kBit/s to 1 Mbit/s (standard 250 kBit/s)			
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)			
	CAN (OUT) cable 300 mm with plug connector M12 (female)			
	External in-/outputs cable 300 mm without plug connector			
	External in-/outputs cable 300 mm without plug connector (additionally from 32 in-/outputs)			
	Optional with plug connector (standard plug connectors see page 120)			S
CAN expansion stage 1		E309	1	
- 7 analoge Joystickachsen				
- 16 digitale Joystickfunktionen				
- Input for capacitive sensor				
With additional external in-/out	puts			
- 8 external LED-outputs (dimm	able optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs		2	
- 16 external LED-outputs (dimr	nable optional), 1 switching output (potential-free, 100 mA), 16* external digital inputs		3	
*External LED-outputs can be u	sed for LEDs in the grip			
*With the use of capacitive sens	sor, the external digital inputs are reduced by one input!			

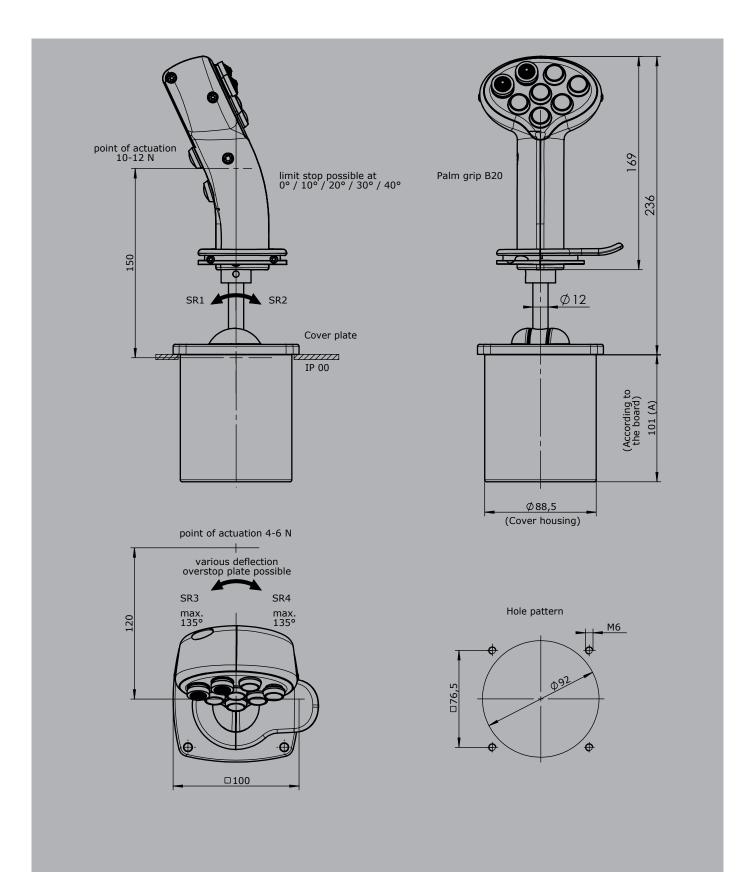


CANopen Safety				
Supply voltage	9-36 V DC			
Idle current consumption	120 mA			
	External digital output for LEDs 5-30 mA (depending on the number of LEDs)			
	Digital switching output (potential-free) 100 mA			
Mounting depth A	E4091: 105 mm			
	E4091X: 130 mm			
	E4101X - E4103X: 130 mm			
	E4104X - E4105X: 160 mm			
Protocol	CANopen Safety EN50325-5			
Baud rate	125 kBit/s to 1 MBit/s (Standard 250 kBits)			
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)			
	CAN (OUT) cable 300 mm with plug connector M12 (female)			
	External in-/outputs cable 300 mm without plug connector			
	External in-/outputs cable 300 mm without plug connector (additionally from 32 in-/outputs)			
	Optional with plug connector (standard plug connectors see page 120)			S
CANopen Safety expansion sta	age 1	E409	1	
- 7 analog joystick axis				
- 16 digital joystick functions				
- Input for capacitive sensor				
With additional external in-/outp	puts			
- 8 external LED-outputs (dimma	able optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs		2	
- 16 external LED-outputs (dimn	nable optional), 1 switching output (potential-free, 100 mA), 16* external digital inputs		3	
*External LED-outputs can be us	sed for LEDs in the grip			
*With the use of capacitive sens	sor, the external digital inputs are reduced by one input!			

Other outputs				
Voltage output for PVG32 0	.250,50,75Us, power supply 9-32V DC			
Mounting depth A	105 mm			
Option	Input for capacitive sensor			
Wiring:	1. cable $14 \times 0.25 \text{ mm}^2$ 300 mm long without plug connector			
	2. cable $14 \times 0.25 \; \text{mm}^2$ 300 mm long without plug connector (optional for grip	o function)		
	Optional with plug connector (standard plug connectors see page 120)			S
	2	2 axis	E907 2	

Attachments	
Z01 Mating connector (CAN) M12 (male insert) with 2 m cable	20201140
Z02 Mating connector (CAN) M12 (female contact) with 2 m cable	20202298







The V25 is a compact and robust joystick commonly used in electro-hydraulic applications. Long life and high reliability is ensured by the latest contactless hall-technology. With many outputs and grip options the V25 series is hugely customisable.

#### Technical data

Mechanical life V25 8 million operating cycles

Supply voltage See interface -40°C to +85°C Operation temperature Degree of protection up to IP67

PLd compatible (EN ISO 13849, complies Functional safety

SIL2 to DIN EN IEC 61508)



Example Р -S... V25 S8 -7 -R10 -X Т -F... **Basic unit** V25.1 1-axis V25 2-axis Control-handle long Standard 100 mm\* +20 mm S8 \*Only available in combination with a handle! Gate Ρ Cross gate (deflection angle max. 15°) Grip / Palm Grip Knob (included in basic unit!) M Mechanical zero interlock Т Knob with dead man Н Knob with signal button D Knob with push button KDA/70 В.. Palm Grip B... (see page Palm Grip 154) Spring return (includet in basic unit!) Ζ Spring return Degree of protection В Cover housing B10 Joystick-main board sealed B11 Joystick-main board sealed and grip function sealed, grip with drain hole For a schematic description of the protection class, see page 121 **Interface** (description see on the following page) E0xx Switching output E1xx Voltage output E2xx Current output ЕЗхх CAN-interface **CANopen Safety interface** E4xx E9xx Other outputs



V25 S8 P T -Z -B10 -E... -S... -X

Plug connectors

S... Standard plug connectors (see page 120)

Special model

X Special / customer specified

Combination possibilities with our grips



**Digital output** Supply voltage 9-32 V DC Current carrying capacity Direction signal 150 mA Zero position signal 500 mA Mounting depth A 60 mm Wiring 1. cable 14 x 0,25 mm<sup>2</sup> 500 mm long without plug connector 2. cable 14 x 0,25 mm<sup>2</sup> (optional for grip function) 500 mm long without plug connector S Optional with plug connector (standard plug connectors see page 120) 2 Direction signals + 1 zero position signal (galvanically isolated) per axis E0011 1 axis 2 axis 2

Voltage output (not stabilized) 4.75-5.25 V DC Supply voltage Current carrying capacity Direction signal 8 mA Mounting depth A 60 mm Wiring 1. cable 14 x 0,25 mm<sup>2</sup> 500 mm long without plug connector 2. cable 14 x 0,25 mm<sup>2</sup> (optional for grip function) 500 mm long without plug connector S Optional with plug connector (standard plug connectors see page 120) 0,5...2,5...4,5 V redundant + 2 direction signals per axis E1041 1 axis 2 axis **Output options** Characteristic: Inverse dual Dual 2 Inverse Dual with dead zone +/- 3° (standard) 3 Dual with dead zone +/- 3°



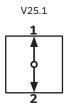
Voltage output				
Supply voltage	9-32 V DC (*11,5-32)			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	60 mm			
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long wit	hout plug connector		
	2. cable $14 \times 0.25 \text{ mm}^2$ (optional for grip	function) 500 mm long without plug	connector	
	Optional with plug connector (standard)	olug connectors see page 120)		S
0,52,54,5 V redundant + 2	direction signals + 1 zero position signal (ga	Ivanically isolated) per axis		
		1 axis	E1121	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
0510 V redundant + 2 dire	ection signals + 1 zero position signal (galvani	ically isolated) per axis, supply voltag	ge 11,5 - 32 V DC	
		1 axis	E132 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
10010 V + 2 direction sign sensor redundant with error r	nals + 1 zero position signal (galvanically isola nonitoring and error signal	ted) per axis, supply voltage 11,5 - 3	2 V DC,	
		1 axis	E1361	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
		Output options		
		Characteristic:		
		Inverse dual *1		1
		Dual *1		2
		Inverse dual with dead zon		3
		Dual with dead zone +/- 3°		4
		*1 not combinable with out	tput E136X	
		Single *2		5
		Single with dead zone +/- 3	3° *2 (standard)	6
		*2 not combinable with out	tput E112X and E132X	
		Digital output signals:		
		Output signals standard:		
		Direction signals and zero	position signals 1,5A 24 V DC	1
*Axis for arin functions interf	ace can vary depending upon actuation elem	nentl		
Voltage output with other value		ione.		

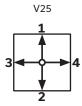


Current output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	60 mm			
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long	g without plug connector		
	2. cable 14 x 0,25 mm <sup>2</sup> (optional for	grip function) 500 mm long without plug co	nnector	
	Optional with plug connector (stand	lard plug connectors see page 120)		S
01020 mA + 2 direction s	ignals + 1 zero position signal (galvanicall	ly isolated) per axis, sensor redundant with e	error monitoring	
and error signal				
		1 axis	E206 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
20020 mA + 2 direction s	gnals + 1 zero position signal (galvanicall	ly isolated) per axis, sensor redundant with e	error monitoring	
and error signal				
		1 axis	E208 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
41220 mA + 2 direction s	ignals + 1 zero position signal (galvanical	ly isolated) per axis, sensor redundant with e	error monitoring	
and error signal				
		1 axis	E214 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
20420 mA + 2 direction s	ignals + 1 zero position signal (galvanical	ly isolated) per axis, sensor redundant with e	error monitoring	
and error signal				
		1 axis	E216 1	
		2 axis	2	
		3 axis*	3	
		4 axis*	4	
		Output options		
		Single	5	
		Single with dead zone +/- 3° (stan	idard) 6	
		Digital output signals:		
		Output signals standard:		
		Direction signals and zero positio	n signals 1,5A 24 V DC	1
*Axis for grip functions, inter	face can vary depending upon actuation (	element!		



#### Identification of the installation variants with switching directions:





CAN			
Supply voltage	9-32 V DC		
Idle current consumption	120 mA (24 V DC)		
Current carrying capacity	Direction signal 100 mA		
	Zero position signal 100 mA		
	External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs)		
	Digital switching output (potential-free) 100 mA		
Mounting depth A	60 mm (expansion stage 1)		
	70 mm (expansion stage 2)		
	90 mm (expansion stage 3)		
Protocol	CANopen CiA DS 301 or SAE J1939 (based on)		
Baud rate	20 kBit/s to 1 Mbit/s (standard 250 kBit/s)		
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)		
	CAN (OUT) cable 300 mm with plug connector M12 (female)		
	External in-/outputs cable 300 mm long without plug connector		
	External in-/outputs cable 300 mm long without plug connector (additional from 32 in-/outputs)		
	Optional with plug connector (standard plug connectors see page 120)	S	
CAN expansion stage 1		E304 1	
- 4 analog joystick axis			
- 15 digital joystick functions			
- Input for capacitive sensor			
Main-axis with additional digital	I outputs separately wired (not via CAN)		
- 2 direction signals per main ax	cis	1	
CAN expansion stage 2		E305 1	
- 7 analog joystick axis			
- 15 digital joystick functions			
- 2 inputs for capacitive sensors			
With additional external in-/out	puts		
- 8 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs		2	
- 16 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 16 external digital inputs		3	
	*External LED-outputs can be used for LEDs in the grip		



CAN expansion stage 3	E306 1	
- 10 analog joystick axis		
- 15 digital joystick functions		
- 2 inputs for capacitive sensors		
With additional external in-/outputs		
- 8 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 8 external digital inputs	2	
- 16 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 16 external digital inputs	3	
- 24 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 24 external digital inputs	4	
- 32 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 32 external digital inputs	5	
*External LED-outputs can be used for LEDs in the grip		
Main-axis with additional digital outputs separately wired (not via CAN)		
- 2 direction signals + 1 zero position signal (potential-free) per axis		3
With additional analog outputs on request!		
CANapan Safaty		
CANopen Safety		

with additional analog outpo			
CANopen Safety			
Supply voltage	9-32 V DC		
Idle current consumption	120 mA (24 V DC)		
Current carrying capacity	Direction signal 100 mA		
	Zero position signal 100 mA (potential-free)		
	External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs)		
	Digital switching output (potential-free) 100 mA		
Baud rate	20 kBit/s to 1 MBit/s (standard 250 kBit/s)		
Mounting depth	60 mm (expansion stage 1)		
	70 mm (expansion stage 2)		
	90 mm (expansion stage 3)		
Protocol	CANopen Safety EN50325-5		
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)		
	CAN (OUT) cable 300 mm with plug connector M12 (female)		
	External in-/outputs cable 300 mm long without plug connector		
	External in-/outputs cable 300 mm long without plug connector (additional from 32 in-/outputs)		
	Optional with plug connector (standard plug connectors see page 120)		S
CANopen Safety expansion	stage 1	E404 1	
- 4 analog joystick axis			
- 15 digital joystick functions			
- Input for capacitive sensor			
Main-axis with additional dig	ital outputs separately wired (not via CAN)		
- 2 direction signals per main	axis		1
CANopen Safety expansion	stage 2	E405 1	
- 7 analog joystick axis	stage 2	L403 I	
- 15 digital joystick functions			
- 2 inputs for capacitive sens			
- 2 inputs for capacitive sens	013		
With additional external in-/c	putputs		
	outputs nmable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs	2	
- 8 external LED-outputs (dim		2	

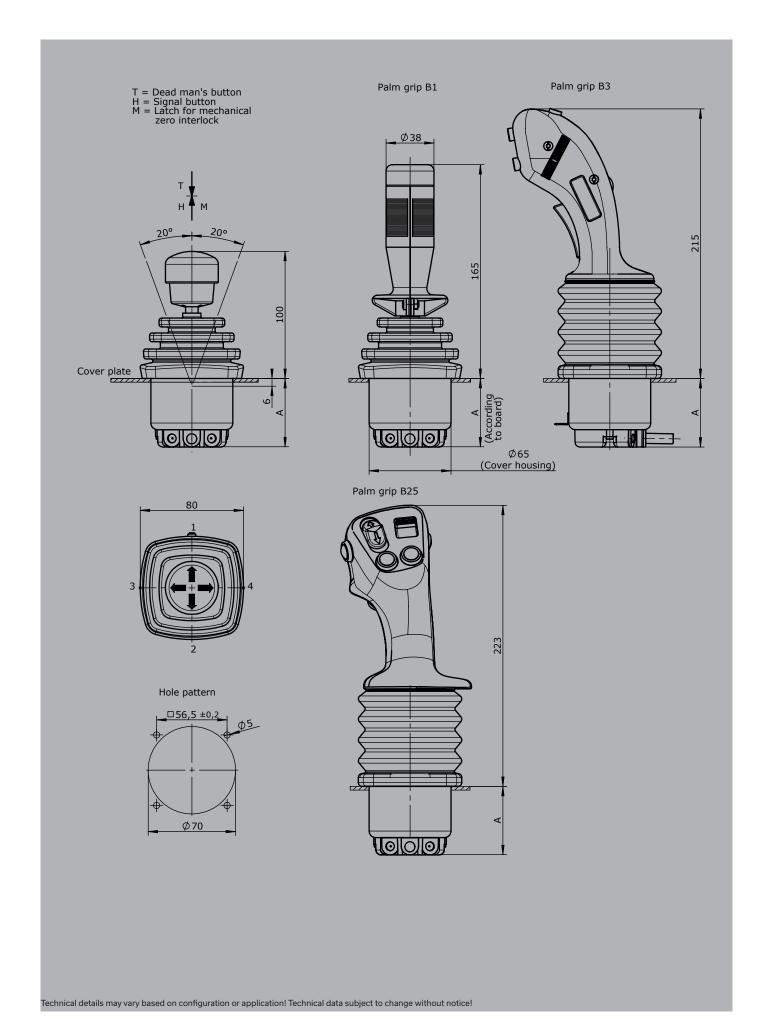


CANopen Safety expansion stage 3	E406 1	
- 10 analog joystick axis		
- 15 digital joystick functions		
- 2 inputs for capacitive sensor		
With additional external in-/outputs		
- 8 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 8 external digital inputs	2	
- 16 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 16 external digital inputs	3	
- 24 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 24 external digital inputs	4	
- 32 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 32 external digital inputs	5	
*External LED-outputs can be used for LEDs in the grip		
Main-axis with additional digital outputs separately wired (not via CAN)		
- 2 direction signals + 1 zero position signal (potential-free) per axis		3
With additional analog outputs on request!		

Other outputs				
Voltage output for PVG32 0,25	0,50,75Us, power supply 9-32 V DC			
Option	Input for capacitive sensor			
Mounting depth A	60 mm			
Wiring:	1. cable 14 x 0,25 mm <sup>2</sup> 300 mm long without plug connector			
	2. cable $14 \times 0.25 \text{ mm}^2$ 300 mm long without plug connector (optional for $90 \text{ mm}^2$	grip function)		
	Optional with plug connector (standard plug connectors see page 120)			S
		1 axis	E907 1	
		2 axis	2	
		3 axis	3	
		4 axis	4	
Main-axis with additional direction	on signals and zero direction signals (potential-free) per main-axis			3

Attachments	
Z01 Mating connector M12 male insert with 2 m cable	20201140
Z02 Mating connector M12 female insert with 2 m cable	20202298







The Multi-Axis Controller V24 is designed as a driving joystick for construction and agricultural machinery. It has a parking position which can be inserted in the zero position. The V24 is characterized by its extremely rugged design. Long life and high reliability is ensured by the latest contactless hall-technology. Through its various interfaces and many possibilities of combination with our numerous ball grips the V24 is very flexible.

#### **Technical data**

Mechanical life V24 20 million operating cycles

See interface Supply voltage Operation temperature -40°C to +85°C up to IP67 Degree of protection

PLd compatible (EN ISO 13849, complies Functional safety

SIL2 to DIN EN IEC 61508)



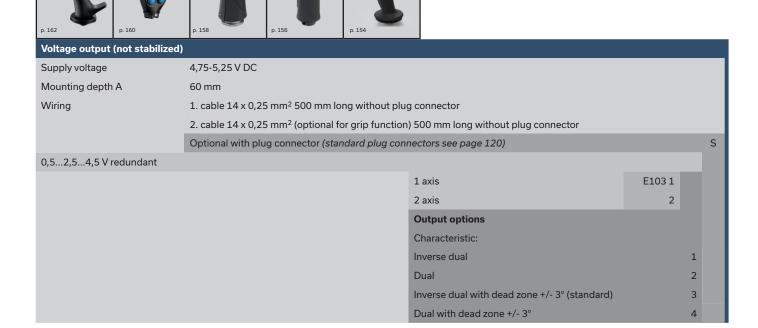
				Example					
		V24	P1	Т	-R	-B10	-E	-S	-X
Basic ι	unit								
V24.1	1-axis								
V24L	1-axis with parking position left								
V24R	1-axis parking position right								
Gate									
P1	T-gate main axis axial (included in basic unit!)								
P2	T-gate main axis right outside								
P3	T-gate main axis left outside								
PX	Special gate								
Grip / I	Palm Grip								
	Knob (included in basic unit!)								
Т	Dead man								
Н	Signal button								
D	Push button								
В	Palm Grip B (see page Palm Grip 154)								
Main a	xis								
R	Friction brake adjustable (included in basic unit!)								
Degree	e of protection								
B10	Joystick-main board sealed (IP67)								
B11	Joystick-main board sealed (IP67) and grip function sealed,	grip with d	rain hole						
For a so	chematic description of the protection class, see page 150								
Interfa	<b>ce</b> (description see on the following pages)								
E1xx	Voltage output								
E2xx	Current output								
ЕЗхх	CAN-interface								
E4xx	CANopen Safety interface								
E9xx	Other outputs								
Plug co	onnectors								
S	Standard plug connectors (see page 120)								
Specia	l model								

B32

B33

B34





Voltage output						
Supply voltage	9-32 V DC (*11,5-32)					
Current carrying capacity	Direction signal 150 mA					
	Zero position signal 500 mA					
Mounting depth A	65 mm					
Option	Input for capacitive sensor					
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long	g without plug connector				
	2. cable $14 \times 0.25 \text{ mm}^2$ (optional for	2. cable 14 x 0,25 mm <sup>2</sup> (optional for grip function) 500 mm long without plug connector				
	Optional with plug connector (standard plug connectors see page 120)					
0,52,54,5 V redundant + 2 direction signals + 1 zero position signal (galvanically isolated) per axis						
		1 axis	E1121			
		2 axis	2			
		3 axis*	3			
		4 axis*	4			
		5 axis*	5			
		6 axis*	6			
0510 V redundant + 2 dire	ction signals + 1 zero position signal (ga	lvanically isolated) per axis, supply voltage	11,5 - 32 V DC			
		1 axis	E1321			
		2 axis	2			

Technical details may vary based on configuration or application! Technical data subject to change without notice!



	3 axis*	3	
	4 axis*	4	
	5 axis*	5	
	6 axis*	6	
10010 V + 2 direction signals + 1 zero position signal (galvanically isolated) per	axis, supply voltage 11,5 - 3	2 V DC,	
sensor redundant with error monitoring and error signal			
	1 axis	E136 1	
	2 axis	2	
	3 axis*	3	
	4 axis*	4	
	5 axis*	5	
	6 axis*	6	
	Output options		
	Characteristic:		
	Inverse dual *1		1
	Dual *1		2
	Inverse dual with dead zon	e +/- 3° *1 (standard)	3
	Dual with dead zone +/- 3°	*1	4
	*1 not combinable with out		
	Single *2		5
	Single with dead zone *2 (s	tandard)	6
	*2 not combinable with out	put E112X and E132X	
*Axis for grip functions, interface can vary depending upon actuation element!			
Voltage output with other value on request!			

Current output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	65 mm			
Option	Input for capacitive sensor			
Wiring	1. cable $14 \times 0.25 \text{ mm}^2 500 \text{ mm}$ long without	t plug connector		
	2. cable 14 x 0,25 mm <sup>2</sup> (optional for grip fund	ction) 500 mm long withou	t plug connector	
	Optional with plug connector (standard plug	connectors see page 120)		S
01020 mA + 2 direction si	gnals + 1 zero position signal (galvanically isolate	d) per axis, sensor redunda	ant with error monitoring	
and error signal				
		1 axis	E206	1
		2 axis		2
		3 axis*		3
		4 axis*		4
		5 axis*		5
		6 axis*		6
20020 mA + 2 direction si	gnals + 1 zero position signal (galvanically isolate	d) per axis, sensor redunda	ant with error monitoring	
and error signal				
		1 axis	E208	1
		2 axis		2
		3 axis*		3
		4 axis*		4
		5 axis*		5
		6 axis*		6



41220 mA + 2 direction signals + 1 zero position signal (gal	vanically isolated) per axis, sensor redundant with e	error monitoring
and error signal		
	1 axis	E214 1
	2 axis	2
	3 axis*	3
	4 axis*	4
	5 axis*	5
	6 axis*	6
20420 mA + 2 direction signals + 1 zero position signal (gal	vanically isolated) per axis, sensor redundant with e	error monitoring
and error signal		
	1 axis	E216 1
	2 axis	2
	3 axis*	3
	4 axis*	4
	5 axis*	5
	6 axis*	6
	Output options	
	Single	

CAN				
Supply voltage	9-36 V DC			
Idle current consumption	120 mA			
Mounting depth A	60 mm			
Protocol	CANopen CiA DS 301 or SAE J 1939 (based on)			
Baud rate	125 kBit/s to 1 Mbit/s			
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)			
	CAN (OUT) cable 300 mm with plug connector M12 (female)			
	External in-/outputs cable 300 mm long without plug connector			
	Optional with plug connector (standard plug connectors see page 120)		9	S
CAN		E312 1		
- 7 analog joystick axis				
- 15 digital joystick functions				
*With the use of external inputs,	, the joystickfunctions are reduced by 7 pieces!			
- Input for capacitive sensor				
With additional external in-/outp	puts			
- 8 external LED-outputs, 1 switch	ching output (potentialfree, 100 mA), 7 external digital inputs	2		
- 16 external LED-outputs, 1 swi	tching output (potentialfree, 100 mA), 7 external digital inputs	3		
With additional digital outputs for	or the main-axis			
- 2 direction signals + 1 zero pos	sition signal (potential-free) per axis		3	
Additional analog outputs on red	quest!			

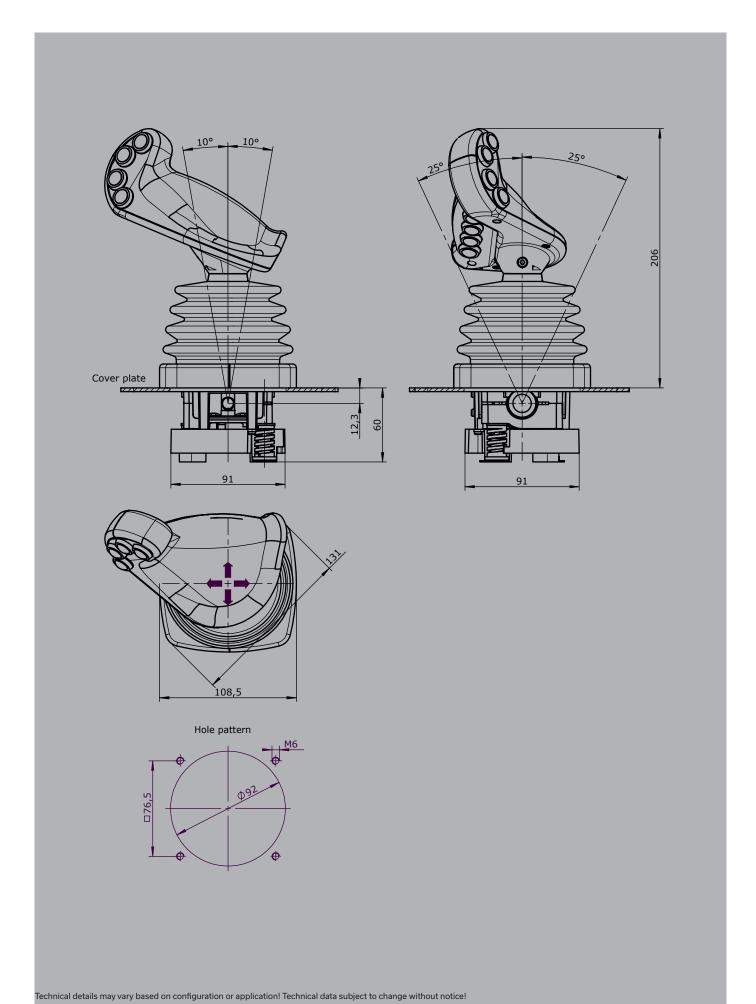


CANopen Safety				
Supply voltage	9-36 V DC			
Idle current consumption	120 mA			
Mounting depth A	60 mm			
Protocol	CANopen Safety EN50325-5			
Baud rate	125 kBit/s to 1 Mbit/s			
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)			
	CAN (OUT) cable 300 mm with plug connector M12 (female)			
	External in-/outputs cable 300 mm long without plug connector			
	Optional with plug connector (standard plug connectors see page 120)			S
<b>CANopen Safety</b>		E411 1		
- 7 analog joystick axis				
- 15 digital joystick functions				
*With the use of external inputs,	the joystickfunctions are reduced by 7 pieces!			
- Input for capacitive sensor				
With additional external in-/outp	outs			
- 8 external LED-outputs, 1 switch	ching output (potentialfree, 100 mA), 7 external digital inputs	2		
- 16 external LED-outputs, 1 swi	tching output (potentialfree, 100 mA), 7 external digital inputs	3		
With additional digital outputs for	or the main-axis			
- 2 direction signals + 1 zero pos	ition signal (potential-free) per axis		3	
Additional analog outputs on red	quest!			

Other outputs					
Voltage output for PVG32 0,2	50,50,75Us, power supply 9-32 V DC				
Mounting depth A	60 mm				
Option	Input for capacitive sensor				
Wiring:	1. cable 14 x 0,25 mm <sup>2</sup> 300 mm long without plug connector				
	2. cable 14 x 0,25 mm <sup>2</sup> 300 mm long without plug connector (optional for grip functi	on)			
	Optional with plug connector (standard plug connectors see page 120)				S
		1 axis	E907 1		
		2 axis	2		
		3 axis	3		
		4 axis	4		
		5 axis	5		
		6 axis	6		
Main-axis with additional direc	tion signals and zero direction signals (potential-free) per main-axis			3	

Attachments	
Z01 Mating connector (CAN) M12 (male insert) with 2 m cable	20201140
Z02 Mating connector (CAN) M12 (female contact) with 2 m cable	20202298







The V1 is a robust Joystick commonly used in electro-hydraulic applications. The modular design enables the switching device to be used universally. Long life and high reliability is ensured by the latest contactless hall-technology.

### Technical data

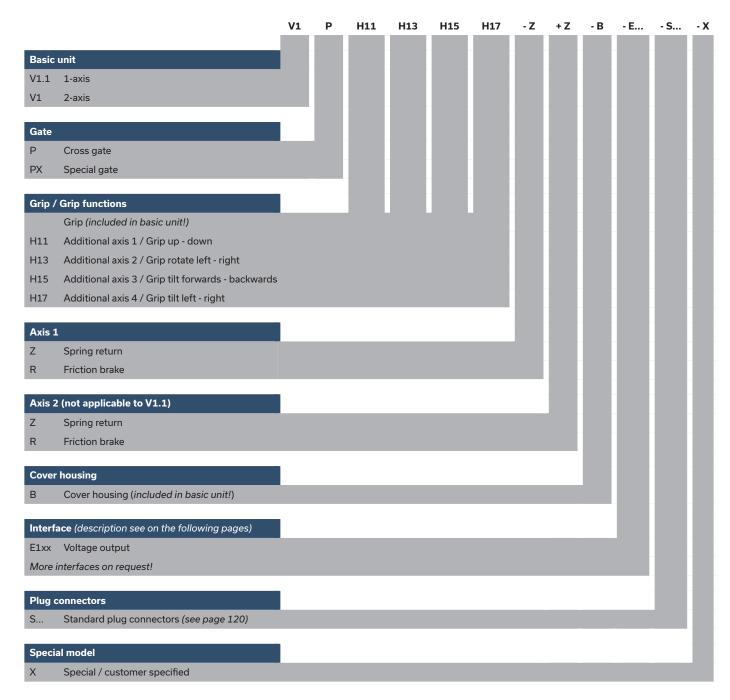
Mechanical life V1 6 million operating cycles

Supply voltage See interface -40°C to +85°C Operation temperature up to IP65 Degree of protection

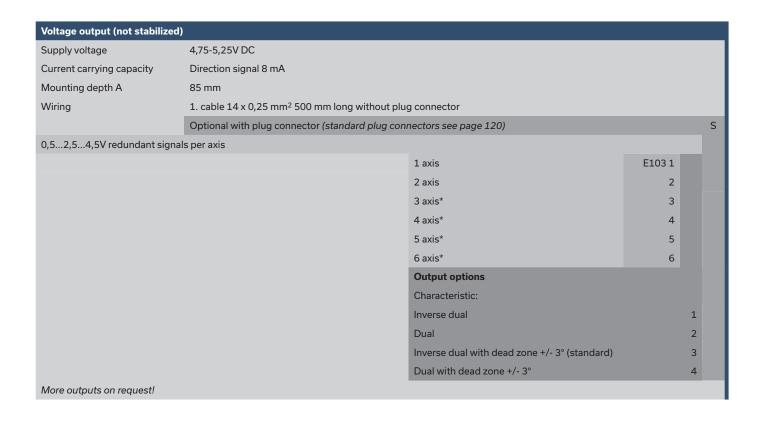
PLd compatible (EN ISO 13849, complies Functional safety

SIL2 to DIN EN IEC 61508)

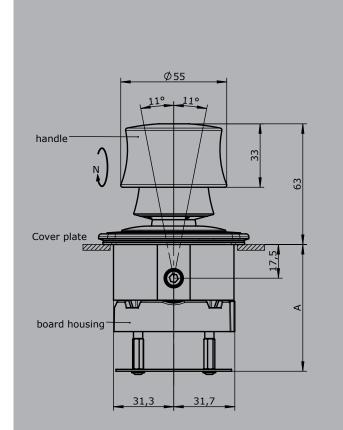


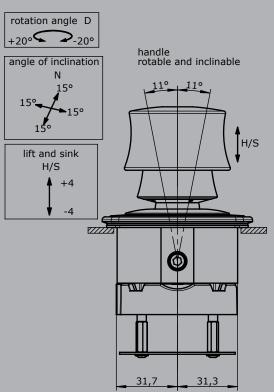


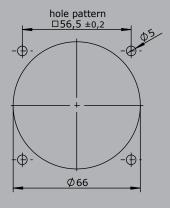


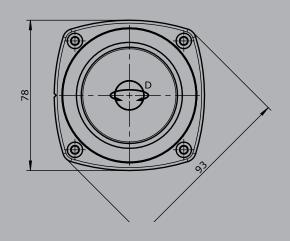












Technical details may vary based on configuration or application! Technical data subject to change without notice!



The Double-Handle Controller D85 is a robust switching device for electro hydraulic and hoisting applications. Long life and high reliability is ensured by the latest contactless hall-technology. The modular design enables the switching device to be used universally.

#### **Technical data**

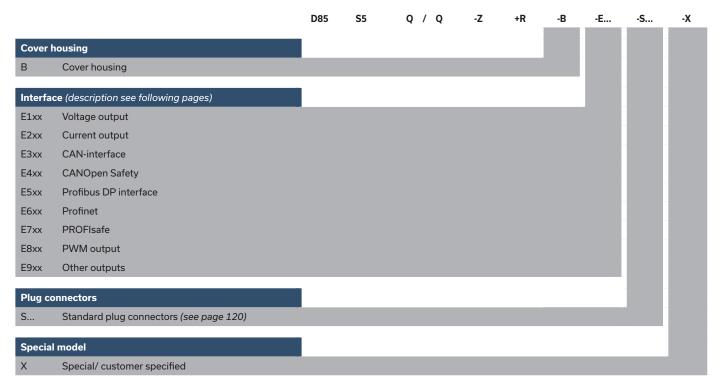
Mechanical life D85 8 million operating cycles

Operation temperature  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$  Degree of protection IP54 front



Example D85 S5 Q Q -Z -B -X / +R -E... -S... **Basic unit** D85 Control-handle extended Standard 160 mm\* S5 -20 mm S8 +20 mm \*Only available in combination with handle! Grip- control-handle left Knob М Mechanical zero interlock Т Dead man Н Signal button D Push button Q T-grip QD T-grip with push button side B10... Palm Grip B10... (see page 213) **Grip- control-handle right** See grip-control-handle left Axis 1: direction 1-2 left Spring return R Friction brake Axis 2: direction 3-4 left Spring return R Friction brake





#### Combination possibilities with our handles



Digital output			
Supply voltage	9-32 V DC		
Current carrying capacity	Direction signal 150 mA		
	Zero position signal 500 mA		
Mounting depth A	85 mm		
Wiring	Cable 500mm long without plug connector		
	Optional with plug connector (standard plug connectors see page 120)		S
2 direction signals + 1 zero pos	sition signal (galvanically isolated) per axis		
	2 axis	E001 2	

Voltage output (not stabilize	ed)				
Supply voltage	4,75-5,25 V DC				
Current carrying capacity	Direction signal 8 mA				
Mounting depth A	85 mm				
Wiring	Cable 500 mm long without plug connector				
	Optional with plug connector (standard plug con	nnectors see page 120)			S
0,52,54,5V redundant + 2	direction signals per axis				
		2 Achsen	E104 2		
		Output options			
		Characteristic:			
		Inverse dual		1	
		Dual		2	
		Inverse dual with dead zone +/- 3° (standa	ard)	3	
		Dual with dead zone +/- 3°		4	



Voltage output				
Supply voltage	9-32 V DC (*11,5-32)			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	85 mm			
Option	Input for capacitive sensor			
Wiring	Cable 500 mm long without plug conne	ctor		
	Optional with plug connector (standard	plug connectors see page 120)		
0,52,54,5 V redundant + 2	2 direction signals + 1 zero position signal (ga	alvanically isolated) per axis		
		2 axis	E112 2	
0510 V redundant + 2 dire	ection signals + 1 zero position signal (galvan	nically isolated) per axis, supply voltage 11,5 - 32 V	DC	
		2 axis	E132 2	
10010 V + 2 direction sign	nals + 1 zero position signal (galvanically isola	ated) per axis, supply voltage 11,5 - 32 V DC, sens	or redundant	
with error monitoring and erro	or signal			
		2 axis	E136 2	
with error monitoring		2 axis	E138 2	
		Output options		
		Output options Characteristic:		
			1	
		Characteristic:	1 2	
		Characteristic: Inverse dual *1	2	
		Characteristic: Inverse dual *1 Dual *1	2	
		Characteristic: Inverse dual *1  Dual *1  Inverse dual with dead zone +/- 3° *1 (st	2 (andard) 3 4	
		Characteristic: Inverse dual *1  Dual *1  Inverse dual with dead zone +/- 3° *1 (st  Dual with dead zone +/- 3°*1	2 (andard) 3 4	
		Characteristic: Inverse dual *1  Dual *1  Inverse dual with dead zone +/- 3° *1 (st  Dual with dead zone +/- 3°*1  *1 not combinable with output E136X a	2 tandard) 3 4 nd E138X	
		Characteristic: Inverse dual *1  Dual *1  Inverse dual with dead zone +/- 3° *1 (st  Dual with dead zone +/- 3°*1  *1 not combinable with output E136X a  Single *2	2 tandard) 3 4 nd E138X 5 rd) 6	
		Characteristic: Inverse dual *1  Dual *1  Inverse dual with dead zone +/- 3° *1 (st  Dual with dead zone +/- 3°*1  *1 not combinable with output E136X a  Single *2  Single with dead zone +/- 3° *2 (standa	2 tandard) 3 4 nd E138X 5 rd) 6	
		Characteristic: Inverse dual *1  Dual *1  Inverse dual with dead zone +/- 3° *1 (st  Dual with dead zone +/- 3°*1  *1 not combinable with output E136X a  Single *2  Single with dead zone +/- 3° *2 (standa *2 not combinable with output E112X a	2 tandard) 3 4 nd E138X 5 rd) 6	



Current output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	85 mm			
Option	Input for capacitive sensor			
Wiring	Cable 500 mm long without plug connector			
	Optional with plug connector (standard plug	connectors see page 120)		S
01020 mA + 2 direction sign	nals + 1 zero position signal (galvanically isolated	) per axis, sensor redundar	nt with error monitoring signal	
and error signal				
		2 axis	E206 2	
20020 mA + 2 direction sign	als + 1 zero position signal (galvanically isolated	) per axis, sensor redundar	nt with error monitoring	
and error signal				
		2 axis	E208 2	
41220 mA + 2 direction sign	nals + 1 zero position signal (galvanically isolated	) per axis, sensor redundar	nt with error monitoring	
and error signal				
		2 axis	E214 2	
20420 mA + 2 direction sign	nals + 1 zero position signal (galvanically isolated	) per axis, sensor redundar	nt with error monitoring	
and error signal				
		2 axis	E216 2	
+20020 mA + 2 direction sign	gnals + 1 zero position signal (galvanically isolate	ed) per axis, sensor redund	ant with error monitoring	
and error signal				
		2 axis	E226 2	
		Output options		
		Single		5
		Single with dead zone +/-	- 3° (standard)	6
		Digital output signals:		
		Output signals tandard:		
		Direction signals and zero	o position signals 1,5A 24 V DC	1
Current output with other value	on request!			

CAN	
Supply voltage	9-36 V DC
Idle current consumption	120 mA
Current carrying capacity	Direction signal 100 mA
	Zero position signal 100 mA
	External digital output for LEDs 5-30 mA (dependent on the number of LEDs)
	Digital switching output (potential-free) 100 mA
Mounting depth A	E3091: 85 mm
	E3091X: 105 mm
	E3101X - E3103X: 105 mm
	E3104X - E3105X: 125 mm
Protocol	CANOpen CiA DS 301 or SAE J 1939 (based on)
Baud rate	125 kBit/s to 1 Mbit/s (standard 250 kBit/s)
Output value	2550255
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)
	CAN (OUT) cable 300 mm with plug connector M12 (female)
	External in-/outputs cable 300 mm without plug connector
	External in-/outputs cable 300 mm without plug connector (additionally from 32 in-/outputs)

Technical details may vary based on configuration or application! Technical data subject to change without notice!



	Optional with plug connector (standard plug connectors see page 120)		S
CAN expansion stage 1		E309 1	
- 7 analoge Joystickachsen			_
- 16 digitale Joystickfunktionen			_
- Input for capacitive sensor			
With additional external in-/outp	outs		
- 8 external LED-outputs (dimma	able optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs	2	
- 16 external LED-outputs (dimm	nable optional), 1 switching output (potential-free, 100 mA), 16* external digital inputs	3	
External LED-outputs can be use			
*With the use of capacitive sens	or, the external digital inputs reduce by one input!		
CAN expansion stage 2		E310 1	_
- 10 analog joystick axis			
- 16 digital joystick functions			
- 2 inputs for capacitive sensor			
With additional external in-/outp	outs		
- 8 external LED-outputs (dimma	able optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs	2	
- 16 external LED-outputs (dimm	nable optional), 1 switching output (potential-free, 100 mA), 16* external digital inputs	3	
- 24 external LED-outputs (dimm	nable optional), 1 switching output (potential-free, 100 mA), 24 external digital inputs	4	
- 32 external LED-outputs (dimm	nable optional), 1 switching output (potential-free, 100 mA), 32* external digital inputs	5	
External LED-outputs can be use	ed in the grip for LEDs		
*With the use of capacitive sens	or, the external digital inputs reduce by one input!		
Main-axis with additional digital-	-/analog outputs separately wired (not via CAN)		
- 2 direction signals + 1 zero pos	ition signal (potential-free) per main-axis		
Additional analog outputs on red	quest!		

CANopen Safety	
Supply voltage	9-36 V DC
Idle current consumption	120 mA
Current carrying capacity	Direction signal 100 mA
	Zero position signal 100 mA
	External digital output for LEDs 5-30 mA (depending on the number of LEDs)
	Digital switching output (potential-free) 100 mA
Mounting depth A	E4091: 85 mm
	E4091X: 105 mm
	E4101X - E4103X: 105 mm
	E4104X - E4105X: 125 mm
Protocol	CAN Safety EN50325-5
Baud rate	125 kBit/s to 1 MBit/s (Standard 250 kBits)
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)
	CAN (OUT) cable 300 mm with plug connector M12 (female)
	External in-/outputs cable 300 mm without plug connector
	External in-/outputs cable 300 mm without plug connector (additionally from 32 in-/outputs)



Optional with plug connector (standard plug connectors see page 120)		S
CANopen Safety expansion stage 1	E409 1	
- 7 analog joystick axis		_
- 16 digital joystick functions		_
- Input for capacitive sensor		
With additional external in-/outputs		
- 8 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs	2	_
- 16 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 16* external digital inputs	3	_
External LED-outputs can be used in the grip for LEDs		
*With the use of capacitive sensor, the external digital inputs reduce by one input!		_
CANopen Safety expansion stage 2	E410 1	
- 10 analog joystick axis		_
- 16 digital joystick functions		
With additional external in-/outputs		
- 8 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs	2	_
$-16\ external\ LED\text{-}outputs\ (dimmable\ optional),\ 1\ switching\ output\ (potential-free,\ 100\ mA),\ 16^*\ external\ digital\ inputs$	3	_
- 24 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 24 external digital inputs	4	_
- 32 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 32* external digital inputs	5	_
External LED-outputs can be used in the grip for LEDs		
*With the use of capacitive sensor, the external digital inputs reduce by one input!		
Main-axis with additional digital-/analog outputs separately wired (not via CAN)		
- 2 direction signals + 1 zero position signal (potential-free) per main-axis		3
Additional analog outputs on request!		

Profibus DP			
Supply voltage	18-30 V DC		
Baud rate	to 12 MBit/s		
Output value	0128255		
Mounting depth A	105 mm		
Wiring	Profibus, cable 100 mm with plug D-Sub 9		
	Supply voltage (if applicable contact wiring) cable $12 \times 0.25 \text{ mm}^2 300 \text{ mm}$ long without plug contact wiring)	nector	
	External in-/outputs, cable 300 mm long without plug connector		
	Optional with plug connector (standard plug connectors see page 120)		S
Profibus DP		E501 1	
- 4 analog joystick axis			
- 16 digital joystick function			
- Input for capacitive sensor			
With additional external in-/o	utputs		
- 8 external LED-output, 8 ext	ternal digital input	2	
- 16 external LED-output, 16	external digital input	3	
External LED-outputs can be	used in the grip for LEDs		
With additional contact equip	oment separately wired (not via profibus)		
- 2 direction contacts + 1 zero	- 2 direction contacts + 1 zero position contact (not potential-free) per main-axis		
- 1 zero position contact (pot	ential-free) per main-axis		2



Profinet			
Supply voltage	18-30 V DC		
Baud rate	to 100 MBit/s		
Output value	05121023		
Mounting depth A	105 mm		
Verdrahtung	Profinet (1), cable 300 mm with M12 plug connector (female)		
	Profinet (2), cable 300 mm with M12 plug connector (female)		
	Supply voltage (if applicable contact wiring) cable $12 \times 0.25 \text{ mm}^2 300 \text{ mm}$ long without plug contact wiring)	nector	
	External in-/outputs, cable 300 mm long without plug connector		
	Optional with plug connector (standard plug connectors see page 120)		S
Profinet		E601 1	
- 4 analog joystick axis			
- 16 digital joystick functions			
- Input for capacitive sensor			
With additional external in-/out	puts		
- 8 external LED-outputs, 8 exte	rnal digital inputs	2	
- 16 external LED-outputs, 16 ex	xternal digital inputs	3	
*External LED-outputs can be us	sed in the grip for LEDs		
Main-axis with additional signals	s separately wired (not via profinet)		
- 2 direction signals + zero posit	ion signal (potential-free) per main-axis		3

PROFIsafe				
Supply voltage	18-30 V DC			
Baud rate	to 12 MBit/s			
Output value	05121023			
Mounting depth A	105 mm			
Wiring	Profinet (1), cable 300 mm with M12 plug connector (female)			
	Profinet (2), cable 300 mm with M12 plug connector (female)			
	Supply voltage (if applicable contact wiring) cable 12 x 0,25 mm <sup>2</sup> 300 mm long without plug contact	nector		
	External in-/outputs, cable 300 mm long without plug connector			
	Optional with plug connector (standard plug connectors see page 120)		S	
- 4 analog joystick axis		E701 1		
- 16 digital joystick functions				
- Input for capacitive sensor				
With additional external in-/outp	puts			
- 8 external LED-outputs, 8 exte	rnal digital inputs	2		
- 16 external LED-outputs, 16 external digital inputs				
*External LED-outputs can be used in the grip for LEDs				
Main-axis with additional signals	s separately wired (not via profinet safe)			
- 2 direction signals + zero posit	ion signal (potential-free) per main-axis		3	

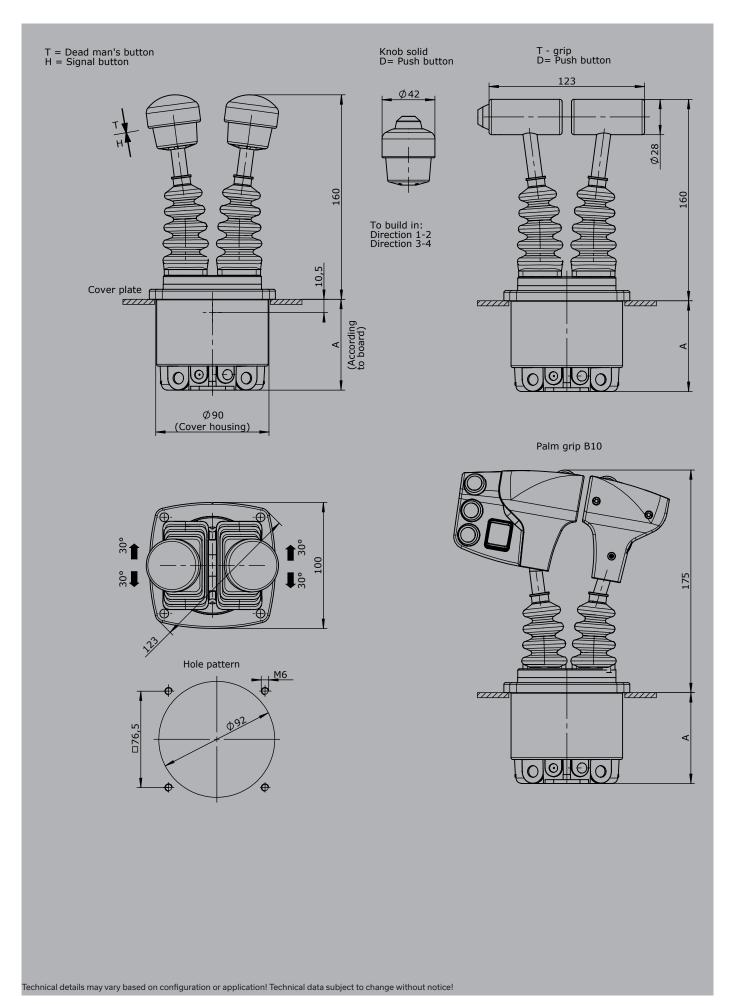


**PWM Outputs** Supply Voltage: 9-32 V DC Valve control current: max. 3 A PWM-frequency: 1225 Hz Dither frequency: 1...250 Hz adjustable Mounting depth A 85 mm Other features Creep speed per axis 5 configurable switching outputs 2A LED outputs for status indication Input for redundant deadman Wiring: Built-in socket Phoenix 2-pole (power supply) Cable 1 (PWM) 12 x 1 mm<sup>2</sup> 300 mm long without plug Cable 2 (switching output) 12 x 1 mm<sup>2</sup> 300 mm long without plug Cable 3 (creep speed / dead man)  $14 \times 0.25 \text{ mm}^2$  300mm long without plug S Optional with plug connector (standard plug connectors see page 120) E801 2 PWM Output 0-3 A for 2 proportional valve magnets per axis 2 axis

Other outputs				
Voltage output for PVG32 0,25	.0,50,75 Us, power supply 9-32 V DC			
Option	Input for capacitive sensor			
Wiring	Cable 14 x 0,25 mm <sup>2</sup> 300 mm long without plug connector			
	Optional with plug connector (standard plug connectors see page 120)			S
		2 axis	E907 2	
Main-axis with additional direction	on contacts per main-axis			4
8 Bit Gray-Code with direction si	gnals per main-axis, supply voltage 9-36 V DC			
Wiring:	Cable 37 x 0,14 mm <sup>2</sup> 300 mm long without plug connector (axis 1+2)			
	Optional with plug connector (standard plug connectors see page 120)			S
		2 axis	E903	2
8 Bit Binär-Code with direction s	ignals per main-axis, supply voltage 9-36 V DC			
Wiring:	Cable 37 x 0,14 mm <sup>2</sup> 300 mm long without plug connector (axis 1+2)			
	Optional with plug connector (standard plug connectors see page 120)			S
		2 axis	E904	2

Attachments	
Z01 Mating connector (CAN) M12 (male insert) with 2 m cable	20201140
Z02 Mating connector (CAN) M12 (female contact) with 2 m cable	20202298
Z03 Mating connector (Profibus) straight	22201440
Z04 Mating connector (Profibus) 90° angled	22201741
Z05 Mating connector (Profinet) M12 (male insert) with 2 m cable	5300000222







The V28 is a compact joystick commonly used in electro-hydraulic applications. Long life and high reliability is ensured by the latest contactless hall-technology. With many outputs and grip options the V28 series is hugely customisable.

### Technical data

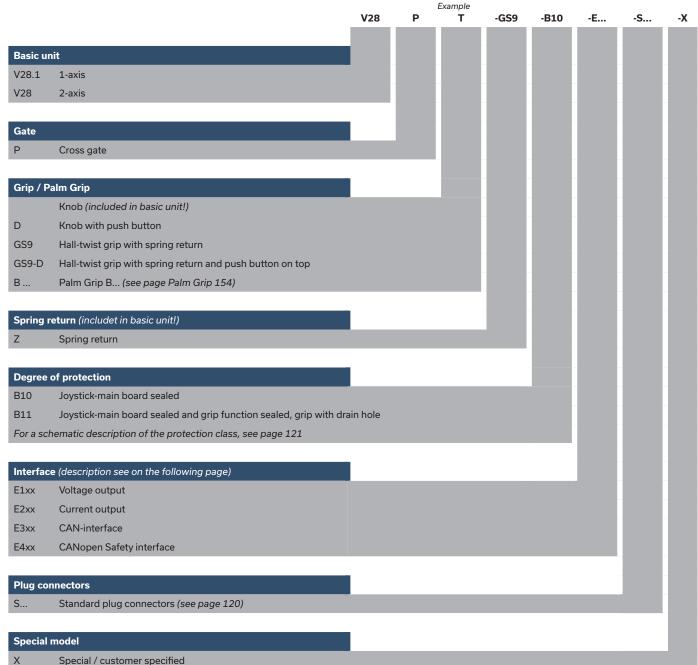
Mechanical life V28 5 million operating cycles

Supply voltage See interface -40°C to +85°C Operation temperature Degree of protection up to IP67

PLd compatible (EN ISO 13849, complies Functional safety

SIL2 to DIN EN IEC 61508)







Combination possibilities with our grips



p. 192	p. 160	p. 158	p. 56			
Voltage outp	out (not stabilized	)				
Supply voltag	ge	4,75-5,25 V DC				
Current carry	ring capacity	Direction signal 8	3 mA			
Mounting de	pth A	35 mm				
Wiring		1. cable 14 x 0,25	5 mm <sup>2</sup> 500 mm lo	ng without plug connector		
		2. cable 14 x 0,25	5 mm² (optional fo	or grip function) 500 mm long without plug connector		
		Optional with plu	ıg connector (star	dard plug connectors see page 120)		S
0,52,54,5	V redundant			1 axis	E103 1	
				2 axis	2	
0,52,54,5	V redundant + 2 d	lirection signals per	axis			
				1 axis	E104 1	
				2 axis	2	
				<b>Output options</b>		
				Characteristic:		
				Inverse dual		1
				Dual		2
				Inverse Dual with dead zone +/- 3° (standard)		3
				Dual with dead zone +/- 3°		4

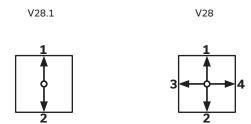


Voltage output				
Supply voltage	9-32 V DC (*11,5-32)			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	35 mm			
Wiring	1. cable $14 \times 0.25 \text{ mm}^2 500 \text{ mm}$ long without pl	ug connector		
	2. cable $14 \times 0.25 \text{ mm}^2$ (optional for grip function	on) 500 mm long without plug	connector	
	Optional with plug connector (standard plug co	nnectors see page 120)		S
0,52,54,5 V redundant + 2 o	direction signals + 1 zero position signal (galvanica	lly isolated) per axis		
		1 axis	E1121	
		2 axis	2	
		3 axis*	3	
0510 V 2 direction signals +	+ 1 zero position signal (galvanically isolated) per a	kis, supply voltage 11,5 - 32 V	'DC	
sensor redundant with error me	onitoring			
		1 axis	E132 1	
		2 axis	2	
		3 axis*	3	
10010 V + 2 direction signa	ıls + 1 zero position signal (galvanically isolated) pe	r axis, supply voltage 11,5 - 3	2 V DC,	
sensor redundant with error m	onitoring			
		1 axis	E136 1	
		2 axis	2	
		3 axis*	3	
		Output options		
		Characteristic:		
		Inverse dual *1		1
		Dual *1		2
		Inverse dual with dead zon	e +/- 3° *1 (standard)	3
		Dual with dead zone +/- 3°	*1	4
		*1 not combinable with out	put E136X	
		Single *2		5
		Single with dead zone +/- 3		6
		*2 not combinable with out	put E112X and E132X	
	ce can vary depending upon actuation element!			
Voltage output with other value	e on request!			



Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
,	Zero position signal 500 mA			
Mounting depth A	35 mm			
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm lo	ong without plug connector		
······································		for grip function) 500 mm long without plug con	nnector	
		ndard plug connectors see page 120)		
0. 10. 20 mA + 2 directions		cally isolated) per axis, sensor redundant with er	rror monitorina	
ozo m/    z direction s	ighais · 1 2010 position signal (garvaine	1 axis	E206 1	
		2 axis	2	
		3 axis*	3	
20 0 20 mA + 2 direction s	ignals + 1 zero position signal (galvanic	cally isolated) per axis, sensor redundant with er		
zoozo m/	ignals (12010 position signal (galvalla	1 axis	E208 1	
		2 axis	2	
		3 axis*	3	
4 12 20 mA + 2 direction s	ignals + 1 zero position signal (galvanic	cally isolated) per axis, sensor redundant with er		
	.g. (g. 1 20.0 p. 20.110.110.151.1111 (g. 11111.111	1 axis	E214 1	
		2 axis	2	
		3 axis*	3	
	ignals + 1 zero position signal (galvanic	cally isolated) per axis, sensor redundant with er		
20 4 20 mA + 2 direction s	ignais I zero poemen eigna (garram			
20420 mA + 2 direction s			F216.1	
20420 mA + 2 direction s		1 axis	E216 1	
20420 mA + 2 direction s		1 axis 2 axis	2	
20420 mA + 2 direction s		1 axis 2 axis 3 axis*		
20420 mA + 2 direction s		1 axis 2 axis 3 axis* Output options	2 3	
20420 mA + 2 direction s		1 axis 2 axis 3 axis*  Output options  Single	2 3	
20420 mA + 2 direction s		1 axis 2 axis 3 axis* Output options	2 3	ı
	face can vary depending upon actuatic	1 axis 2 axis 3 axis*  Output options  Single  Single with dead zone +/- 3° (stand	2 3	l

### Identification of the installation variants with switching directions:



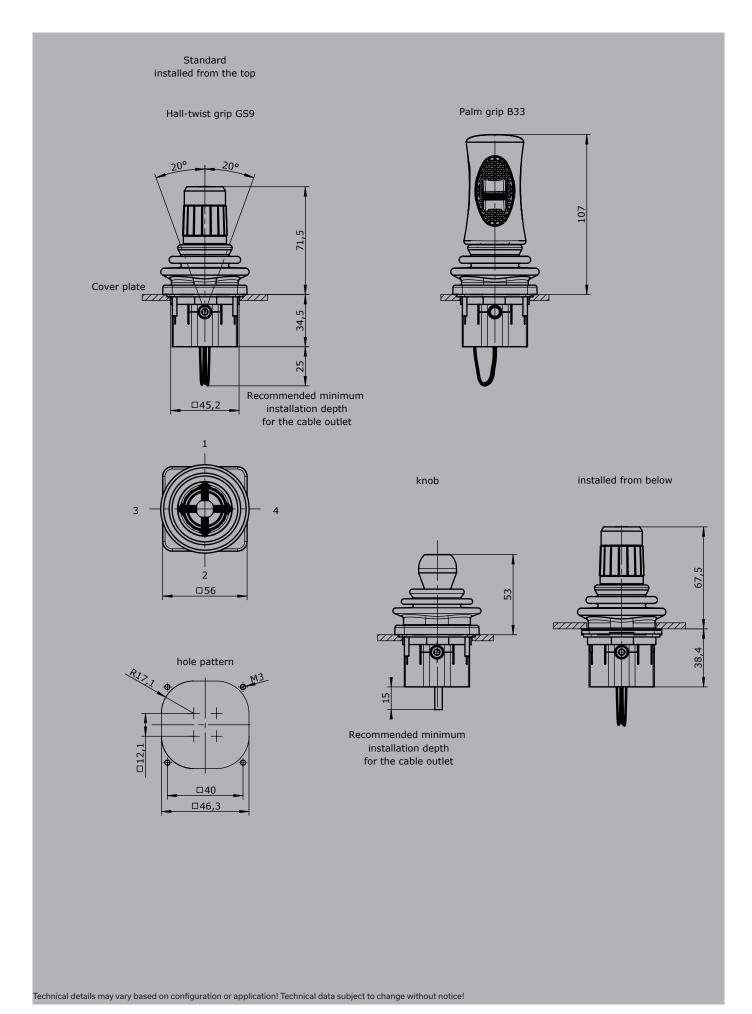


CAN			
Supply voltage	9-32 V DC		
Idle current consumption	120 mA (24 V DC)		
Current carrying capacity	External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs)		
Mounting depth A	35 mm		
Protocol	CANopen CiA DS 301 or SAE J1939 (based on)		
Baud rate	20 kBit/s to 1 Mbit/s (standard 250 kBit/s)		
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)		
	CAN (OUT) cable 300 mm with plug connector M12 (female)		
	External in-/outputs cable 300 mm long without plug connector		
	Optional with plug connector (standard plug connectors see page 120)		S
CAN		E3141	_
- 4 analog joystick axis			_
- 8 digital joystick functions (inc	l. input for capacitive sensor)		
- 8 LED-Outputs (dimmable opt	ional) for grip function		

CANopen Safety			
Supply voltage	9-32 V DC		
Idle current consumption	120 mA (24 V DC)		
Current carrying capacity	External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs)		
Baud rate	20 kBit/s to 1 MBit/s (standard 250 kBit/s)		
Mounting depth	35 mm		
Protocol	CANopen Safety EN50325-5		
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)		
	CAN (OUT) cable 300 mm with plug connector M12 (female)		
	External in-/outputs cable 300 mm long without plug connector		
	Optional with plug connector (standard plug connectors see page 120)		S
CANopen Safety		E413 1	
- 4 analog joystick axis			
- 8 digital joystick functions (in	cl. input for capacitive sensor)		
- 8 LED-Outputs (dimmable op	tional) for grip function		

Attachments	
Z01 Mating connector M12 male insert with 2 m cable	20201140
Z02 Mating connector M12 female insert with 2 m cable	20202298









The Single-Axis Controller S26 is a hall sensor switching device designed for electro-hydraulic and remote controlled hydraulic. The modular design of the switching device is universally applicable.

### **Technical data**

Mechanical life S26 6 million operating cycles

-40°C to +85°C Operating temperature

Degree of protection up to IP54, electronic assembly IP67

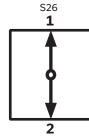
PLd compatible (EN ISO 13849, complies SIL2 to DIN EN IEC 61508) Functional safety



Example **S26** - Z Т - E... - S... - X **Basic unit** S26 1-axis Grip / Palm Grip М Mechanical zero interlock Т Dead man Н Signal button D Push button В... Palm Grip B... (on request!) Ζ Spring return R Friction brake **Interface** (description on the following pages) E0xx Digital output E1xx Voltage output E2xx Current output Plug connectors Standard plug connectors (see page 120) Special model Special / customer specified

#### Identification of the installation variants

with switching directions:



Technical details may vary based on configuration or application! Technical data subject to change without notice!



Digital output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Wiring	Cable 500 mm long without plug connector			
	Optional with plug connector (standard plug co	onnectors see page 120)		S
2 direction signals + 1 zero posi	tion signal (galvanically isolated)			
		1 axis	E001 1	

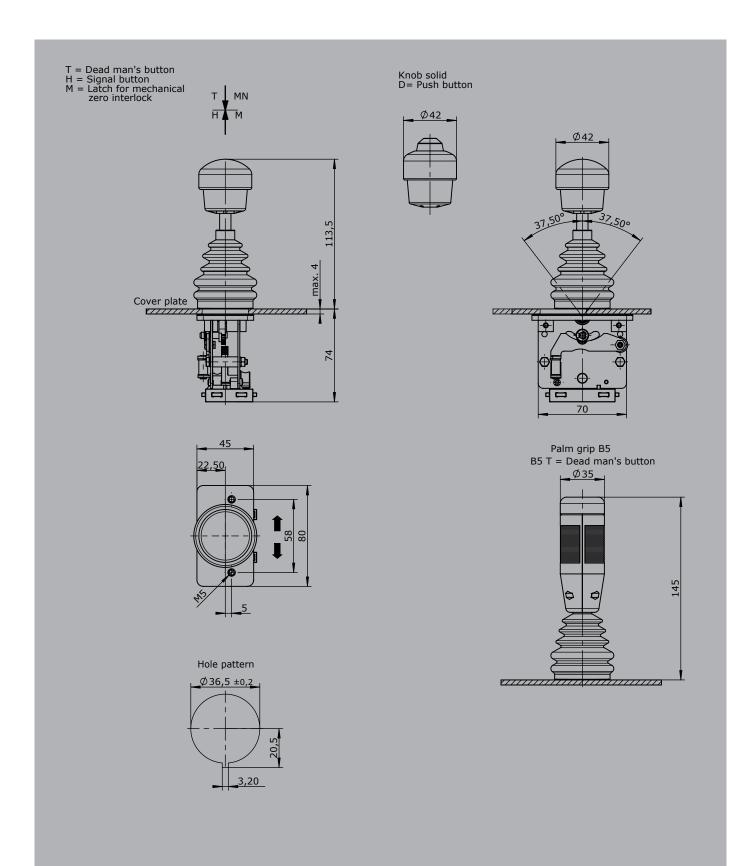
Voltage output (not stabilize	d)			
Supply voltage	4,75-5,25 V DC			
Current carrying capacity	Direction signal 8 mA			
Wiring	Cable 500 mm long without plug connector			
	Optional with plug connector (standard plug connector)	onnectors see page 120)		S
0,52,54,5 V redundant + 2	direction signals			
		1 axis	E104 1	
		Output options		
		Characteristic:		
		Inverse dual		1
		Dual		2
		Inverse dual with dead zone +/- 3° (standard)		3
		Dual with dead zone +/- 3° *1		4

Voltage output				
Supply voltage	9-32 V DC (*11,5-32 V)			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Wiring	Cable 500 mm long without plug connector			
	Optional with plug connector (standard plug co	onnectors see page 120)		S
0,52,54,5 V redundant + 2 d	irection signals + 1 zero position signal (galvanica	ally isolated)		
		1 axis	E1121	
0510 V redundant + 2 direct	ion signals + 1 zero position signal (galvanically is	solated), supply voltage 11,5 - 32 V DC		
		1 axis	E1321	
10010 V + 2 direction signal	s + 1 zero position signal (galvanically isolated), s	supply voltage 11,5 - 32 V DC, sensor redundant		
with error monitoring and error	signal			
		1 axis	E1361	
		Output options		
		Characteristic:		
		Inverse dual *1		1
		Dual *1		2
		Inverse dual with dead zone +/- 3° *1 (standard)		3
		Dual with dead zone +/- 3° *1		4
		*1 not combinable with output E136X		
		Single *2		5
		Single with dead zone *2 (standard)		6
Voltage output with other value	on request!	*2 not combinable with output E112X and E132X		



Current output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Wiring	Cable 500 mm long without plug connector			
	Optional with plug connector (standard plug connectors see page	2 120)		S
01020 mA + 2 direction si	gnals + 1 zero position signal (galvanically isolated), sensor redundant	with error monitoring and erro	r signal	
		1 axis	E206 1	
20020 mA + 2 direction si	gnals + 1 zero position signal (galvanically isolated), sensor redundant	with error monitoring and erro	r signal	
		1 axis	E208 1	
41220 mA + 2 direction si	gnals + 1 zero position signal (galvanically isolated), sensor redundant	with error monitoring and erro	r signal	
		1 axis	E214 1	
20420 mA + 2 direction si	gnals + 1 zero position signal (galvanically isolated), sensor redundant	with error monitoring and erro	r signal	
		1 axis	E216 1	
		Output options		
		Single		5
		Single with dead zone +/-	3° (standard)	6
Current output with other value	ue on request!			







The V22 is a joystick commonly used in electro-hydraulic applications. Long life and high reliability is ensured by the latest contactless hall-technology.

#### **Technical data**

Mechanical life V22 3 million operating cycles

-40°C to +85°C Operation temperature IP67 front Degree of protection

PLd compatible (EN ISO 13849, complies Functional safety

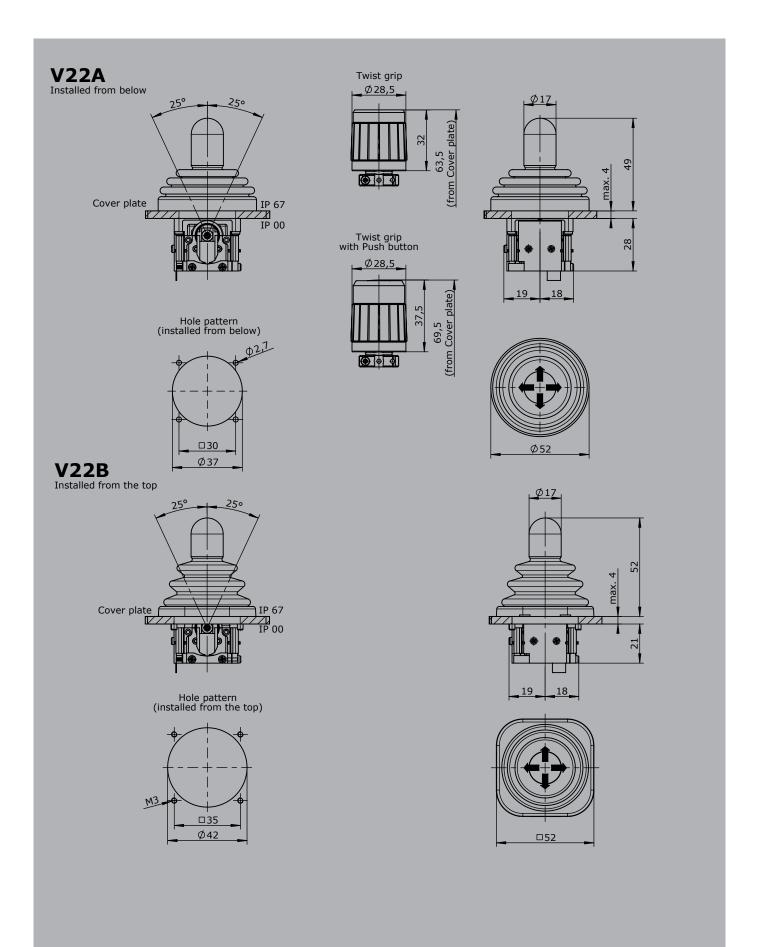
SIL2 to DIN EN IEC 61508)



Example -E10321 .P V22A n **Basic unit** V22.1A 1-axis with spring return, installation from below V22A 2-axis with spring return, installation from below V22.1B 1-axis with spring return, installation from top V22B 2-axis with spring return, installation from top Gate Р Cross gate PXSpecial gate Grip Knob (standard) D Push button GS9 Hall-twist grip with spring return Hall-twist grip with spring return and push button on top GS9-D Interface Voltage output E103 1 0,5...2,5...4,5 V redundant, Ub= 5 V 1 axis 2 2 axis Characteristic: Inverse dual (standard) Dual Special model Special / customer specified

Attachments	
Mating connector JST 8-pole	5300000260
Mating connector JST 8-pole with single wire 500 mm long	5300000261









The S11 is a one-axis joystick designed for electro-hydraulic and remote controlled hydraulic. Long life and high reliability is ensured by the latest contactless hall-technology. The modular design of the switching device is universally applicable.

#### **Technical data**

Mechanical life S11 6 million operating cycles

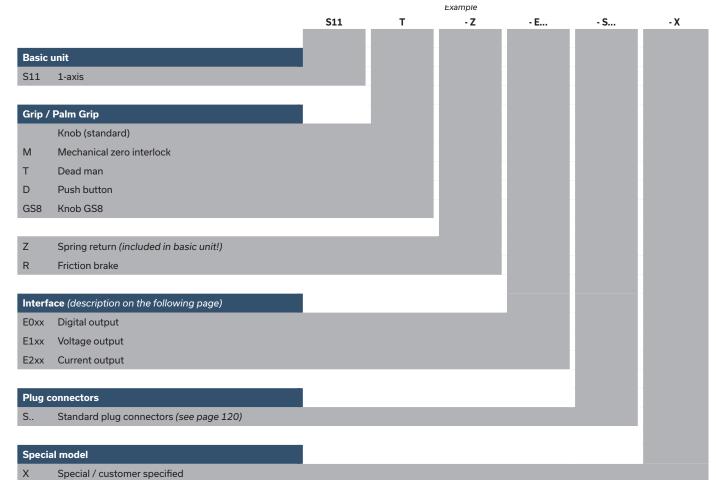
-40°C to +85°C Operating temperature

up to IP65, electronic assembly IP67 Degree of protection

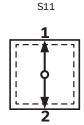
PLd compatible (EN ISO 13849, complies Functional safety

SIL2 to EN IEC 61508)





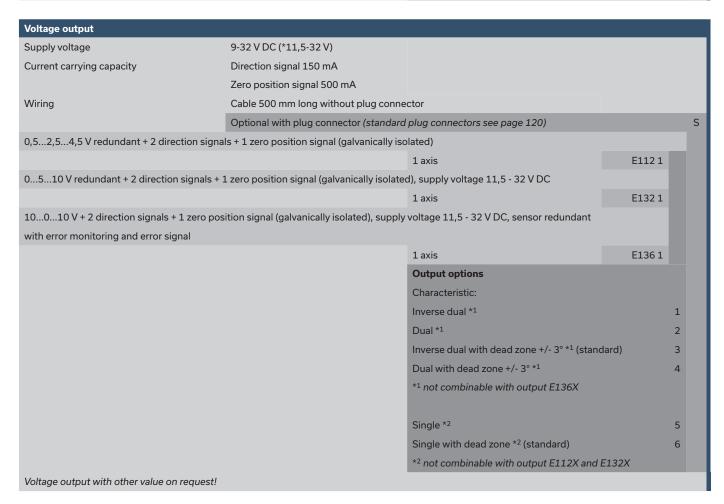
#### Identification of the installation variants with switching directions:





Digital Output		
Supply voltage	9-32 V DC	
Current carrying capacity	Direction signal 150 mA	
	Zero position signal 500 mA	
Wiring	Cable 500 mm long without plug connector	
	Optional with plug connector (standard plug connectors see page 120)	S
Cable 500mm long with plug (male)		
	1 axis	E0011

Voltage output (not stabilized)				
Supply voltage	4,75-5,25 V DC			
Current carrying capacity	Direction signal 8 mA			
Wiring	Cable 500 mm long without plug conne	ector		
	Optional with plug connector (standard	plug connectors see page 120)		S
0,52,54,5V redundant + 2 direction signal	ls			
		1 axis	E104 1	
		Output options		
		Characteristic:		
		Inverse dual		1
		Dual		2
		Inverse dual with dead zone +/- 3° (standard)		3
		Dual with dead zone +/- 3°		4

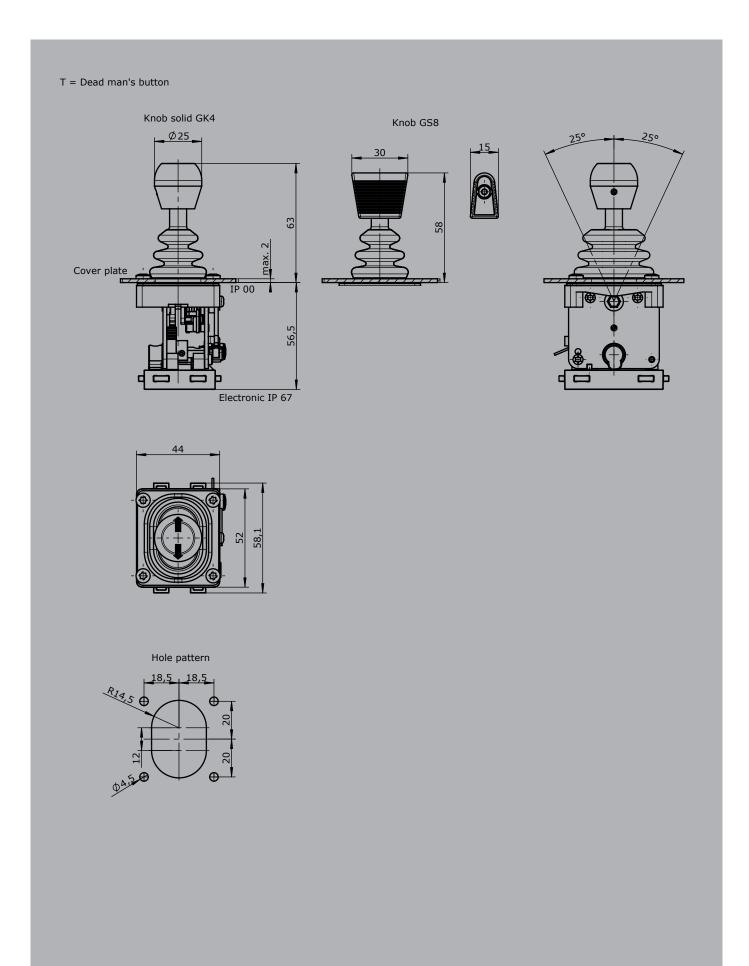




Current output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Wiring	Cable 500 mm long without plug connector			
	Optional with plug connector (standard plug connectors see page 2)	age 120)		
01020 mA + 2 direction s	ignals + 1 zero position signal (galvanically isolated), sensor redun	dant with error monitoring and	error signal	
		1 axis	E206 1	
20020 mA + 2 direction s	ignals + 1 zero position signal (galvanically isolated), sensor redun	dant with error monitoring and	error signal	
		1 axis	E208 1	
41220 mA + 2 direction s	signals + 1 zero position signal (galvanically isolated), sensor redun-	dant with error monitoring and	error signal	
		1 axis	E214 1	
20420 mA + 2 direction s	ignals + 1 zero position signal (galvanically isolated), sensor redun	dant with error monitoring and	error signal	
		1 axis	E216 1	
		Output options		
		Single		5
		Single with dead zone +/-3°	(standard)	6
Voltage output with other val	lue on request!			

## **Single-Axis Controller** S11









The V8/VV8 is a robust joystick commonly used in electro-hydraulic applications. With many output options including voltage, amperage and switch contacts and many grip options the V8 / VV8 series is hugely customisable.

### **Technical data**

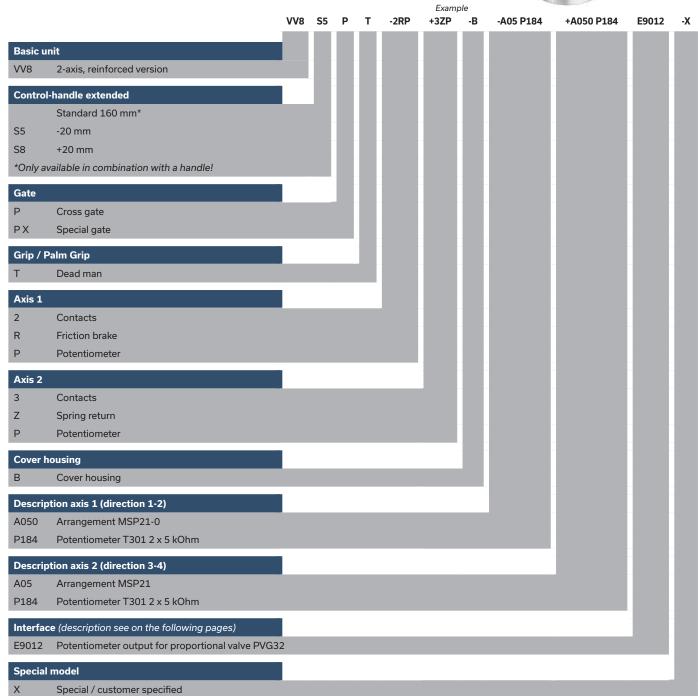
Mechanical life V8 10 million operating cycles

Mechanical life VV8 20 million operating cycles

Operation temperature -40°C to +85°C

Degree of protection up to IP54

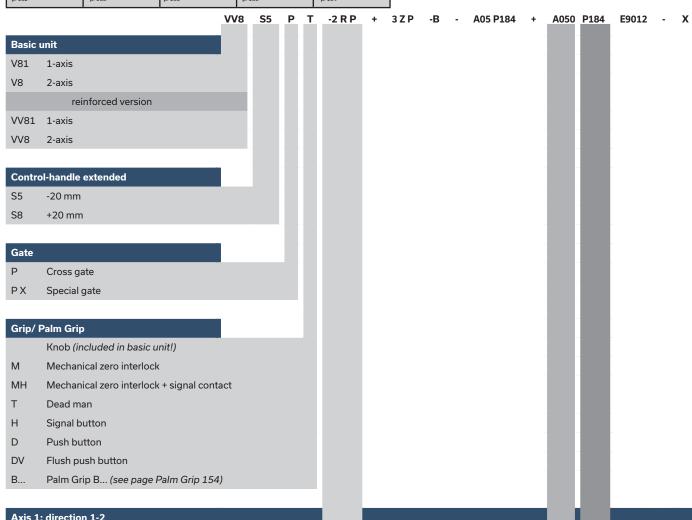




### **Multi-Axis Controller** V8 / VV8

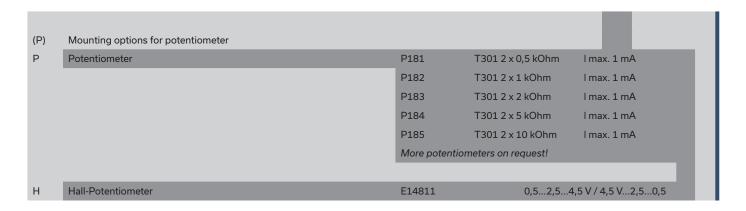






	AXIS 1	direction 1-2		_							
	1	1 contact	Standard contact - ar	andard contact - arrangement see page 122							
	2	2 contacts	e.g.								
	3	3 contacts	A98	MS0	Zero position contact						
			A05	MS21	Direction contacts						
			A050	MS21-0	Direction contacts + zero position contact						
Z Spring return											
	R	Friction brake only available with a VV8!									
	Technica	details may vary based on configuration or app	olication! Technical data su	bject to change withou	ut notice!						





VV8	55	Р	- 1	-2 R P	+	3 Z P	-B	-	A05	P184	+	A050 P184	E9012	-	Х

Axis 2	: direction 3-4 (not applied for V81/V	V81)			
1	1 contact	Standard contact -	arrangement se	e page 1	122
2	2 contacts	e.g.			
3	3 contacts	A98	MS0		Zero position contact
		A05	MS21		Direction contacts
		A050	MS21-0		Direction contacts + zero position contact
Z	Spring return				
R	Friction brake only available with a V	V8!			
(P)	Mounting options for potentiometer				
Р	Potentiometer			P181	T301 2 x 0,5 kOhm I max. 1 mA
				P182	T301 2 x 1 kOhm I max. 1 mA
				P183	T301 2 x 2 kOhm I max. 1 mA
				P184	T301 2 x 5 kOhm I max. 1 mA
				P185	T301 2 x 10 kOhm I max. 1 mA
				More p	potentiometers on request!
Н	Hall-Potentiometer			E1481	0,52,54,5V/4,5V2,50,5

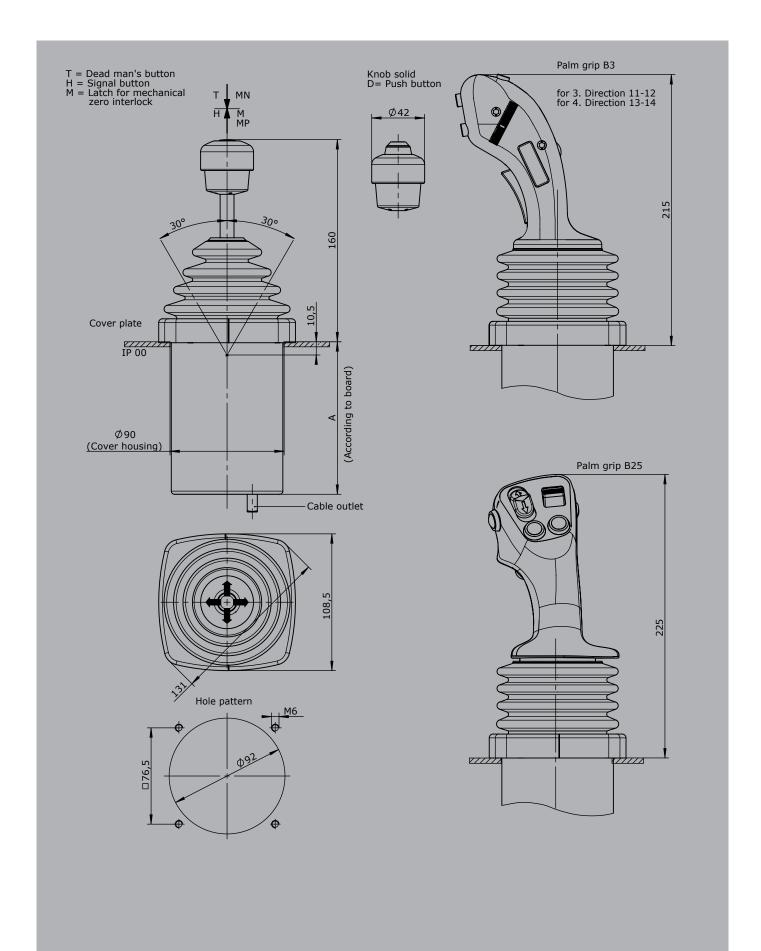
	8VV	S5	Р	Т	-2 R P	+	3 Z P	-B	-	A05 P184	+	A050 P184	E9012	-	Х
Cover housing															

Cover I	10USI	ng			
В	Cov	er housing			
Interfa	се				
		Potentiometer output			
E901	E901 Potentiometer output for propo		tional valve PVG32		
		0,250,50,75 Us			
	1		1 axis		
	2		2 axis		
	3		3 axis		
	4		4 axis		

Specia	ıl model
Χ	Special / customer specified

# **Multi-Axis Controller** V8 / VV8





## **Multi-Axis Controller** V6 / VV6



The Multi-Axis Controller V6 / VV6 is a robust switching device designed for crane systems and hoisting equipment. The modular design and the many possible combinations with our Palm Grips make this joystick universally applicable.

### **Technical data**

Mechanical life V6 10 million operating cycles

Mechanical life VV6 20 million operating cycles

Operation temperature -40°C to +85°C

Degree of protection up to IP54 front



Example V62L -01 Z P -A05 P134 S5 Ρ Т +03A R C +A110 C01 -X **Basic unit** V62L 2-axis left Control-handle extended S5 -20 mm Gate Cross gate Grip / Palm Grip Dead man Axis 1 (direction 1-2) 01 2 contacts (2A 250 V AC15) Ζ Spring return Ρ Potentiometer Axis 2 (direction 3-4) 6 contacts (4A 250 V AC15) 03A R Friction brake С Opto-electronical encoder Description axis 1 (direction 1-2) A05 Arrangement MS21 P134 Potentiometer T396 2 x 5 kOhm Description axis 2 (direction 3-4) A110 Arrangement MS24-0 OEC 2-1-1 Special model Special / customer specified





p. 199

p. 199

p. 192

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p. 190

p. 156

V62L

S

V62L S5 P T -01 Z P +03A R C -A05 P134 +A110 C01 -X

#### Basic unit V61L 1-axis left V61R 1-axis right V61.1 1-axis V64.1 1-axis V62L 2-axis left V62R 2-axis right V64 2-axis reinforced version VV61L 1-axis left VV61R 1-axis right VV61.1 1-axis VV64.1 1-axis VV62L 2-axis left VV62R 2-axis right VV64 2 axis

### Control-handle extended

Standard 180 mm\*

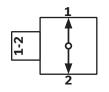
S3 -40 mm S5 -20 mm S8 +20 mm

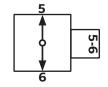
\*Only available in combination with a handle!

#### Gate

Р	Cross gate
PX	Special gate

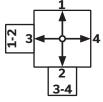
### Identification of the installation variants with switching directions:

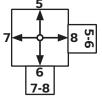




V61L/VV61L

V61R/VV61R





V62L/VV62L

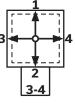
V62R/VV62R





V64.1/VV64.1

V61.1/VV61.1



V64/VV64



-01 Z P +03A R C -A05 P134 V62L S5 Т +A110 C01 -X Grip / Palm Grip Knob (included in basic unit!) Μ Mechanical zero interlock MN Mechanical zero interlock (push down) Т Dead man MT\* Mechanical zero interlock + dead man Н Signal button МН Mechanical zero interlock + signal button D Push button MD\* Mechanical zero interlock + push button DV Flush push button Mechanical zero interlock + flush push button MDV\* \*Only possible with VV6! В... Palm Grip B... (see Palm Grip page 154) Attention! When using some handles the deflection angle can be reduced to 28°!

			V62L	S5	Р	Т	-01 Z P	+03A R C	-A05 P134	+A110 C01	-X
Axis	1: di	rection 1-2 left / direction 5-6 right									
		(Standard contacts gold-plated 2A 250 V	'AC15)				•				
01		2 contacts		Standar	d conta	ct - arran	gement see p	page 122			
02		4 contacts		z.B.							
03		6 contacts		A980			MS00				
04		8 contacts		A05			MS21				
05		10 contacts		A0500			MS21-00				
06		12 contacts		A110			MS24-0				
	A= silver contacts (4A 250V AC15)				ntact - a	rrangeme	t				
Z R (P)	Frict	ng return tion brake sibility of mounting potentiometer and enc	oder (Ge	ssmann-i	types)						
Р	Pote	entiometer		P131		T396 2 >	c 0,5 kOhm	l max. 1 mA			
				P132		T396 2 >	k 1 kOhm	I max. 1 mA			
				P133		T396 2 >	c 2 kOhm	l max. 1 mA			
				P134		T396 2 >	k 5 kOhm	l max. 1 mA			
				P135		T396 2 >	(10 kOhm	l max. 1 mA			
				More po	otention	neters on	request!				
С	Enco	oder		C Encoder see page 130							



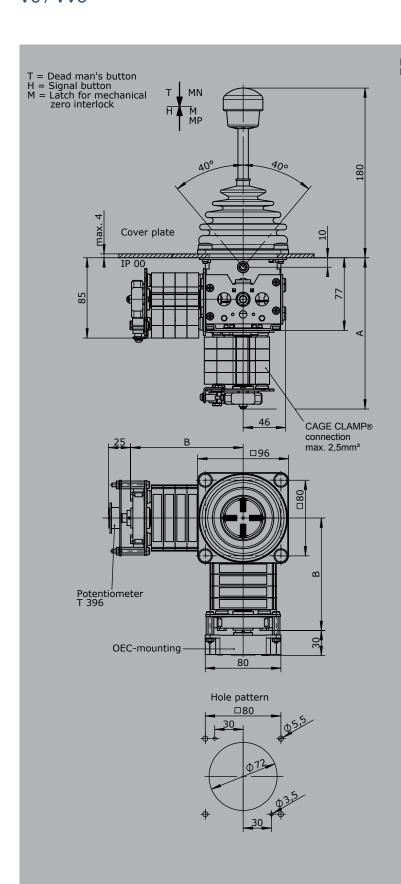


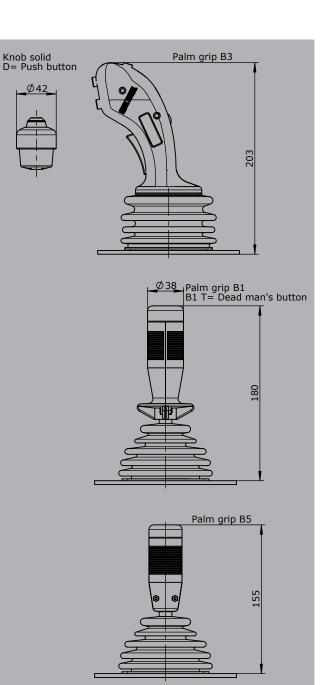
V62L S5 P -01 Z P +03A R C -A05 P134 +A110 C01 -X Axis 2: direction 3-4 left / Direction 7-8 right (not applicable for V/VV61, V/VV61.1, V/VV64.1) (Standard contacts gold-plated 2A 250 V AC15) 01 2 contacts Standard contact - arrangement see page 122 02 4 contacts z.B. 03 6 contacts A980 MS00 8 contacts A05 04 MS21 05 10 contacts A0500 MS21-00 06 12 contacts A110 MS24-0 A = Silver contacts (4A 250 V AC15) A99 contact - arrangement according customer request Z Spring return R Friction brake (P) Possibility of mounting potentiometer and encoder (Gessmann-types) Potentiometer P131 T396 2 x 0,5 kOhm I max. 1 mA P132 T396 2 x 1 kOhm I max. 1 mA P133 T396 2 x 2 kOhm I max. 1 mA T396 2 x 5 kOhm P134 I max. 1 mA P135 T396 2 x 10 kOhm I max. 1 mA More potentiometers on request! Encoder C... Encoder see page 157 V62L S5 P T -01 Z P +03A R C -A05 P134 +A110 C01 Special model Special /customer specified **Attachments** Indicating labels Indicating labels with engraving

# **Multi-Axis Controller** V6 / VV6



Ø42





Туре	No. of contacts	Dim. A	Dim. B
01	2	119	82
02	4	131	94
03	6	144	107
04	8	156	119
05	10	169	132
06	12	181	144

Technical details may vary based on configuration or application! Technical data subject to change without notice!







The Multi-Axis Controller VA6 is available in either single-axis or multi-axis options and is a robust explosion proof controller commonly used in crane and hoisting applications. The modular design enables the switching device to be used universally.

### **Technical data**

Mechanical life VA6 10 million operating cycles

Operation temperature -40°C to +85°C

Degree of protection IP54 front

IP66 (microswitch and poteniometer)

Identifications (Ex) II 2G IIC T5 or T6

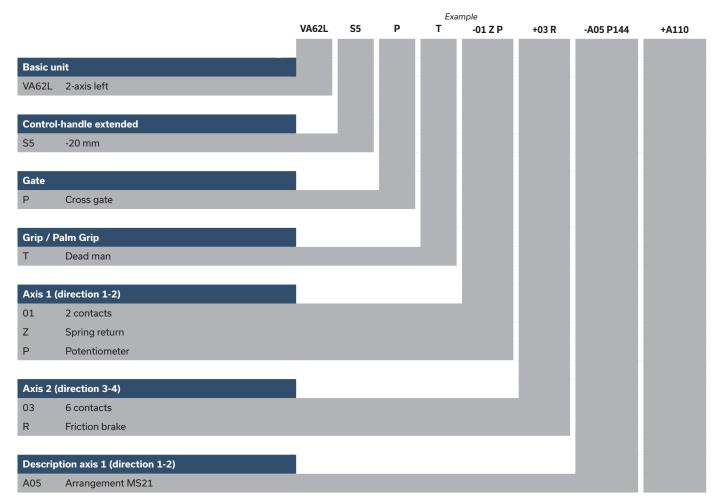
⟨€x⟩ II 2D T85° or T95°C

Group of devices

Equipment category 2D and 2G

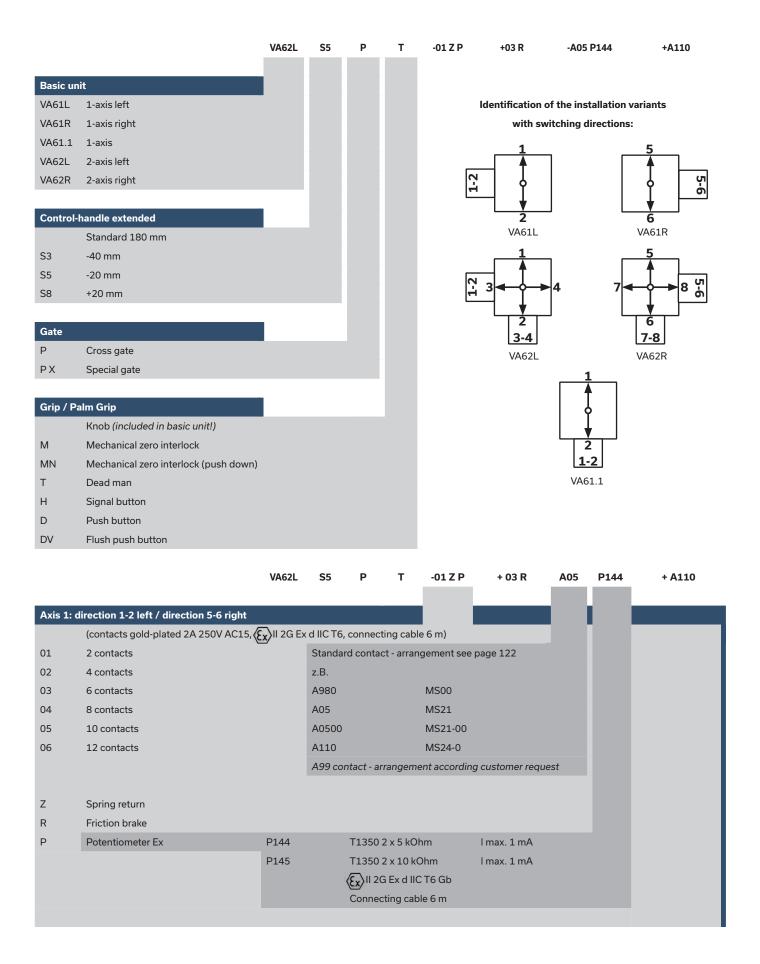
Certificate OBAC 17 ATEX 0126X











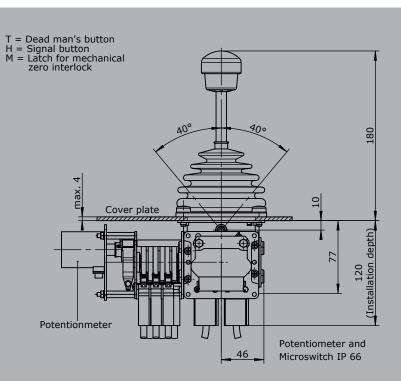




-01 Z P +03 R -A05 P144 VA62L S5 P +A110 Axis 2: direction 3-4 left / Direction 7-8 right (not applicable for VA61, VA61.1) (contacts gold-plated 2A 250 V AC15, (Ex) II 2G Ex d IIC T6, connection cable 6 m) 01 2 contacts Standard contact - arrangement see page 122 4 contacts z.B. 03 6 contacts A980 MS00 8 contacts A05 MS21 04 MS21-00 05 10 contacts A0500 06 12 contacts A110 MS24-0 A99 contact - arrangement according customer request Ζ Spring return R Friction brake P144 T1350 2 x 5 kOhm Potentiometer Ex I max. 1 mA P145 T1350 2 x 10 kOhm I max. 1 mA ⟨Ex⟩ II 2G Ex d IIC T6 Gb connection cable 6 m

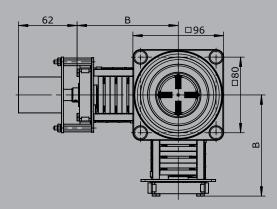




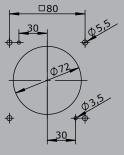








Hole pattern



Туре	No. of contacts	Dim. B
01	2	82
02	4	94
03	6	107
04	8	119
05	10	132
06	12	144

### **Double-Handle Controller**



The Double-Handle Controller D8 is a robust switching device for electro hydraulic and the hoisting applications. The modular design enables the switching device to be used universally.

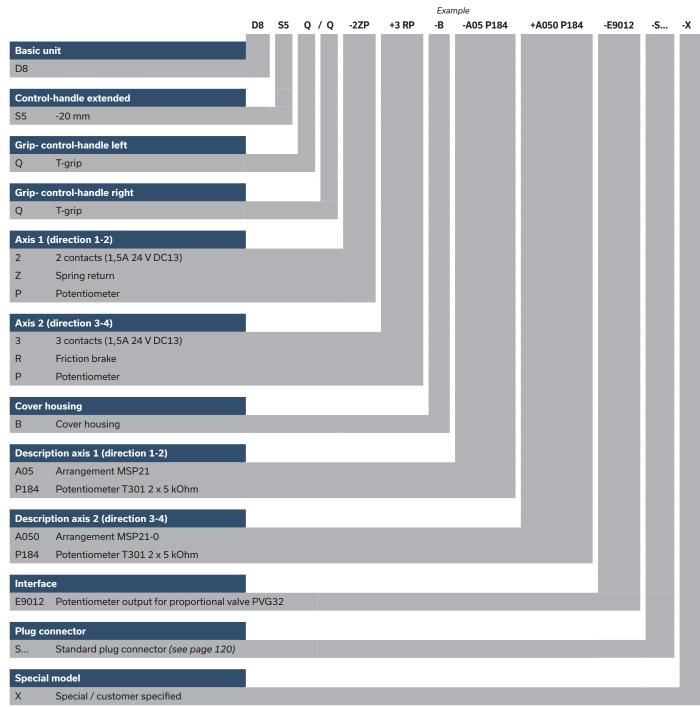
#### **Technical data**

Mechanical life D8 8 million operating cycles

Operation temperature -40°C to +85°C

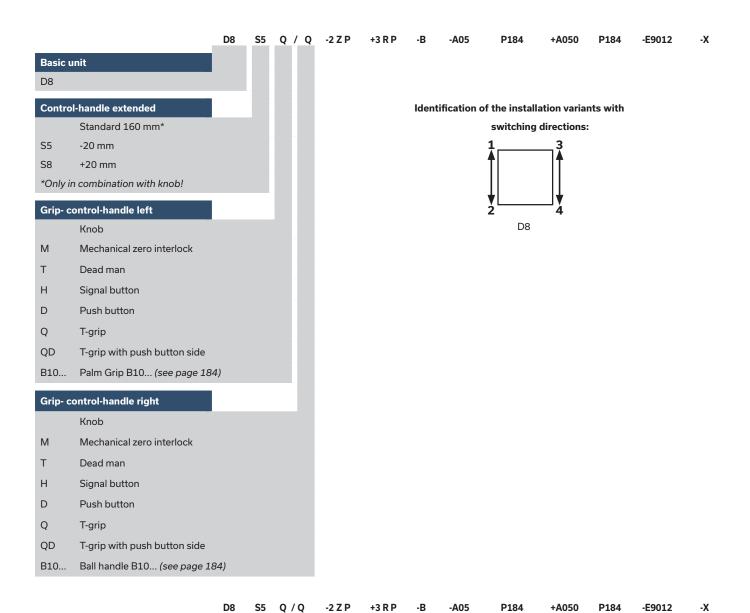
Degree of protection up to IP54 front





### **Double-Handle Controller**





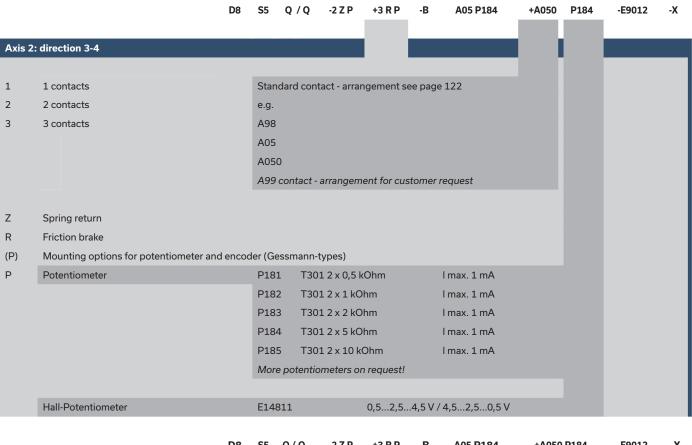
			33 (7)		Į
Axis 1:	direction 1-2 left				ı
1	1 contact	Standa	rd contact - arrangemer	nt see page 122	
2	2 contacts	e.g.			
3	3 contacts	A98			
		A05			
		A050			
		A99 co	ntact - arrangement for	customer request	
_					
Z	Spring return				
R	Friction brake				
(P)	Mounting options for potent	iometer a	nd encoder (Gessmann	-types)	
Р	Potentiometer	P181	T301 2 x 0,5 kOhm	l max. 1 mA	
		P182	T301 2 x 1 kOhm	l max. 1 mA	
		P183	T301 2 x 2 kOhm	l max. 1 mA	
		P184	T301 2 x 5 kOhm	I max. 1 mA	
		P185	T301 2 x 10 kOhm	I max. 1 mA	
		More p	otentiometers on reque	st!	
	11-11		F1 4011	05 25 45 1/45 25	0.5.1/
Н	Hall-potentiometer		E14811	0,52,54,5 V / 4,52,5	0,5 V

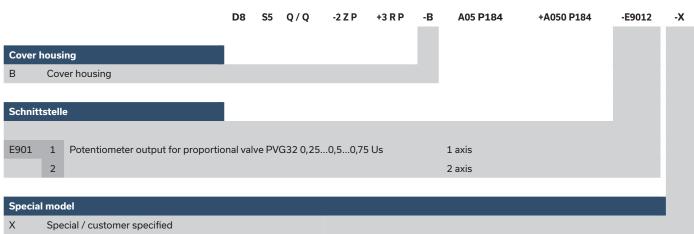
### **Double-Handle Controller**



Combination possibilities with our handles

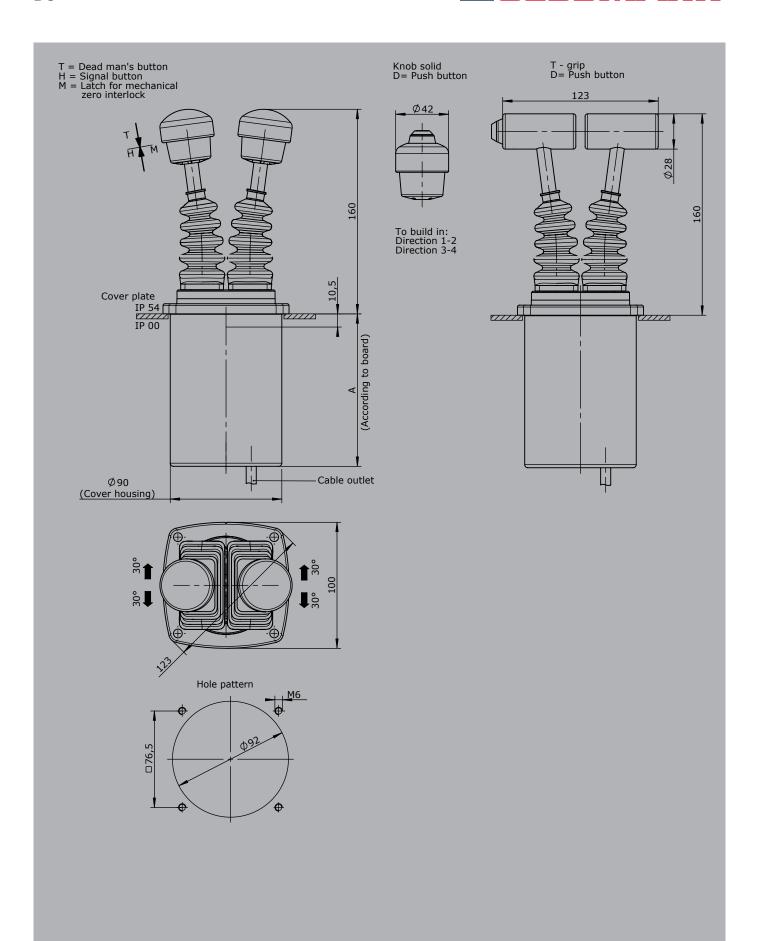






# **Double-Handle Controller** D8









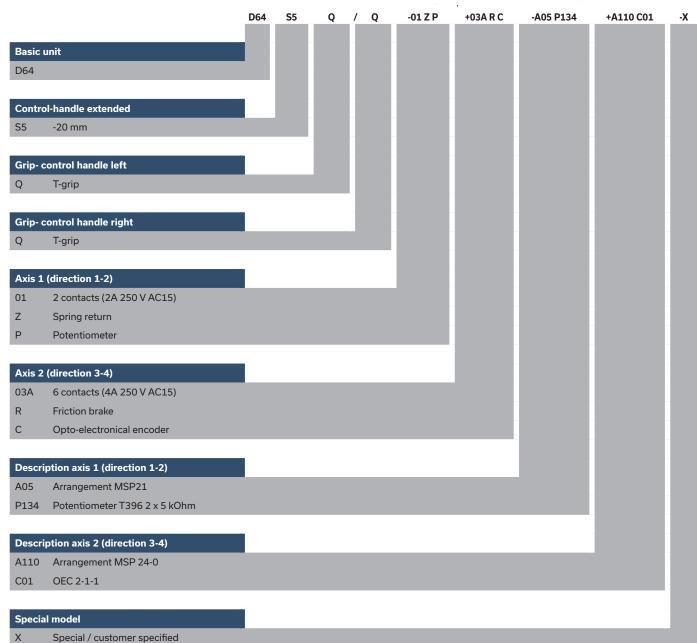
The Double-Handle Controller D64/DD64 is a robust controller used commonly in crane and hoisting applications. The modular design enables the switching device to be used universally.

### **Technical data**

Mechanical life D6410 million operating cyclesMechanical life DD6420 million operating cycles

Operation temperature  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ Degree of protection up to IP54 front

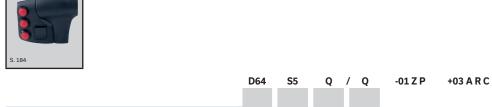






### Combination possibilities with our handles





Identification of the installation variants with switching directions:

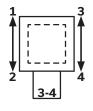
-A05

P134

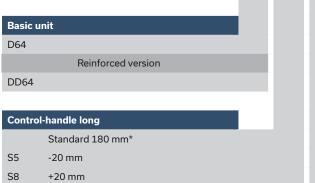
+A110

C01

-X



D64 / DD64



### **Grip- control handle left**

\*Only in combination with knob!

	Knob
М	Mechanical zero interlock
Т	Dead man
Н	Signal button
D	Push button
DV	Flush push button
Q	T-grip
QM	T-grip with mechanical zero interlock
QMH	T-grip with mechanical zero interlock + signal contact
QH	T-grip + signal button
QD	T-grip + push button side
B10	Palm Grip B10 (see page 184)

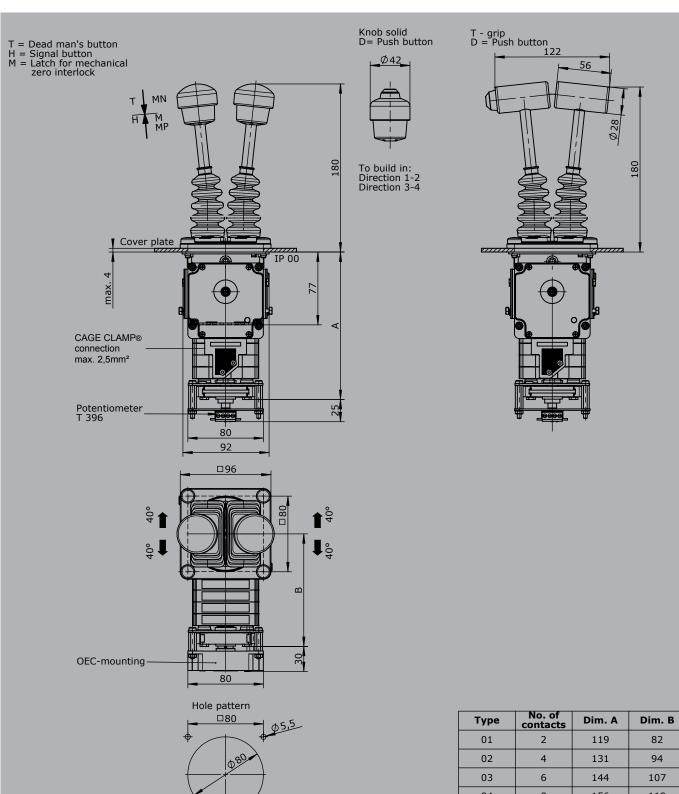
### Grip- control handle right

Knob  M Mechanical zero interlock  T Dead man  H Signal button  D Push button
T Dead man H Signal button
H Signal button
D Push button
DV Flush push button
Q T-grip
QM T-grip with mechanical zero interlock
QMH T-grip with mechanical zero interlock + signal contact
QH T-grip with signal button
QD T-grip push button side
B10 Palm Grip B10 (see page 184)



			D64	S5	Q	) /	Q	-01 Z P	+03 A R C	-A05	P134	+A110	C01	-X
Axis	s 1: di	irection 1-2												
, tall		(Standard contacts gold-plated 2A 250 V A	C15)	_			_						_	
01		2 contacts		ard conta	acts -	see	arrang	ement page	122					
02		4 contacts	e.g.											
03		6 contacts	A980		MS	00								
04		8 contacts	A05		MS2									
05		10 contacts	A0500	1		 21-0	0							
06		12 contacts	A110			24-0								
00		Silver contact (4A 250 V AC15)		ontact - a				ording custo	mer request					
Z	Snri	ing return												
R		tion brake												
(P)		unting options for potentiometer and encode	r (Gassn	nann-tvr	2001									
(F)		entiometer	i (Gessii	P131	Jes)	Т3	396 2 v	0,5 kOhm	l max. 1 mA					
F	FUL	entionietei		P131				1 kOhm	I max. 1 mA					
				P132				2 kOhm	I max. 1 mA					
				P133				5 kOhm	Imax. 1 mA					
				P134				10 kOhm	I max. 1 mA					
					ooten			on request!	I IIIax. I IIIA					
0	-													
С	Enc	oder		C En	code	r see	e page	130						
			D64	S5	Q	/	Q	-01 Z P	+03 A R C	-A05	P134	+A110	C01	-X
Δχίο	: 2: di	irection 3-4												
7 DATE		(Standard contacts gold plated 2A 250 V A	C15)	_			_			_	_			
01	П	2 contacts	,	Standa	rd co	ontac	ct - see	arrangemen	t on page 122					
02		4 contacts		e.g.				g						
03		6 contacts		A980		M	1500							
04	П	8 contacts		A05			IS21							
05		10 contacts		A0500			.S21-0	Ω						
06	Н	12 contacts		A110			1S24-0							
		Silver contacts (4A 250 V AC15)			ntact			nent accordii	ng customer red	auest				
									.9	-,				
Z		ing return												
R		tion brake												
(P)		unting options for potentiometer and encode	r (Gessn	,,	oes)	_								
Р	Pote	entiometer		P131				c 0,5 kOhm	I max. 1 mA					
				P132				k 1 kOhm	I max. 1 mA					
				P133				c 2 kOhm	I max. 1 mA					
				P134				k 5 kOhm	I max. 1 mA					
				P135				c 10 kOhm	l max. 1 mA					
				More p	otent	tiom	eters c	n request!						
С	Enc	oder		C End	coder	r see	page :	130						
Spe	cial m	nodel												
Х	Spe	cial / customer specified												
Atta	chme	ents												
Indi	cating	glabels												
	_	g labels engraved												





Туре	No. of contacts	Dim. A	Dim. B
01	2	119	82
02	4	131	94
03	6	144	107
04	8	156	119
05	10	169	132
06	12	181	144

Technical details may vary based on configuration or application! Technical data subject to change without notice!





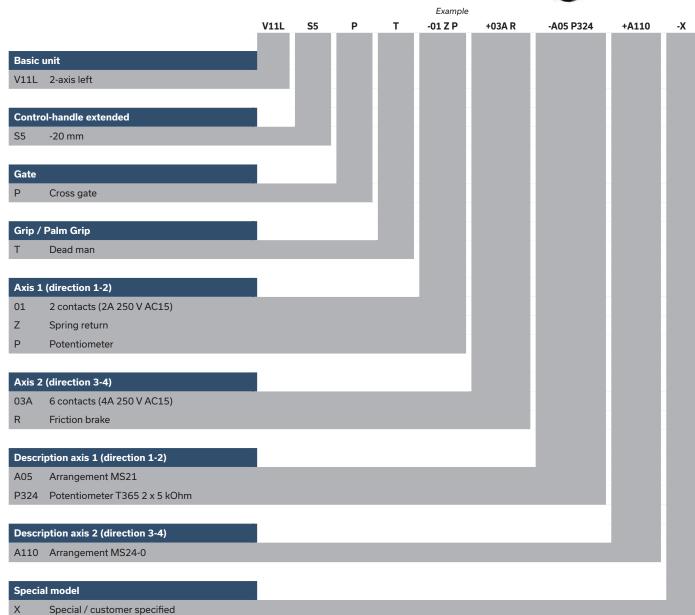
The Multi-Axis Controller V11 is a robust switching device for crane and hoisting applications. The modular design enables the switching device to be used universally.

#### **Technical data**

Mechanical life 10 million operating cycles

Operation temperature  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ Degree of protection up to IP54 front







Combination possibilities with our grips



Т

01 Z P

### Control-handle extended

V11.1R 1-axis right

Standard 120 mm\*

S5 -20 mm S8 +20 mm

\*Only available in combination with a handle!

### Gate

P Cross gate
P X Special gate

### Grip / Palm Grip

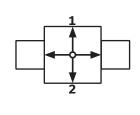
MN Mechanical zero interlock (push down)

T Dead manH Signal buttonD Push buttonDV Flush push button

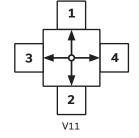
B... Palm Grip B... (see page Palm Grip 154)

### Identification of the installation variants with switching directions:

A05 P324



03A R P



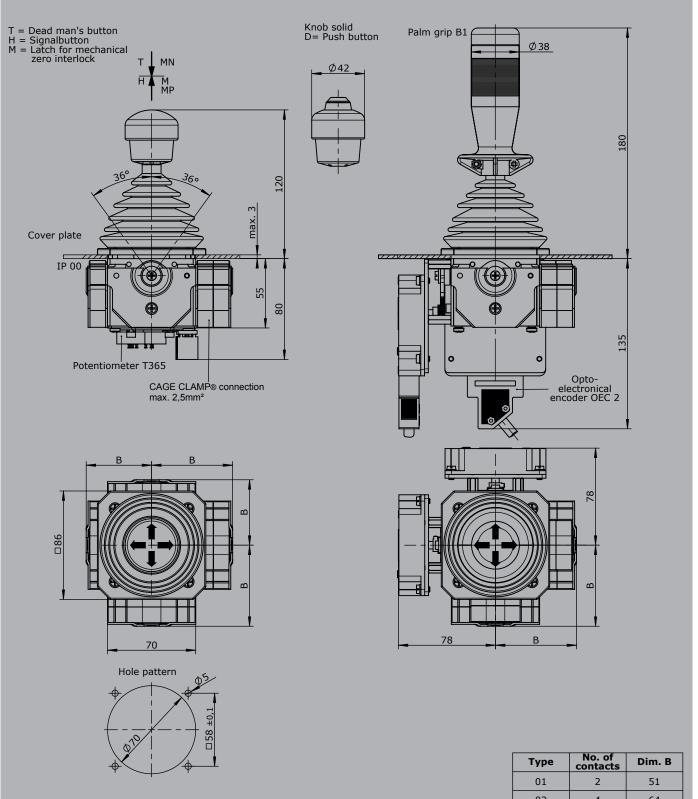
A110 P325 -

V11.1



			V11L	S5	P	т	٠,	01 Z P	+	03A R P -	A05 P324	- +	A110 P325	- X
Axis	s 1: d	irection 1-2 left / direction 5-6 righ	nt								-			
		(Standard contacts gold-plated 2A	250 V AC	(15)									_	
01		2 contacts		Stand	ard co	ntact -	arrang	gement s	ee pa	age 122				
02		4 contacts		e.g.										
03		6 contacts		A980			MS0	0						
				A05			MS2	1						
				A0500	0		MS2	1-00						
				A110			MS2	4-0						
				(Max.	4 step	s per s	switchi	na direct	ion p	oossible!)				
	<b>A</b> =	Silver contacts (4A 250 V AC15)	-		·	·			·	customer reque	st			
	_	, ,								·				
Z	Spr	ing return												
R	Fric	tion brake												
(P)	Pos	sibility of mounting potentiometer a	nd encod	er (Ges	smanı	n-types	s)							
Р	Pot	entiometer		P324		T365	52 x 5	kOhm		I max. 1 mA				
				P325		T365	5 2 x 10	) kOhm		I max. 1 mA				
				More	potent	tiomete	ers on	request!						
С	Enc	oder		C Er	acadar	.coo.p.	age 13	0						
C	EIIC	oder		C EI	icodei	see pa	age 13	U						
					_	_								
			V11L	S5	Р	Т	-	01 Z P	+	03A R P -	A05 P324	+	A110 P325	- X
Axis	s 2: d	irection 3-4 left / direction 7-8 righ		C4.F.\		_	_		(r	not applied for V	(11.1)			_
01		(Standard contacts gold-plated 2A	( 250 V A							122				
01		2 contacts (2A 250V AC15)			ard co	ntact -	arrang	gement s	ee pa	age 122				
02		4 contacts (2A 250V AC15)		z.B.			1400	_						
03	ш	6 contacts (2A 250V AC15)		A980			MS0							
				A05	_		MS2							
				A0500	)		MS2							
				A110			MS2							
			_							oossible!)				
	A=	Silver contacts (4A 250 V AC15)		A99 c	ontact	: - arrar	ngeme	nt accord	ding (	customer reque	st			
_														
Z		ing return												
R		tion brake												
(P)		sibility of mounting potentiometer a	nd encod		smanı									
Р	Pot	entiometer		P324			52x5			I max. 1 mA				
				P325				) kOhm		l max. 1 mA				
				More	potent	iomete	ers on l	request!						
С	Enc	oder		C Er	ncoder	see pa	age 13	0						
			V11L	S5	P	Т	-	01 Z P	+	03A R P -	A05 P324	+	A110 P325	- X
														_
Spe	cial n	nodel												
X	Spe	cial / customer specified												
Atta	achm	ents												
_		glabels												
		g labels with engraving												
mul	catility	grabers with engraving												





Type	No. of contacts	Dim. B
01	2	51
02	4	64
03	6	76

Technical details may vary based on configuration or application! Technical data subject to change without notice!





The V14 is a robust switching device for remote control and electro-hydraulic applications. Due to its modular design, this control unit can be used universally. The integrated sensor system has signal and potentiometer tracks in conductive plastic technology. Switching contacts are also available as an option.

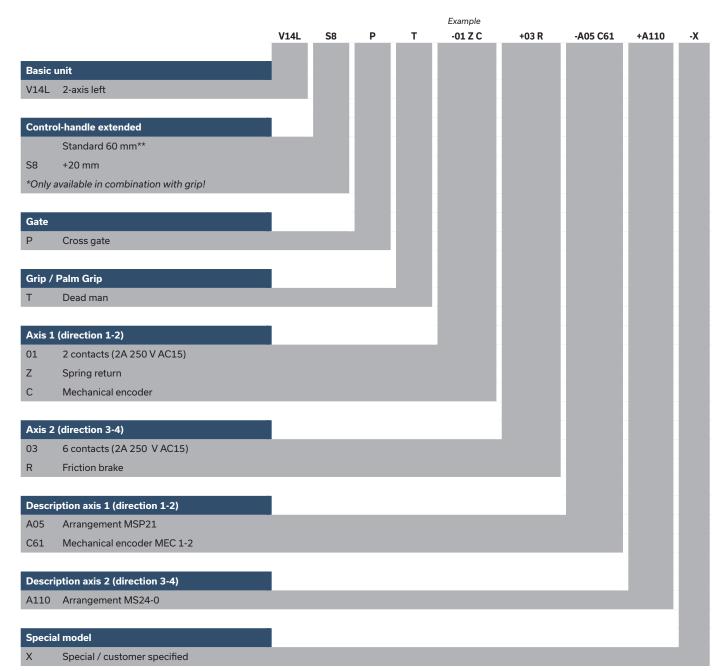
#### **Technical data**

Mechanical life V14 6 million operating cycles

Operation temperature -40°C to +85°C

Degree of protection up to IP65











V14L S8 P T - 01 Z C + 03 R - A05 C61 + A110 - X
Basic unit

### V14.1L 1-axis left V14.1R 1-axis righ

V14.1R 1-axis right V14L 2-axis left V14R 2-axis right

#### Control-handle extended

Standard 60 mm\*

S8 +20 mm

\*Only available in combination with a handle!

### Gate

P Cross gate
P X Special gate

#### Grip / Palm Grip

M Mechanical zero interlock

MH Mechanical zero interlock + signal contact

T Dead man

Knob 25 mm (standard)

H Signal button

GK1 Knob 42 mm

GK1M Mechanical zero interlock

Signal button

GK1MN Mechanical zero interlock (push down)

GK1T Dead man

GK1H

GK1MH Mechanical zero interlock + signal contact

GK1D Push button

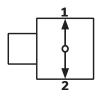
GK1DV Flush push button

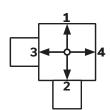
GS9 Hall-twist grip with spring return

GS9-D Hall-twist grip with spring return and push button on top

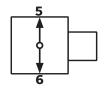
B... Palm Grip B... (see page Palm Grip page 154)

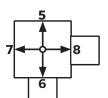
Identification of the installation variants with switching directions:





V14.1L





V14L

V14.1R

V14R

\*Attention! The Multi-Axis Controller V14 is not suitable for large Palm Grips (B3, B7/B8, B9...)

V14L S8 01 Z C 03 R A05 C61 A110 Axis 1: direction 1-2 left / direction 5-6 right (Standard contacts gold-plated 2A 250V AC15) 2 contacts Standard contact - arrangement see page 122 01 02 4 contacts e.g. 03 6 contacts A05 MS21 A0500 MS21-00 A110 MS24-0

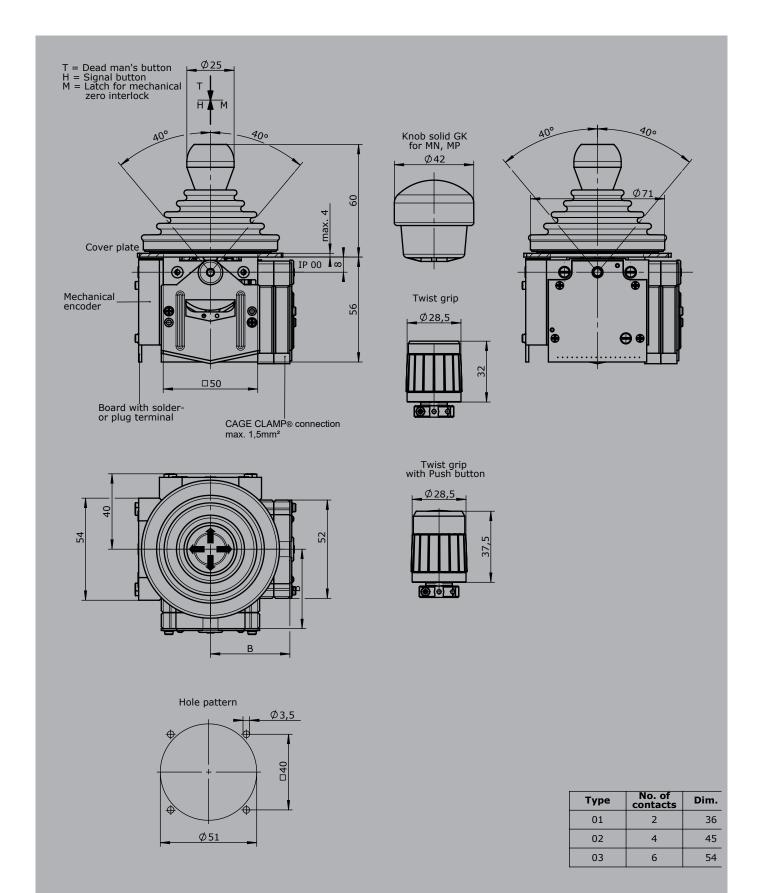
A99 contact - arrangement according customer request



V14L **S8** - 01 Z C + 03 R A05 C61 A110 Spring return (included in basic unit!) R Friction brake С MEC 1-2 Mechanical encoder C61 EA/02-10 I max. 1 mA Potentiometer track 2 x 10 kOhm Arrangement MS26-0 Direction tack C62 MEC 1-7 EA/10-10 I max. 1 mA Potentiometer track 2 x 5 kOhm Direction track Arrangement MS26-0-1 C63 MEC 1-6 EA/09-10 6 Bit Gray Code C64 MEC 1-6-5 ER/36-10 Us=18-30 V Current output 20...4...20 mA C65 MEC 1-6-8 ER/36-12 Us=18-30 V Current output 20...0...20 mA C67 MEC 1-6-9 ER/36-11 Us=18-30 V Voltage output 10...0...10 V Hall-Potentiometer E14811 0,5...2,5...4,5 V / 4,5...2,5...0,5 V A05 C61 A110 **V14L S8** 01Z C 03 R X Axis 2: direction 3-4 left / direction 7-8 right (not applied for V14.1L and V14.1R) See description axis 1! Special model

X Special / customer specified





_	4
Ċ	V
C	0
C	V
_	4
Ċ	0
_	-
Ċ	٥
Ξ	
-	1
C	٧
C	2
r	٧

## **Single-Axis Controller**





The S14 is a compact single-axis joystick designed for remote control and electrohydraulic applications. Due to its modular design, this control unit can be used universally. The integrated sensor system has signal and potentiometer tracks in conductive plastic technology. Optionaly switch contacts are also available.

#### **Technical data**

GK1M

Mechanical zero interlock

Mechanical life S14 6 million operating cycles

Operating temperature -40°C to +85°C up to IP65 Degree of protection



S14L S8 т -01ZC -A05 C61 -X Basic unit S14L Control-handle extended Standard 60 mm\* S8 +20 mm \*Only possible in combination with handle! Grip / Palm Grip Dead man Axis 1 (direction 1-2) 2 contacts (2A 250 V AC15) Ζ Spring return С Mechanical encoder Description axis 1 (direction 1-2) A05 Arrangement MSP21 C61 Mechanical encoder MEC 1-2 Special model Special / customer specified

S14L S8 -01ZC -A05 C61 Т Basic unit S14L 1-axis left S14R 1-axis right Control-handle extended Standard 60 mm\* Identification of the installation S8 +20 mm variants with switching directions: \*Only possible in combination with handle! Grip / Palm Grip Knob (standard) Μ Mechanical zero interlock МН Mechanical zero interlock + signal contact Т Dead man Н Signal button GK1 Knob 42 mm

S14

Technical details may vary based on configuration or application! Technical data subject to change without notice!

-X

# **Single-Axis Controller** S14



		S14L	<b>S8</b>	т	-01ZC	-A05	C61	-X
GK1MN	Mechanical zero interlock (push down)							
GK1T	Dead man							
GK1H GK1MH	Signal button  Mechanical zero interlock + signal contact							
GK1D	Push button							
GK1DV	Flush push button							
GS9	Hall-twist grip with spring return							
GS9-D	Hall-twist grip with spring return and push button on top							
В	Palm Grip B (on request!)							
		S14L	<b>S</b> 8	т	-01ZC	-A05	C61	-X
							_	Щ.
Axis 1: d	lirection 1-2 left / direction 5-6 right						_	_
01	(Standard contacts gold-plated 2A 250V AC15)  2 contacts	Ctandar	d contact - a	rrangomon	t coo paga '	122		
02	4 contacts	z.B.	u contact - a	mangemen	t see page .	122		
03	6 contacts	A05		MS21				
		A0500		MS21-00	)			
		A110		MS24-0				
		A99 cor	ntact - arrang	gement acco	ording custo	omer request		
Z	Spring return (included in basic unit!)							
R	Friction brake	054	14504.0					_
С	Mechanical encoder	C61	MEC 1-2 EA/02-10			I max. 1 mA		
			Potentiom	eter track		2 x 10 kOhm		
			Direction t	rack		Arrangement M	S26-0	
		C62	MEC 1-7					
			EA/10-10			I max. 1 mA		
			Potentiom			2 x 5 kOhm		
		060	Direction t	rack		Arrangement M	S26-0-1	
		C63	MEC 1-6 EA/09-10					
			6 Bit Gray	Code				
		C64	MEC 1-6-5					
			ER/36-10			Us= 18-30 V		
			Current ou	tput 204.	20 mA			
		C65	MEC 1-6-8					
			ER/ 36-10			Us= 18-30 V		
		C67	MEC 1-6-9	itput 200.	20 MA			
		207	ER/36-11			Us= 18-30 V		
				tput 100.	10V			
		More po	otentiometer	s on reques	it!			
Н	Hall-Potentiometer	E14811				0,52,55,4 V	/ 4,52,50,5	V
		S14L	S8	т	-01ZC	-A05	C61	-X
			50	•		, 100	301	^

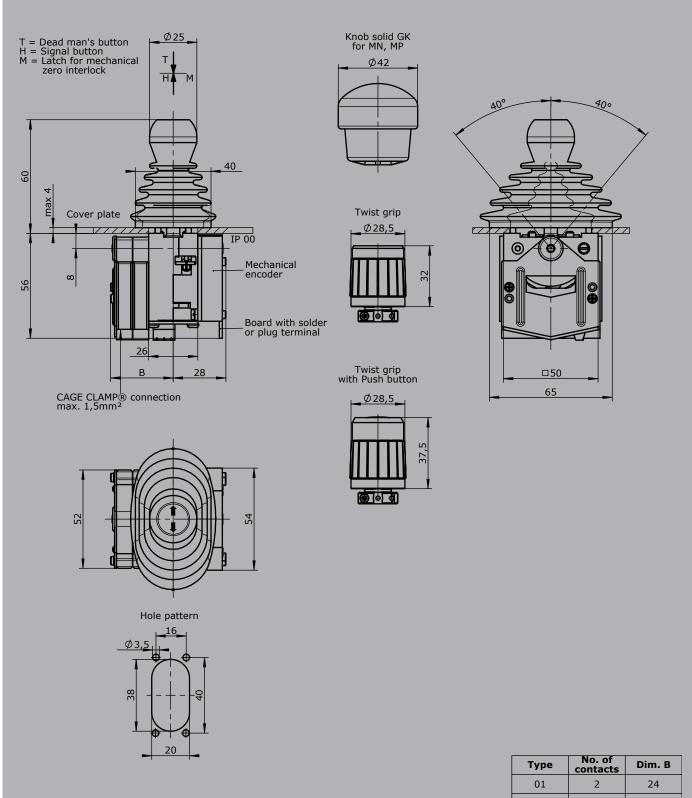
V2021/1 01.01.2021

Special model

Special / customer specified

## **Single-Axis Controller S14**





. 33
42

## **Single-Axis Controller** S2 / SS2 / S21





The Single-Axis Controller S2 / SS2 / S21 is a robust switching device for remote controlled and electrohydraulic applications. The modular design of the switching device is universally applicable.

### Technical data

Mechanical life S2 / S216 million operating cyclesMechanical life SS210 million operating cycles

Operating temperature -40°C to +85°C

Degree of protection up to IP54



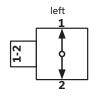
∟xampie S2L S5 Т - 02 Z P - A050 P134 - X Basic unit S2L left Control-handle extended S5 -20 mm Grip / Palm Grip Dead man Axis 1 (direction 1-2) 3 contacts (2A 250 V AC15) 02 Ζ Spring return Р Potentiometer Description axis 1 (direction 1-2) A050 Arrangement MSP21-0 P134 Potentiometer T396 2 x 5 kOhm Special model Special / customer specified

S<sub>2</sub>L S5 **Basic unit** S2L Single-Axis Controller left Single-Axis Controller right S2R S21L Single-Axis Controller left with flange 96 x 96 mm Single-Axis Controller right with flange 96 x 96 mm S21R Reinforced version Single-Axis Controller left SS2L SS2R Single-Axis Controller right SS21L Single-Axis Controller left with flange 96 x 96 mm SS21R Single-Axis Controller right with flange 96 x 96 mm Control-handle extended Standard S5 -20 mm S8 +20 mm

Identification of the installation variants with switching directions:

- A050 P134

- 02 Z P





- X

# Single-Axis Controller S2/SS2/S21



- X



Grip / Palm Grip Knob (standard) Mechanical zero interlock MN Mechanical zero interlock (push down) Dead man Т MT Mechanical zero interlock + dead man Н Signal button MH Mechanical zero interlock + signal button D Push button MD Mechanical zero interlock + push button DV Flush push button MDV Mechanical zero interlock + flush push button В... Palm Grip B... (see page Palm Grip 154)

S2L S5 - 02 Z P - A050 P134 - X Т Axis 1: direction 1-2 left / direction 5-6 right 02 3 contacts Standard contact - arrangement see page 122

03 5 contacts 04 7 contacts A98 MS0 05 A05 MS21 9 contacts A0500 MS21-00 A110 MS24-0 A99 contact - arrangement according customer request

R Friction brake (P)

Possibility of mounting potentiometer and encoder (Gessmann-types) Potentiometer P131 T396 2 x 0,5 kOhm I max. 1 mA

> P132 T396 2 x 1 kOhm I max. 1 mA P133 T396 2 x 2 kOhm I max. 1 mA P134 T396 2 x 5 kOhm I max. 1 mA P135 T396 2 x 10 kOhm I max. 1 mA

More potentiometers on request!

Encoder C... Encoder see page 157

> - A050 P134 S2L - 02 Z P **S5** Т - X

### Special model

Ζ

Ρ

С

Spring return

- Special / customer specified
- Microswitch (MZT 1) positively driven NC contact

### **Attachments**

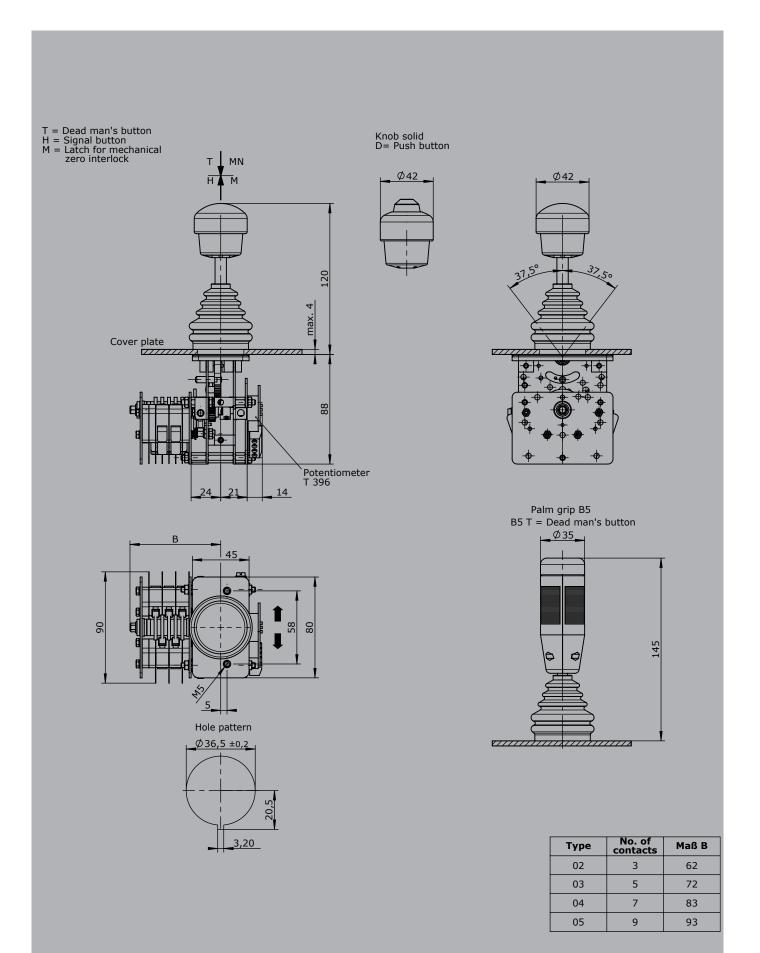
Indicating labels

Indicating labels with engraving

# Single-Axis Controller S2/SS2/S21



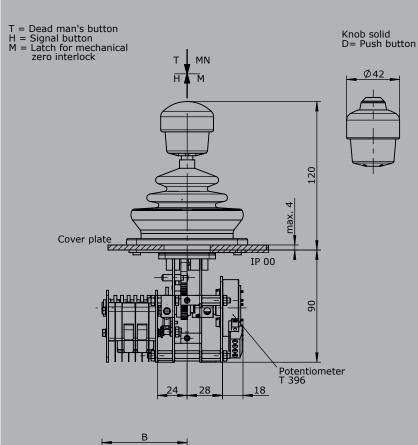


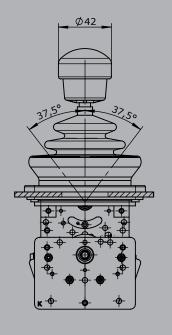


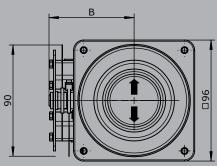
Technical details may vary based on configuration or application! Technical data subject to change without notice!

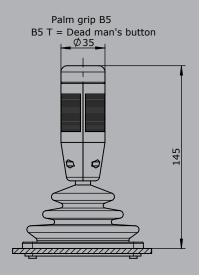
# Single-Axis Controller S2/SS2/S21

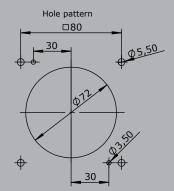












Туре	No. of contacts	Maß B				
02	3	62				
03	5	72				
04	7	83				
05	9	93				

# **Single-Axis Controller** S22 / SS22





The Single-Axis Controller S22 / SS22 is a robust switching device for remote controlled and electrohydraulic applications. The modular design of the switching device is universally applicable.

#### **Technical data**

Mechanical life S226 million operating cyclesMechanical life SS2210 million operating cycles

Operating temperature -40°C to +85°C

Degree of protection up to IP54



Example S22L S5 Т - 3 Z P - A050 P134 - X Basic unit S22L left Control-handle extended -20 mm Grip / Palm Grip Dead man Axis 1 (direction 1-2) 3 contacts (2A 250 V AC15) 3 Ζ Spring return Ρ Potentiometer Description axis 1 (direction 1-2) Arrangement MSP21-0 A050 P134 Potentiometer T396 2 x 5 kOhm Special model Χ Special / customer specified

		S22L	S5	т	- 3 Z P	- A050 P134
Basic ur	nit					
S22L	Single-Axis Controller left			lde	entification of the	e installation variants
S22R	Single-Axis Controller right				with switch	ing directions:
	Reinforced version			S2	22L / SS22L	S22R / SS22R
SS22L	Single-Axis Controller left			_	1	5
SS22R	Single-Axis Controller right				<b>†</b>	<b> </b>
		_		1-2	<b>Ŷ</b>	
Control-	-handle extended				2	<u> </u>
	Standard				2	•
S5	-20 mm					
S8	+20 mm					

Technical details may vary based on configuration or application! Technical data subject to change without notice!

- X

5-6

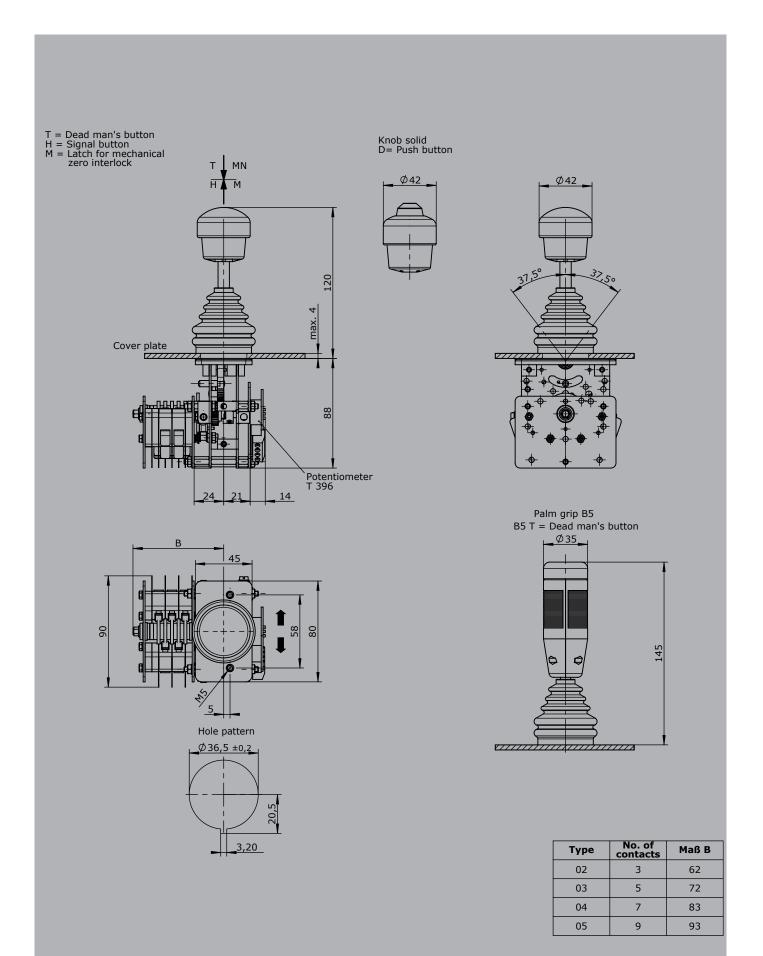
### **Single-Axis Controller** S22 / SS22



Т - 3 Z P S22L S5 - A050 P134 - X Grip / Palm Grip Knob (standard) Μ Mechanical zero interlock MN Mechanical zero interlock (push down) Т Dead man Mechanical zero interlock + dead man MT Н Signal button МН Mechanical zero interlock + signal button D Push button MD Mechanical zero interlock + push button DV Flush push button MDV Mechanical zero interlock + flush push button В... Palm Grip B... (on request!) Т S22L S5 - 3 Z P - A050 P134 - X Axis 1: direction 1-2 left / direction 5-6 right 1 contact Standard contact - arrangement see page 122 2 contacts z.B. 3 3 contacts A98 MS0 MS21 4 contacts A05 A0500 MS21-00 A99 contact - arrangement according customer request Z Spring return R Friction brake (P) Possibility of mounting potentiometer and encoder (Gessmann-types) P131 T396 2 x 0,5 kOhm Potentiometer I max. 1 mA P132 T396 2 x 1 kOhm I max. 1 mA P133 T396 2 x 2 kOhm I max. 1 mA I max. 1 mA P134 T396 2 x 5 kOhm P135 T396 2 x 10 kOhm I max. 1 mA More potentiometers on request! Codierer C...Encoder see page 130 Т S22L S5 - 3 Z P - A050 P134 - X Special model Χ Special / customer specified Switching run 2-0-2 Attachments Indicating labels Indicating labels with engraving

# **Single-Axis Controller** S22 / SS22





Technical details may vary based on configuration or application! Technical data subject to change without notice!







The V23 is a switching device for remote control applications. The integrated sensor system has signal and potentiometer tracks in conductive plastic technology. Detent points are optionally selectable. Due to its small dimensions it can be optimally integrated into small remote control housings.

#### **Technical data**

Mechanical life V23 3 million operating cycles

Operation temperature -40°C to +85°C

Degree of protection IP67 front



		V23A	Example -P	e -C80	+C80	-X
Basic un	it					
V23.1A	1-axis with spring return, installation from below					
V23A	2-axis with spring return, installation from below					
V23.1B	1-axis with spring return, installation from top					
V23B	2-axis with spring return, installation from top					
		- 1				
Gate		_				
Р	Cross gate					
PX	Special gate					
Axis 1: d	lirection 1-2					
C80	Mechanical encoder					
	MEC 3-1					
	EA/26-10	l max. 1 mA				
	Potentiometer resistance	2x5 kOhm				
	Contact arrangement	Arrangement MS24	1			
	with 12-pol. JST-connector					
Axis 2: d	lirection 3-4 (not applied for V23.1)					
See desc	cription axis 1!					
		_				
Special r	model					

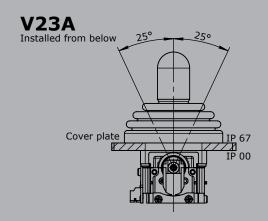
Attachments	
Mating connector JST 12-polig (included in delivery!)	5300000263
Mating connector JST 12-pole with single wire 500 mm long	5300000264

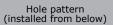
Special / customer specified

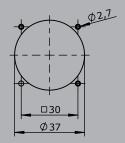
# **Multi-Axis Controller**



27,8



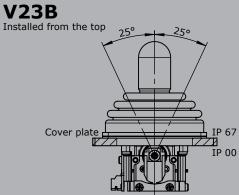




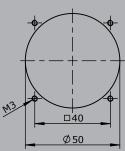
Ø52

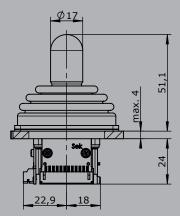
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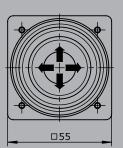
Ø17



Hole pattern (installed from the top)







### **Multi-Axis Controller**



The V20 is a rugged switching device for remote control. The integrated sensor technology has signal and potentiometer tracks in conductive plastic technology. Detent points can be integrated as an option.

#### **Technical data**

Mechanical life V20 3 million operating cycles

Operation temperature -40°C to +85°C

Degree of protection IP65 (optional IP67)



						the state of	Thursday.	
				Example				
		V20	.p	D	-C71	+C71	-В	-X
Basic un	iit							
V20.1	1-axis with spring return							
V20	2-axis with spring return							
V20.1A	1-axis with spring return, IP67 front							
V20A	2-axis with spring return, IP67 front							
Gate								
р	Cross gate							
PX	Special gate							
Grip								
	Knob (standard)							
D	Push button							
GS9	Hall-twist grip with spring return							
GS9-D	Hall-twist grip with spring return and push bu	utton on top						
Axis 1: d	lirection 1-2							
C70	Mechanical encoder							
	MEC 2-1							
	EA/15-10	l max. 1 mA						
	Potentiometer track	2 x 5 kOhm						
	Direction track	Arrangemen	nt MS224-0					
C71	Mechanical encoder							
	MEC 2-2							
	EA/11-10	l max. 1 mA						
	Potentiometer track	2 x 5 kOhm						
	Direction track	Arrangemen	nt MS24-0					
C72	Mechanical encoder							
	MEC 2-5							
	EA/21-10	l max. 1 mA						
	Potentiometer track	2 x 5 kOhm						
	B1 11 1 1							

Arrangement MS25-0

Technical details may vary based on configuration or application! Technical data subject to change without notice!

Direction track

Cover housing KBQ 905 (IP65)

Special / customer specified

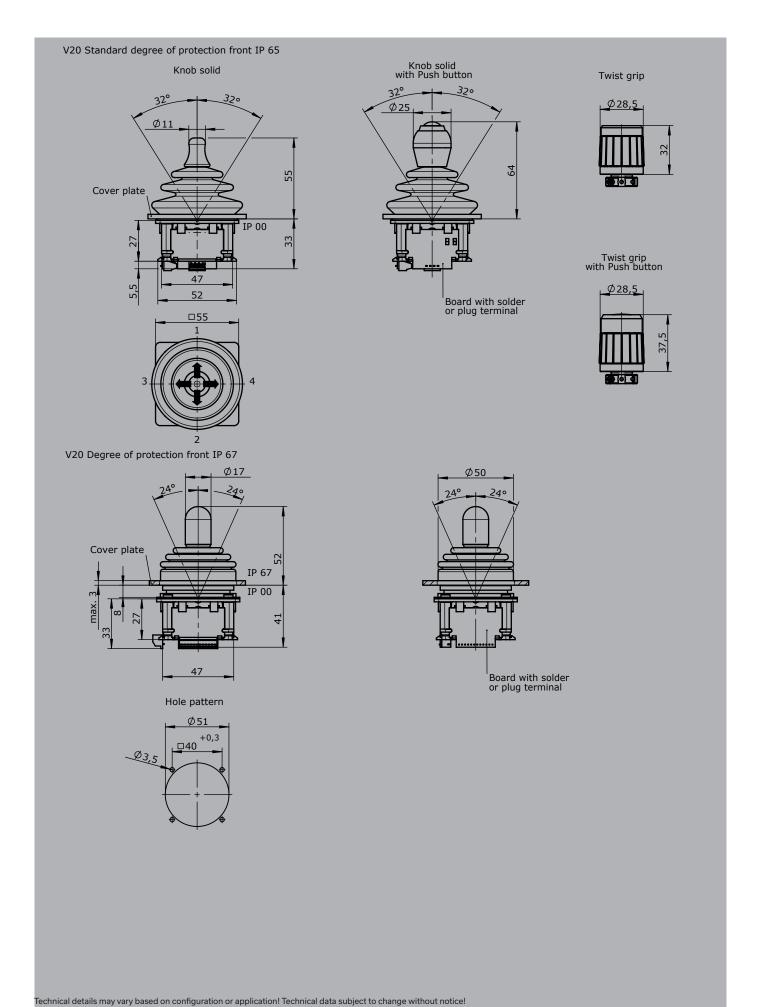
Axis 2: direction 3-4
See description axis 1!

Cover housing

Special model

### **Multi-Axis Controller**





### **Single-Axis Controller**





The S1 is a one-axis joystick for remote control and eletro-hydraulic applications. The modular design of the switching device is universally applicable.

#### **Technical data**

Mechanical life S1 6 million operating cycles

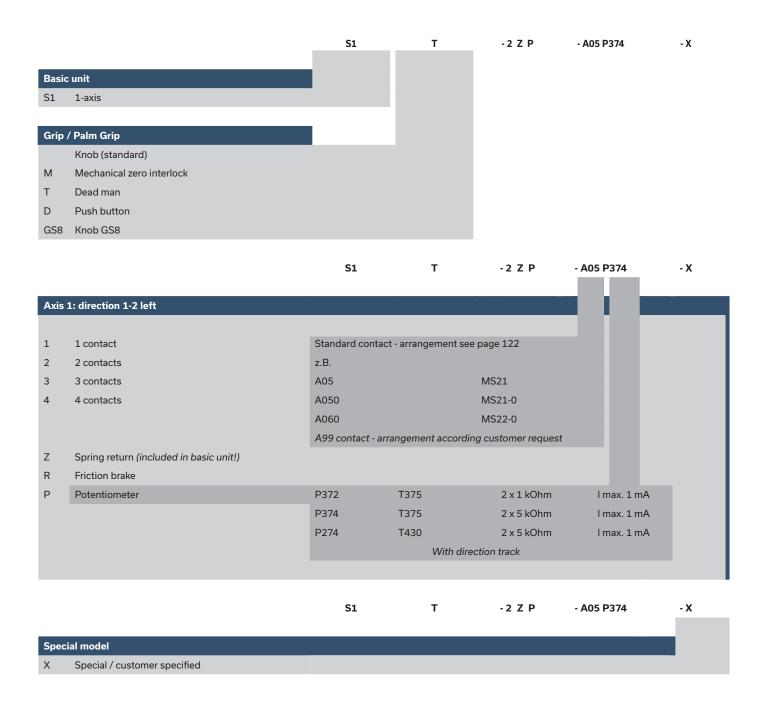
Operating temperature  $-40^{\circ}\text{C to } +85^{\circ}\text{C}$ Degree of protection up to IP65



Example S1 Т - 2 Z P - A05 P374 - X Basic unit S1 1-axis Grip / Palm Grip Dead man Axis 1 (direction 1-2) 2 contacts (1,5A 24 V DC13) Ζ Spring return Ρ Potentiometer Description axis 1 (direction 1-2) A05 Arrangement MSP21 P374 Potentiometer T 375 2 x 5 kOhm Special model Special / customer specified

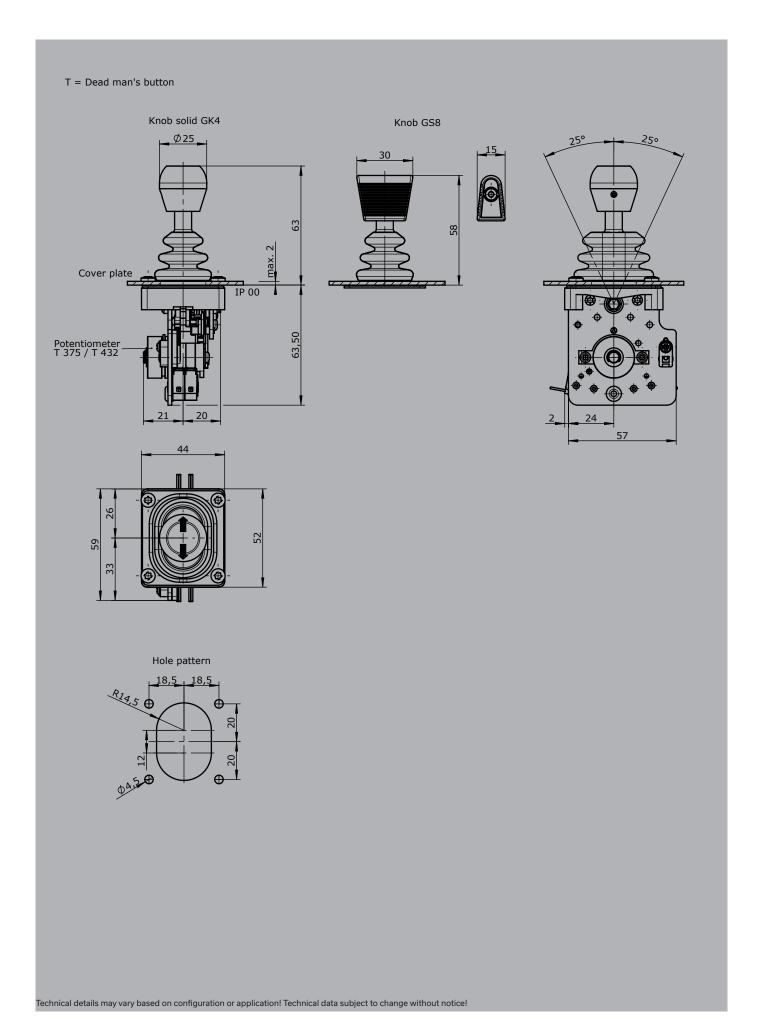
### **Single-Axis Controller**





## **Single-Axis Controller**





## **Control-Switch** N6





The Control-Switch N6 is a rugged switching device for hoisting applications. The modular design enables the switching device to be used universally. The N6 is resistant to oil, maritime conditions e.g. offshore /vessels, UV radiation typically from the sun.

#### **Technical data**

Mechanical life N6 10 million operating cycles

Operating temperature -40°C to +85°C

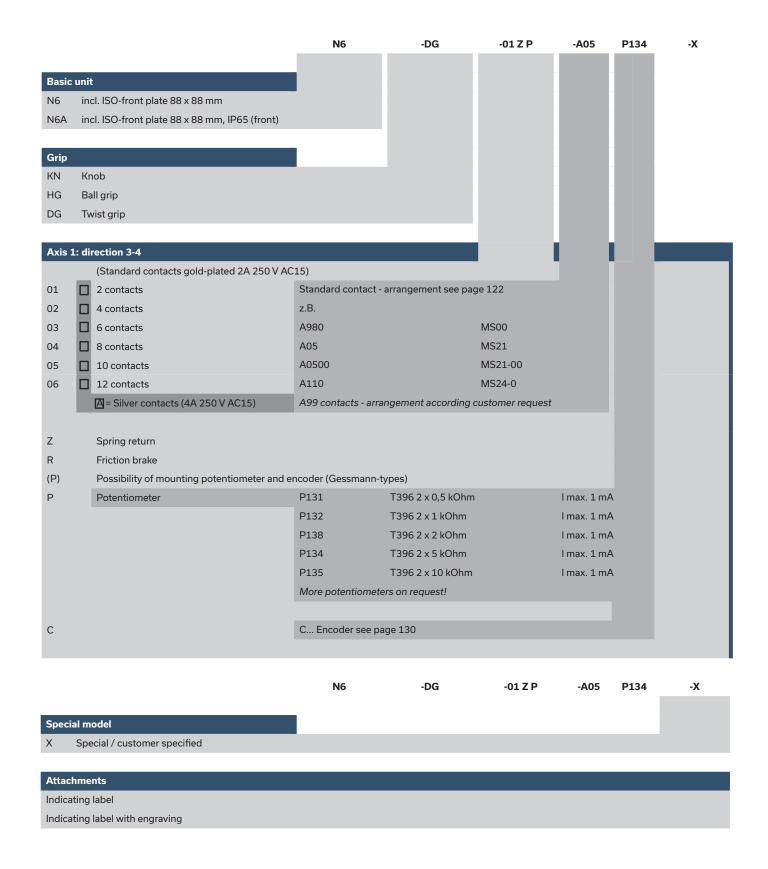
Degree of protection up to IP54



				Example		
		N6	-DG	-01 Z P	-A05 P134	-X
Basic	unit					
N6	incl. ISO-front plate 88 x 88 mm					
Grip						
DG	Twist grip					
Axis 1	(direction 2-4)					
01	2 contacts (2A 250 V AC15)					
Z	Spring return					
Р	Potentiometer					
Descr	iption axis 1 (direction 3-4)					
A05	Arrangement MSP21					
P134	Potentiometer T396 2 x 5 kOhm					
Speci	al model					
X	Special / customer specified					

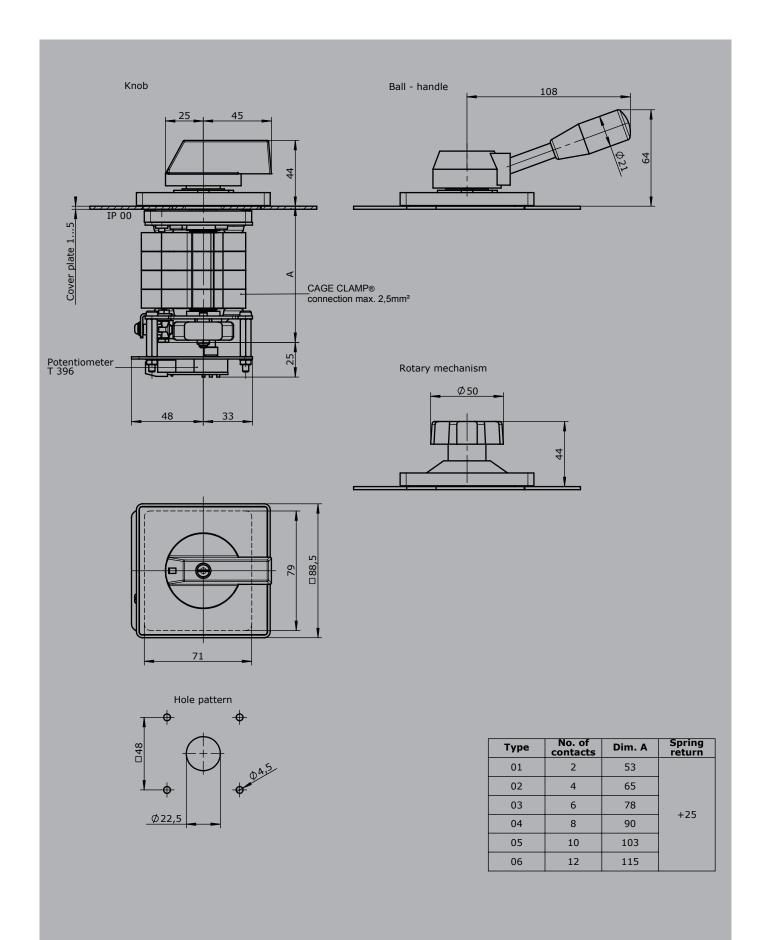
### Control-Switch





## **Control-Switch** N6





## **Control-Switch**





The Control-Switch N9 is a rugged switching device for electrohydraulic and hoisting applications. The modular design enables the switching device to be used universally.

#### **Technical data**

Mechanical life N9 10 million operating cycles

Operating temperature -40°C to +85°C

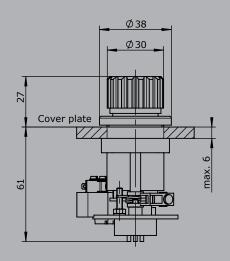
Degree of protection IP54

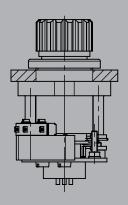


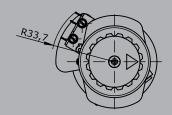
		N9	Example -2 R P	-A05	P134	-)
		NS	-2 R P	-A05	P134	-,
Raci	ic unit	_				
N9	Control switch with twist grip	_				
143	Control Switch with twist grip					
Axis	s 1: direction 3-4					
1	1 contact	Standard cor	ntact - arrangement see pag	ge 122		
2	2 contacts	z.B.				
		A98	MS0			
		A05	MS21			
		A99 contacts	s - arrangement according c	customer request		
R	Friction brake (included in basic unit)					
(P)	Possibility of mounting potentiometer and encode	r (Gessmann-types)				
Р	Potentiometer	P131	T396 2 x 0,5 kOhm	l max. 1 mA		
		P132	T396 2 x 1 kOhm	l max. 1 mA		
		P133	T396 2 x 2 kOhm	l max. 1 mA		
		P134	T396 2 x 5 kOhm	I max. 1 mA		
		P135	T396 2 x 10 kOhm	I max. 1 mA		
		Mara notanti	ometers on request!			
		More potenti				
		Wore potenti				
Н	Hall-Potentiometer	E14811	0,52,54,5 V / 4,52,	50,5 V		
Н	Hall-Potentiometer			50,5 V		
				50,5 V		
	Hall-Potentiometer			50,5 V		

# Control-Switch N9









Hole pattern



## Steering Column Switch



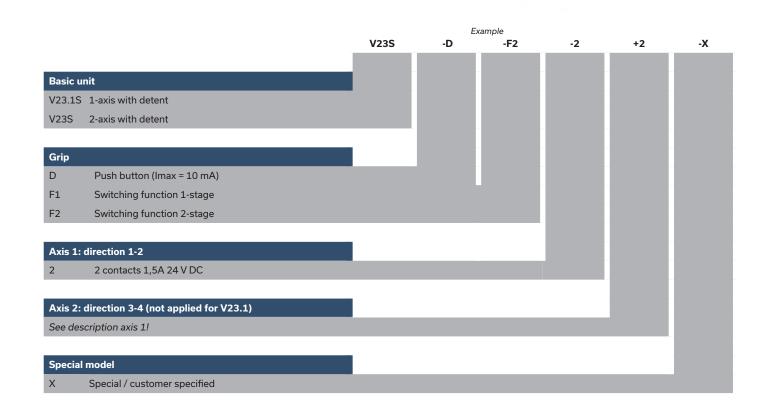
The Steering Column Switch V23 is designed for mounting on a steering column.

#### **Technical data**

Mechanical life V23S 1 million operating cycles

Operation temperature -40°C to +85°C

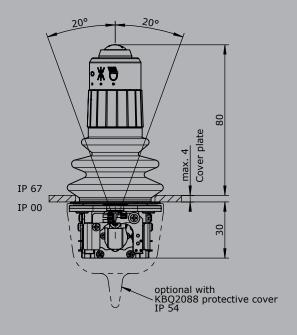


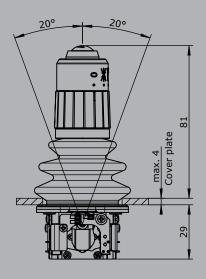


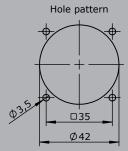
# **Steering Column Switch** V23



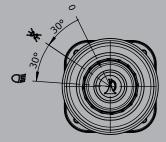
## Steering column switch mounting from below

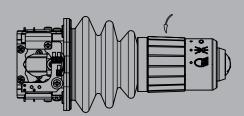












### **Standard Plug Connector**



	Mole	Micro-Fit 3.0 - Suited for cond	uctor cr	ross-section 0.1 til 0.75 mm <sup>2</sup>								
S004	Male housing 10-pole		S012	Female housing 10-pole								
0000			0011									
S006	Male housing 14-pole		S014	Female housing 14-pole								
S007	Male housing 18-pole		S015	Female housing 18-pole								
	De	utsch DTM - Suited for conduct	or cross	s-section 0,25 til 1,5 mm <sup>2</sup>								
S017	Male housing 4-pole		S022	Female housing 4-pole								
S018	Male housing 6-pole		S023	Female housing 6-pole								
S019	Male housing 8-pole		S024	Female housing 8-pole								
S021	Male housing 12-pole		S026	Female housing 12-pole								
	D	eutsch DT - Suited for conducto	r cross-	-section 0,25 til 2,0 mm²								
S027	Male housing 4-pole		S032	Female housing 4-pole								
S028	Male housing 6-pole		S033	Female housing 6-pole								
S029	Male housing 8-pole		S034	Female housing 8-pole								
S031	Male housing 12-pole		S036	Female housing 12-pole								
	AMP CPC - Suited for conductor cross-section 0,12 til 1,5 mm <sup>2</sup>											
S037	Male housing CPC 13 9-pole		S040	Female housing CPC 13 9-pole								
S038	Male housing CPC 17 14-pole		S041	Female housing CPC 17 14-pole								
S039	Male housing CPC 23 37-pole		S042	Female housing CPC 23 37-pole								
	AMP Mini-Univer	sal MATE-N-LOK (sealed) - Suit	ed for co	onductor cross-section 0,12 til 1,5 mm <sup>2</sup>								
S043 🗖	Cap housing 4-pole		S048	plug housing 4-pole								
S044 🗖	Cap housing 6-pole		S049	plug housing 6-pole								
S045 🗖	Cap housing 8-pole	NAME OF THE PARTY	S050	plug housing 8-pole								
S046 🗖	Cap housing 10-pole		S051	plug housing 10-pole								
	P pin	S socket										
		Phoenix - Suited for conduct	or cross	s-section til 1,5 mm²								
S053	Male housing IC 2,5 (STGF) 8-pole with screw terminal		S057	Female housing MSTB 2,5 (STF) 8-pole with screw terminal								
	Male housing IC 2,5 (STGF)	Maria de la companya	S058	Female housing MSTB 2,5 (STF) 12-pole with screw terminal								
S054	12-pole with screw terminal			12-pole with screw terminal								
S054 S055		n the desired polymery to the n	S059	Female housing MSTB 2,5 (STF) 14-pole with screw terminal								

# **Schematic description** of the protection class





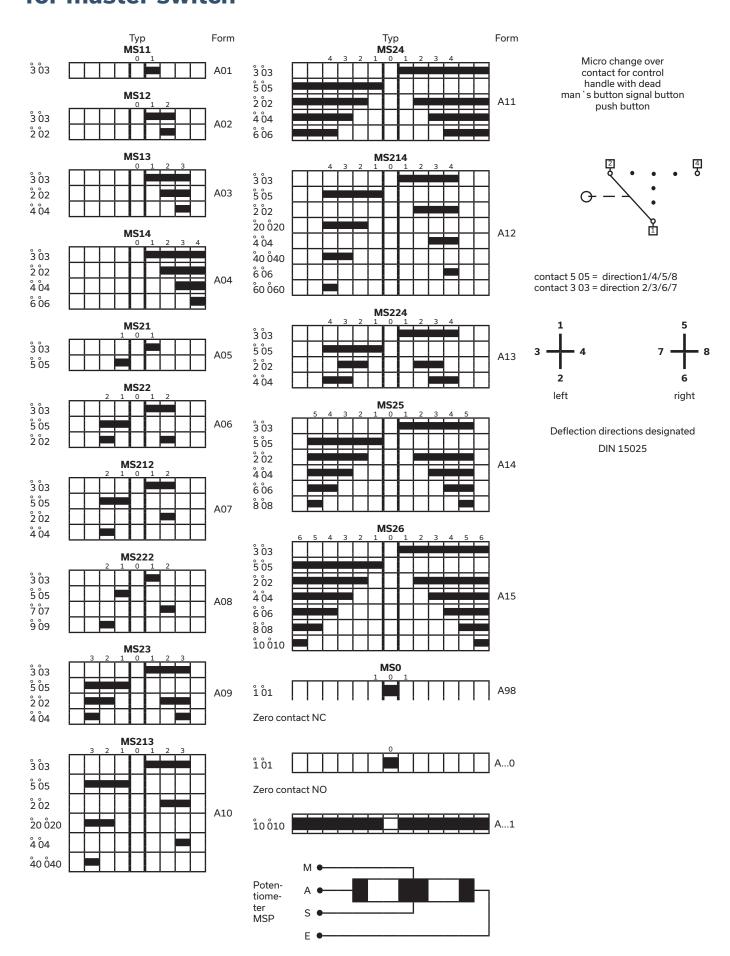
### Degree of protection

B10 Joystick-main circuit board grouted (IP67)

B11 Joystick-main circuit board grouted (IP67) and grip function sealed, grip with drain hole

# **Standard Contact-Arrangement for master switch**





### **Technical data**



### Utilization categories for control switches to IEC/EN 60947-5-1

Type of current	Utilization category	Typical examples of application	Norm	al condit	ions of us	se		
		I= current made, Ic= current broken	Make			Breal		
		le= rated operational current, U= voltage before make Ue= rated operational voltage Ur= recovery voltage T 0,95= time in ms, to reach 95% of the steady-state current. P= UE · le= steady-state power consumption in watts	l – le	U – Ue	cos	lc — le	Ur — Ue	cos
alternating	AC12	Control of resistive loads and solid state loads with isolation by opto couplers control of a.c. electromagnetic loads (>	1	1	0,9	1	1	0,9
current	AC15	72VA)	10	1	0,3	1	1	0,3
			1	U		lc	Ur	
			_	— Ue	t 0,95	_		t 0,95
			le	Ue		le	Ue	
Direct	DC 12	Control of resistive loads and solid state loads with isolation by opto couplers Control of d.c. electromagnets	1	1	1 ms	1	1	1 ms
current	DC 13	., , ,	1	1	6 · P	1	1	6 · P

The value 6-P results from an empirical relationship with is found to represent most d.c. magnetic loads to an upper limit of P = 50 W viz  $6 \cdot P = 300 \text{ ms}$ . Loads having power consumption greater than 50 W are assumed to consist of smaller loads in parallel. Therefore 300 ms is to be an upper limit, irrespective of the power consumption value.

Attach our switching device		V6 S6 N61 I		VV DD(		V1	.1	V5 S2-S23	VV5 SS2-SS21
Rated isolation voltage Ui in Volt		250		250		250		250	250
Rated operational voltage Ue in Volt		250		250		250		250	250
Rated operational current le in Ampere AC 12		6 or	16	6 or	16	6 or	16	10	10
AC 15		2	4	2	4	2	4	2	2
DC 12 2	4 V	6	8	6	8	6	8	4	4
4	3 V	2	4	2	4	2	4	2	2
11	o V	0,5	1	0,5	1	0,5	1	0,2	0,2
22	o V	0,1	0,5	0,1	0,5	0,1	0,5	0,1	0,1
Contacts gold-coated 2-	4 V	5 mA		5 mA		5 mA		5 mA	5 mA
DC 13 2	4 V	1		1		1		3	3
4	3 V	0,5		0,5		0,5		1,5	1,5
11	o v	0,2		0,2		0,2		0,1	0,1
22	o V	0,05		0,05		0,05		0,05	0,05
Short-circuit-protection in Ampere Fuse 9L Circuit-breaker G-characteristic		6 6	16 16	6 6	6 16	6 6	16 16	10 10	10 10
Terminal screws Plug-in connector CAGE CLAMP® connection is a registered trademarkt of WAGO		M 3,5 2,5 mm <sup>2</sup>		M 3,5		M 3,5		M 3,5 6,3 x 0,8	M3,5 6,3 x 0,8
Kontakttechnik GmbH Germany									
Conductor sizes in mm <sup>2</sup> finely stranded with end steeves		1,5		1,5		1,5		1,5	1,5
Mechanical life in million (operation cycles) max. switching frequency c/h 1000		10		20		10		6	10
Mechanical shock resistance									

Mechanical shock resistance IEC 68-2-27

Shock-amplitude > 15 Shock duration 20 ms

Clearances and creepage distances IEC 947-1; 2.5.46.51

Overvoltage category III pollution grade 3

### **Technical data**



Attach our switching device	V8 V85 D8	VV8 VV85 D3 S3	V10 V25 S1	V14 S14	V3	Dead man `s button signal button push button		
Rated isolation voltage Ui in Volt	110	110	110	250	500	250		
Rated operational voltage Ue in Volt	110	110	110	250	350	250		
Rated operational voltage le in Ampere AC 12	2	2	2	6	16	6		
AC 15	0,5	0,5	0,5	2	4	2		
DC 12 24\	/ 2	2	2	6	8	4		
48 \	1	1	1	2	4	2		
110\	0,1	0,1	0,1	0,5	1	0,2		
220\	<i>'</i>			0,1	0,5	0,1		
Contacts gold-coated 24 \	/ 5 mA	5 mA	5 mA	5 mA	5 mA	5 mA		
DC 13 24 \	1,5	1,5	1,5	1	1	3		
48 \	0,5	0,5	0,5	0,5	0,5	1,5		
110\	0,05	0,05	0,05	0,2	0,2	0,1		
220\	′			0,05	0,05	0,05		
Short-circuit-protection in Ampere Fuse 9L Circuit-breaker G-characteristic	4 4	4 4	4 4	6	16 16	6 6		
Terminal screws Plug-in connector CAGE CLAMP® connection is a registered trademarkt of WAGO Kontakttechnik GmbH Germany		Solder terminal		M4 1,5 mm <sup>2</sup>	M 3,5 6,3 x 0,8	6,3 x 0,8		
Conductor sizes in mm <sup>2</sup> finely stranded with end steeves	0,5	0,5	0,5	1	1,5	1,5		
Mechanical life in million (operation cycles) max. switching frequency c/h 1000	8	12	8	6	6	10		
Mechanical shock resistance IEC 68-2-27	Shock-amplitude	> 15 Shock dura	ation 20 ms					
Clearances and creepage distances IEC 947-1; 2.5.46.51	Overvoltage cate	egory III pollution g	rade 3					
Degree of protection to IEC/EN 60529		1. numerial prote and foreign bodi			2. numerial prot	ection of water		
	IP00	No protection			No protection			
	IP54	Dust-protected			protected again	st splashing water		
	IP65	dust-tight			protected again	st water jets		
	IP66	dust-tight			protected again jets	st powerful water		
	IP67	dust-tight			protected against the effects of temporary immersion in water			



The Hall-Potentiometer HG2 is distinguished by its precision and longevity.

#### **Technical data**

Mechanical life 10 million operating cycles

Operation temperature -40°C to +85°C

Degree of protection IP67

Functional safety
PLd compatible (EN ISO 13849, complies

SIL2 to DIN EN IEC 61508)

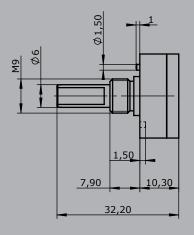


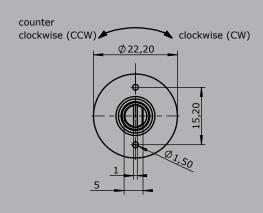
Example HG2A -E14811 -X -60 -6 Basic unit HG2A Hall-Potentiometer HG2 Model A Hall-Potentiometer HG2 Model B HG2B **Operating distance** 0-360° possible Example 60° => 60 Dead zone around the center position No dead zone Example  $+/-3^{\circ} => 6$ Interface Voltage output HG2 1 0,5...2,5...4,5 V dual inverse Ub= 5 V DC E1481 2 0,5...2,5...4,5 V dual positive gradient clockwise (cw) Ub= 5 V DC 3 0,5...2,5...4,5 V dual positive gradient counter clockwise (ccw) Ub= 5 V DC E1491 1 0,5...2,5...4,5 V positive gradient clockwise (cw) with zero position signal Ub= 5 V DC 2 0,5...2,5...4,5 V positive gradient counter clockwise (ccw) with zero position signal Ub= 5 V DC 3 0,5...2,5...4,5 V positive gradient clockwise (cw) with direction signals Ub= 5 V DC 4 0,5...2,5...4,5 V positive gradient counter clockwise (ccw) with direction signals Ub= 5 V DC More interfaces (for example SPI BUS) on request! Special model Special / customer specified



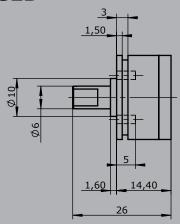


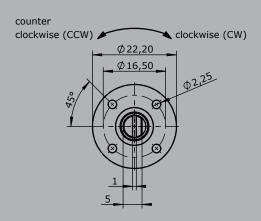
### HG2A





### HG2B





#### N<sub>10</sub>



The N10 is a Hall-Potentiometer for electrohydraulic and hoisting applications. Long life and high reliability is ensured by the latest contactless hall-technology. Up to 18 detent points can be integrated.

#### **Technical data**

Mechanical life 10 million operating cycles

Mechanical life with detent/friction brake 3 million operating cycles

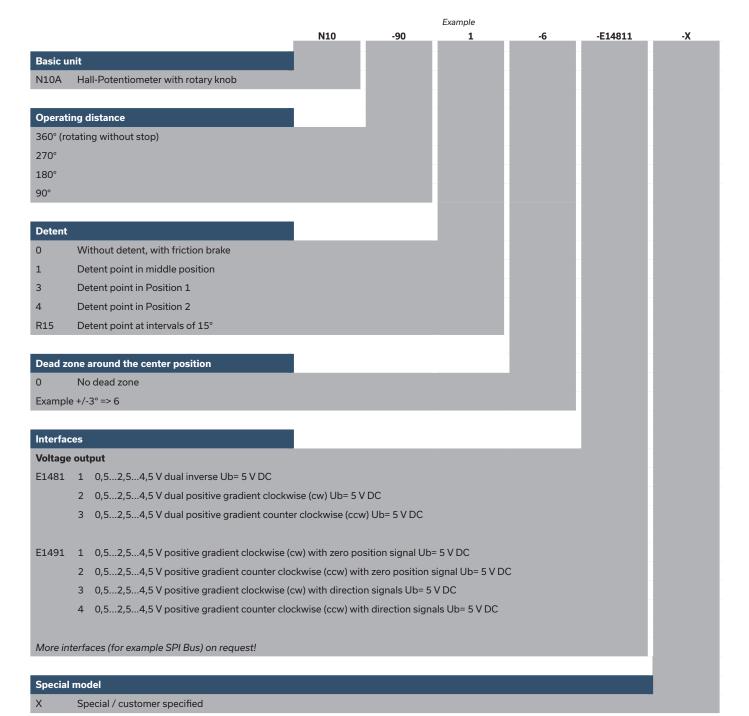
Operating temperature -40°C to +85°C

Degree of protection IP67 (electronic)

Functional safety PLd compatible (EN ISO 13849, complies

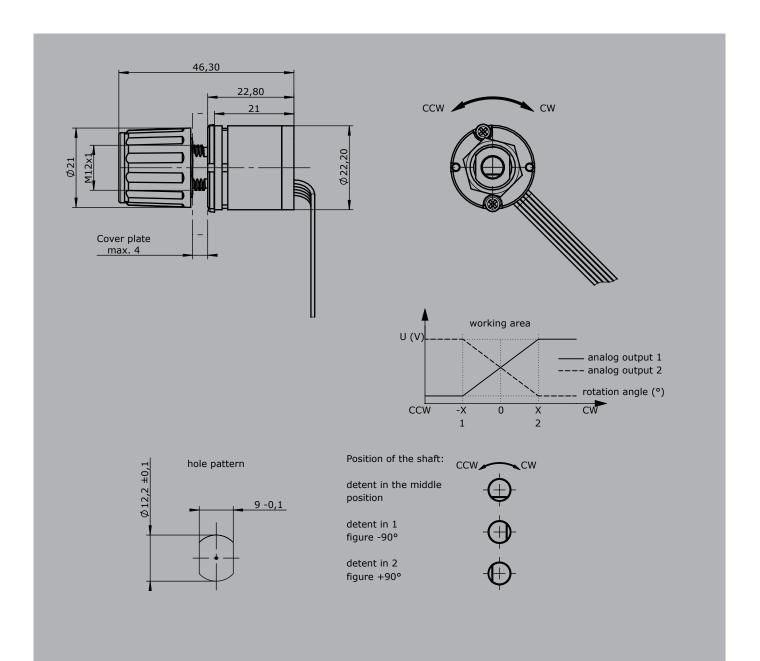
SIL2 to DIN EN IEC 61508)











# Potentiometer with attach to our switching device



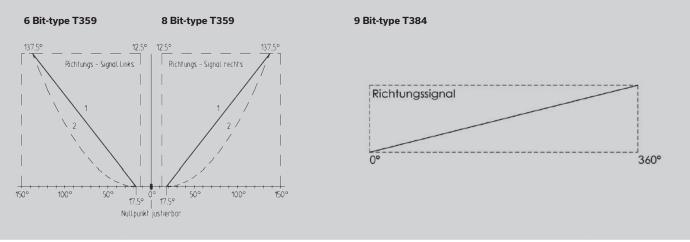
							with	centre	tap life					
											Hall 0,52,54,5 V / 4,52,50,5 V		Addition for Part No.	
			3			Ē	_	_	_	Ε	.54 ,5V		r Par	
		<b>§</b>	lmax wiper (mA)			2 x 0,5 kOhm	2 x 1 kOhm	x 2 kOhm	2 x 5 kOhm	2 x 10 kOhm	52,		on fo	
		ity (>	iper		sion	< 0,5	, 1 X	, 2 k	5 5 5	< 10	all 0,1		dditic	
for mounting	Q.	Capacity (W)	ax w	ρ	Expansion			7	5		Ξ 4,	Part No.	¥	
on	Дyp			Тур		1	2	3	4	5				Comment
V6 / VV6 D64 / DD64	T1420	1,5	10	P44		X	х	X	Х	Х		524004400		
V5 / VV5 V3	T132	2,5	10	P05		X	Х	Х	Х	х		524000500		
S2 / SS2 S6	T132 Öl	2,5	10	P06		X	X		Х	Х		524000600		de constant de la Collège de la constant de la Collège de
N6	T178	1,5	10	P07			X	X	X	+4		524000700		characteristic progressive
P7 P8	T238 T133	1	10	P08		X	Х	X	X	x*1		524000800		*1 R= 2 x 6,5 kOhm
	T396	60	85	P10 P13		X	.,			.,		524001000		
	T1350 Ex	0,5	1	P13		X	X	X	X	X		524001300 524001400		
	T1360	0,5	1	P43		X	Х	X	Х	Х	х	524001400		
1/0 /10/0											X			
V8 / VV8 D8	T239	1	10	P17				X	Х			524001700		
P10 P11	T301	0,5	1	P18			Х	Х	Х	Х		524001800		
P12	T426	0,5	1	P19					Х	Х		524001900		with direction lines
	T432	0,5	1	P20					Х			524002000		
	T246	0,5	1	P21		X	Х		Х	Х		524002100		
	T362	0,5	1	P22			Х	Х	Х			524002200		
	T1003			P42							Х	5240042009		
	T1360			P43					<u> </u>		Х	5240043009		
V10 S1	T321	1	10	P24			х					524002400		
Palm handle	T320	0,5	1	P25			х		х			524002500		
	T1187	0,5	1	P27					х			524002700		with direction lines
	T375	0,5	1	P37			х		Х			524003700		
	T997			P41					ļ		х	5240041009		
V11	T316	1	10	P31					x*2			524003100		*2 R= 2 x 4 kOhm
	T365	0,5	1	P32					х	х		524003200		
D3 S3	T318	0,5	1	P48					х			524004800		
	•				П	v	vithout	centre	tap life					
													art	
			7			_							for F	
		8	r E		_	Ohrr	E H	E H	E	Ohm			tion	
		ity (	wipe		ISIOL	0,5 kOhm	1 kOhm	2 kOhm	5 kOhm	10 kOhm		Part No.	Addition for Part No.	
for mounting	Тур	Capacity (W)	lmax wiper (mA)	Typ	Expansion	1	2	3	4	5		Fait NO.	~~	Commond
on V6 / VV6	⊢ T1491	1,5					Т	Т	ı			524004600		Commend
D64 / DD64	T1491 T131	1,5 2,5		P46 P03		X	X	X	X	X		524004600		
V5 / VV5 V3	T131 Oil	2,5		P03		Х	X	Х	X	X		524000300		
S2 / SS2 S6	T131 OII	2,5 60		P04 P11			Х		X	Х		524000400		
N6 P7 / P8	T374					_			X			524001100		
FIIPO		0,5		P12		Х	X	Х	х	х				
V8 / VV8 /D8 P10/P11/P12	T244 T397	0,5 0,5		P23 P47			х	x x	x x	Х		524002300 524004700		
V10 / S1 Palm grip	T337	0,5		P26			х	x	х	х		524002600		
GE1/GE2	PW70	5	30	P45		х	х		х			524004500		
Technical details m								ubiect to		vithout no	nticel	32700 <del>1</del> 300		

# **Opto-Electronic Encoder** OEC 2



Opto-electronical encod	er OEC 2 with digital output (	gray-/binär-cdode			
Power supply	18-30 V DC				
Rotation angle	Max. +/-150° (by 9 Bit 300°	)			
Digital output	8 Bit Gray-Code T359	Output characteristic linear	OEC 2-1-1	C01	410 g
	8 Bit Binary-Code T359	Output characteristic linear	OEC 2-2-1	C02	410 g
	6 Bit Gray-Code T359	Output characteristic linear	OEC 2-3-1	C031	410 g
	6 Bit Gray-Code T359	Output characteristic quadratic	OEC 2-3-2	C032	410 g
	6 Bit Binary-Code T359	Output characteristic linear	OEC 2-4-1	C041	410 g
	6 Bit Binary-Code T359	Output characteristic quadratic	OEC 2-4-2	C042	410 g
	9 Bit Gray-Code T384	Output characteristic linear one side clockwise	OEC 2-5-4	C054	410 g
	9 Bit Gray-Code T384	Output characteristic linear one side anticlockwise	OEC 2-5-5	C055	410 g
	9 Bit Binary-Code T384	Output characteristic linear one side clockwise	OEC 2-6-4	C064	410 g
	9 Bit Binary-Code T384	Output characteristic linear one side anticlockwise	OEC 2-6-5	C065	410 g

6 Bit-type T359		8-Bit-type T359		9 Bit-type T384				
PIN	connection	Colour-code	PIN	connection	Colour-code	PIN	connection	Colour-code
1	Not connected	-	1	Not connected	-	1	Not connected	-
2	D4	brown	2	D6	brown	2	D6	brown
3	D3	green	3	D5	green	3	D5	green
4	D2	yellow	4	D4	yellow	4	D4	yellow
5	D1	grey	5	D3	grey	5	D3	grey
6	Not connected		6	D2	pink	6	D2	pink
7	Not connected	-	7	D1	blue	7	D1	blue
8	Housing 0 V	black	8	Housing 0 V	black	8	Housing 0 V	black
9	Input 18-30 V DC	red	9	Input 18-30 V DC	red	9	Input 18-30 V DC	red
10	Not connected	-	10	Not connected	-	10	Not connected	-
11	Not connected	-	11	Not connected	-	11	Not connected	-
12	Direction-signal left	violet	12	Direction-signal left	violett	12	Direction-signal left	violett
13	Direction-signal grey	grey-pink	13	Direction-signal right	grey-pink	13	D9	grey-pink
14	D6	red-blue	14	D8	red-blue	14	D8	red-blue
15	D5	white-green	15	D7	white-green	15	D7	white-green
-	Cable screen	brown-green		Cable screen	brown-green	-	Cable screen	brown-green

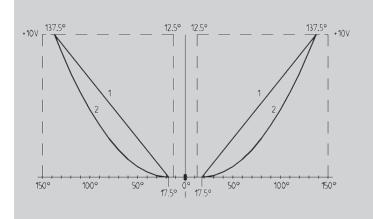


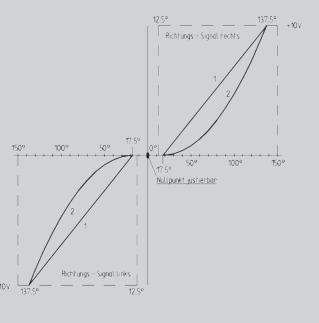
# **Opto-Electronic Encoder** OEC 2



Opto-electronical encoder OE	C 2 with voltage output				
Power supply	18 - 30 V DC				
Scanning	6 Bit Gray-Code				
Rotation angle	Max. +/-150°				
Voltage output	10010 V T366	Output characteristic linear	OEC 2-3-1-1	C111	410 g
	10010 V T366	Output characteristic quadratic	OEC 2-3-2-1	C112	410 g
	-100+10 V T367	Output characteristic linear	OEC 2-3-1-2	C151	410 g
	-100+10 V T367	Output characteristic quadratic	OEC 2-3-2-2	C152	410 g

Voltag	e output	
PIN co	nnection	Colour-code
1	Not connected	-
2	Not connected	-
3	Not connected	-
4	Not connected	-
5	Not connected	-
6	Not connected	-
7	Not connected	-
8	Housing 0V	blue
9	Input 18-30V DC	brown
10	Not connected	-
11	Voltage output	green
12	Direction signal left	yellow
13	Direction signal right	grey
14	Not connected	-
15	Not connected	•
-	Cable screen	white



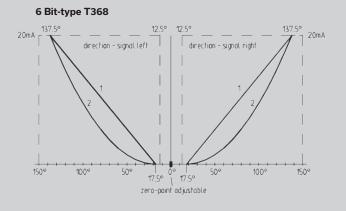


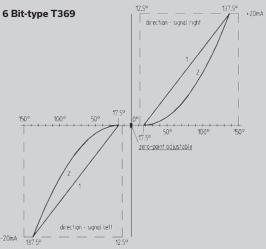
# **Opto-Electronic Encoder** OEC 2



Opto-electronical encoder OEC 2 with current output							
Power supply	18 - 30 V DC						
Scanning	6 Bit Gray-Code						
Rotation angle	Max. +/-150°						
Output current	20420 mA T368	Output characteristic linear	OEC 2-3-1-5	C191	410 g		
	20420 mA T368	Output characteristic quadratic	OEC 2-3-2-5	C192	410 g		
	20020 mA T368	Output characteristic linear	OEC 2-3-1-8	C201	410 g		
	20020 mA T368	Output characteristic quadratic	OEC 2-3-2-8	C202	410 g		
	-200+20 mA T369	Output characteristic linear	OEC 2-3-1-6	C231	410 g		
	-200+20 mA T369	Output characteristic quadratic	OEC 2-3-2-6	C232	410 g		

6 Bit-Type T368		6 Bit-Type T369			
PIN co	onnection	Colour-code	PIN co	nnection	Colour-code
1	Not connected	-	1	Not connected	-
2	Not connected	-	2	Not connected	-
3	Not connected	-	3	Not connected	-
4	Not connected	-	4	Not connected	-
5	Not connected	-	5	Not connected	-
6	Not connected	-	6	Not connected	-
7	Not connected	-	7	Not connected	-
8	Housing 0 V	blue	8	Housing 0V	blue
9	Input 18-30 V DC	brown	9	Input 18-30 V DC	brown
10	Not connected	-	10	Not connected	-
11	Current output	green	11	Current output	green
12	Direction signal left	yellow	12	Direction signal left	yellow
13	Direction signal right	grey	13	Direction signal right	grey
14	Not connected		14	Not connected	-
15	Not connected	-	15	Not connected	-
-	Cable screen	white	-	Cable screen	white





#### Attachment

Plug with cable  $14 \times 0.25 \text{ mm}^2$ , 2000 mm long, cable head open (for OEC 2 with digital outputs) Plug with cable  $7 \times 0.34 \text{ mm}^2$ , 2000 mm long, cable head open (for OEC 2 with analog outputs)

5300000495 5300000496

The OEC 2 is able for mounting on V6,VV6/D64,DD64/V11/S2,SS2/S6/N6. For mounting a potentiometer mounting option (P) of the respective controller is required!

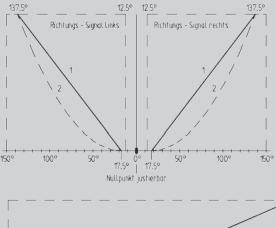
### **Opto-Electronic Encoder**

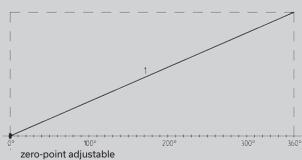
### OEC 4

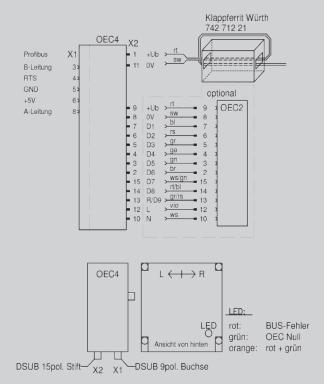
### with interface Profibus DP



Opto-elecetronic encoder				
Power supply	18 - 30 V DC			
Scanning	6, 8 or 9 Bit Gray-Code			
Rotation angle	Max. +/-150°			
Interface	Profibus, DP, address 0-99 adjustable above selector switch			
Voltage output	8 Bit Gray-Code T496 linear	OEC 4-1-1-2	C27	820 g
	8 Bit Binary-Code T496 linear	OEC 4-2-1-2	C28	820 g
	6 Bit Gray-Code T496 linear	OEC 4-3-1-2	C291	820 g
	6 Bit Gray-Code T496 quadratic	OEC 4-3-2-2	C292	820 g
	6 Bit Binary-Code T496 linear	OEC 4-4-1-2	C301	820 g
	6 Bit Binary-Code T496 quadratic	OEC 4-4-2-2	C302	820 g
	9 Bit Gray-Code T497 linear one sided right turn	OEC 4-5-4-2	C314	820 g
	9 Bit Gray-Code T497 linear one sided left turn	OEC 4-5-5-2	C315	820 g
	9 Bit Binary-Code T497 linear one sided right turn	OEC 4-6-4-2	C324	820 g
	9 Bit Binary-Code T497 linear one sided left turn	OEC 4-6-5-2	C325	820 g







#### **Attachment**

Plug (Profibus) straight

Plug (Profibus) 90° angled

Plug with cable 2 x 0,25 mm<sup>2</sup>, 2000 mm long, cable head open (cable for current supply OEC 4 single application)

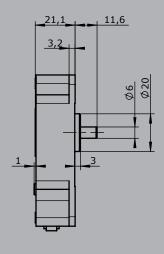
Connecting cable OEC 4/ OEC 2  $(14 \times 0.25 \text{ mm}^2)$  with 2 plug connectors incl. cable for current supply  $(2 \times 0.25 \text{ mm}^2)$  2000 mm long, cable head open)

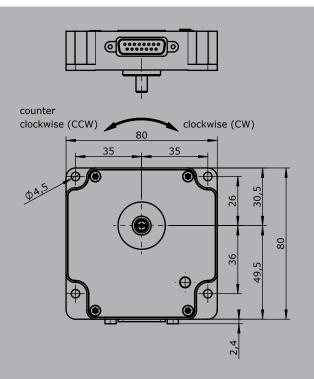
The OEC 4 is able for mounting on V6,VV6/D64,DD64/V11/S2,SS2/S6/N6. For mounting a potentiometer mounting option (P) of the respective controller is required! For a controller with one axis is required 1 piece of OEC 4, for a controller with 2 axis are required 1 piece of OEC 4 and 1 piece of OEC 2.

# Opto-Electronic Encoder OEC 2, OEC 4

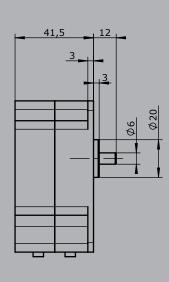


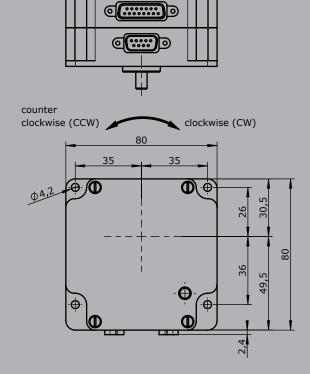
### OEC 2





### **OEC 4**





Technical details may vary based on configuration or application! Technical data subject to change without notice!

## **Electronic Control Unit**





The Electronic Control Unit ES/43 serves for control of proportional valves without position control. There is a version for 4 proportional valve solenoids (ES / 43-10) and a version for 2 Proportional valve solenoids (ES / 43-11) available.

#### Features:

- Stabailized voltage
- Chopper output stage with adjustable frequency
- Ramp time setting ON/OFF delay
- Creep speed circuit adjustable
- Solenoid current setting separate for minimum current and maximum current
- Output current controlled independently of temperature and solenoid
- Power output short-circuit-proof with overload protection
- Voltage input protected against polarity reversal
- Mechanical selection of direction by means of contacts
- LED operating voltage and working display
- Microprocessor technology therefore especially adaptable



Example

#### Technical data:

- Supply voltage		10	32 V DC
- Residual ripple		20%	
- Control voltage range	Ue	0	5 V
- Control current	le	<1mA	
- Dither frequency	f	25	250Hz
- Proportional valve S 1-4	I min.	0	1A
Output	I max. = I min		2A at 12 Volt
Output	I max. = I min		1A at 24 Volt
- Ramp time setting	t on	0,2	25 sec
	t off	0,2	25 sec
- Creep speed	variable reduction		2575%

- Operating temperature -40°C to +80°C - Storage temperature

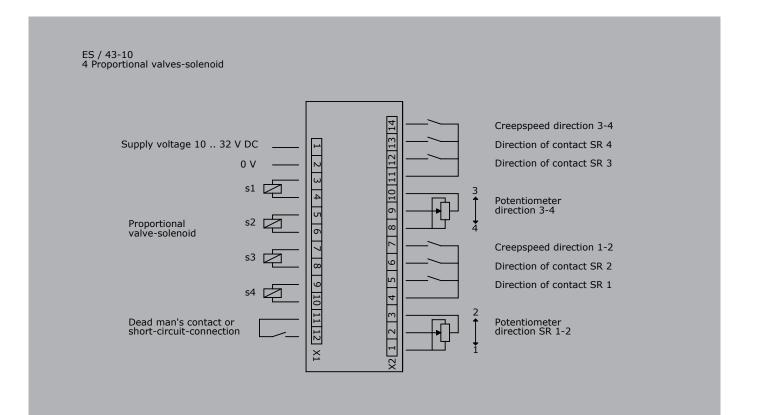
-40°C to +85°C

Electronic Control Unit for 4 proportional valves solenoid ES/43-10

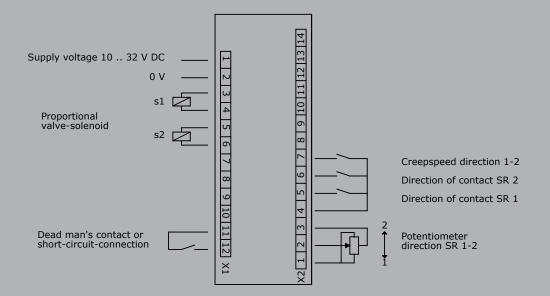
Electronic Control Unit for 2 proportional valves solenoid ES/43-11

## **Electronic Control Unit** ES/43





ES / 43-11 2 Proportional valves-solenoid



Technical details may vary based on configuration or application! Technical data subject to change without notice!

# Mini-Joystick





The V21 is a Mini-Joystick commonly used in electro-hydraulic applications. The V21 is especially suitable for installation in our ball grips. Long life and high reliability is ensured by the latest contactless hall-technology.

#### Technical data

Mechanical life 5 million operating cycles

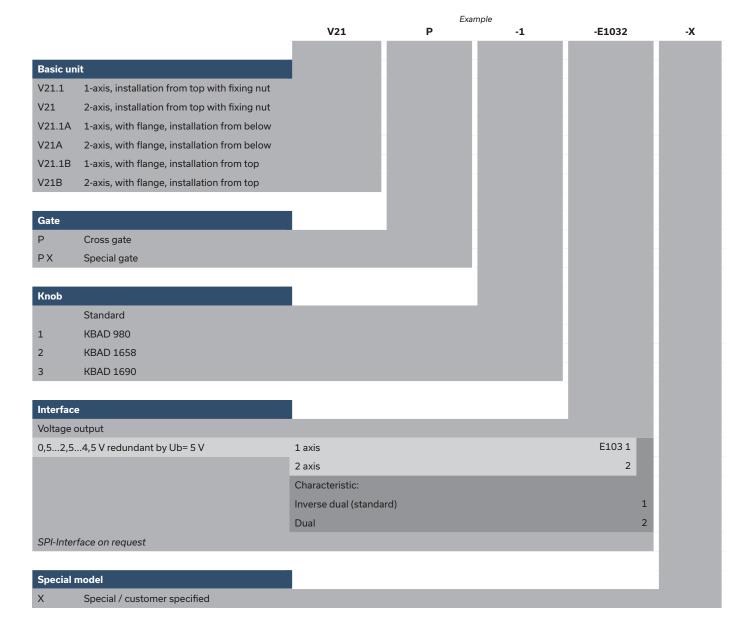
Operating force 1,6 to 3,5N 5V DC stabilized Supply voltage -40°C to +85°C Operation temperature

Degree of protection

PLd compatible (EN ISO 13849, complies Functional safety

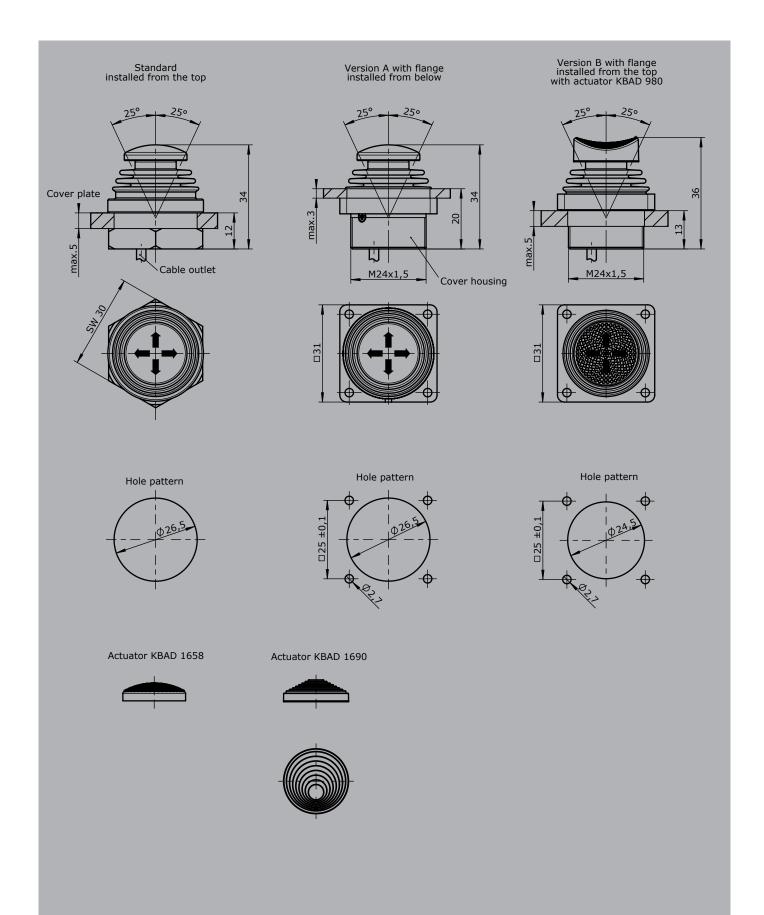
SIL2 to DIN EN IEC 61508)





### Mini-Joystick V21





# Mini-Joystick





The Mini-Joystick S9 is a hallsensor switching device designed for electro-hydraulic applications. Long life and high reliability is ensured by the latest contactless hall-technology. Due to its small size, the S9 is particularly suitable for installation in our ball handles.

#### **Technical data**

Mechanical life S9 5 million operating cycles

1,6 to 3,5N Operating force 5V DC stabilized Supply voltage -40°C to +85°C Operating temperature

Degree of protection IP67

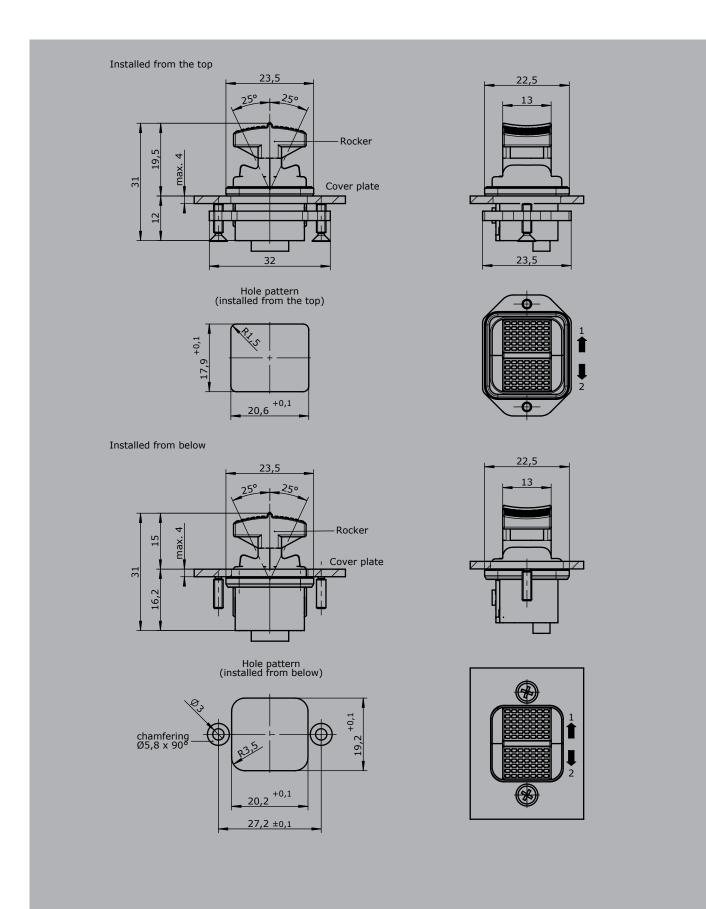
PLd compatible (EN ISO 13849, complies SIL2 to DIN EN IEC 61508) Functional safety



Example - E10311 S9 - X **Basic unit** S9 Interface E1031 0,5...2,5...4,5 V redundant by Ub= 5 V Output option inverse dual 1 Output option dual Special model Special / customer specified

# Mini-Joystick





## Fingertip Joystick **S15**



The S15 is a Fingertip Joystick designed for electro-hydraulic applications. A long service life and high reliability is achieved by the latest contactless hall-technology. With the different actuator colours the appearance can be individually designed.

#### **Technical data**

Mechanical life S15 5 million operating cycles

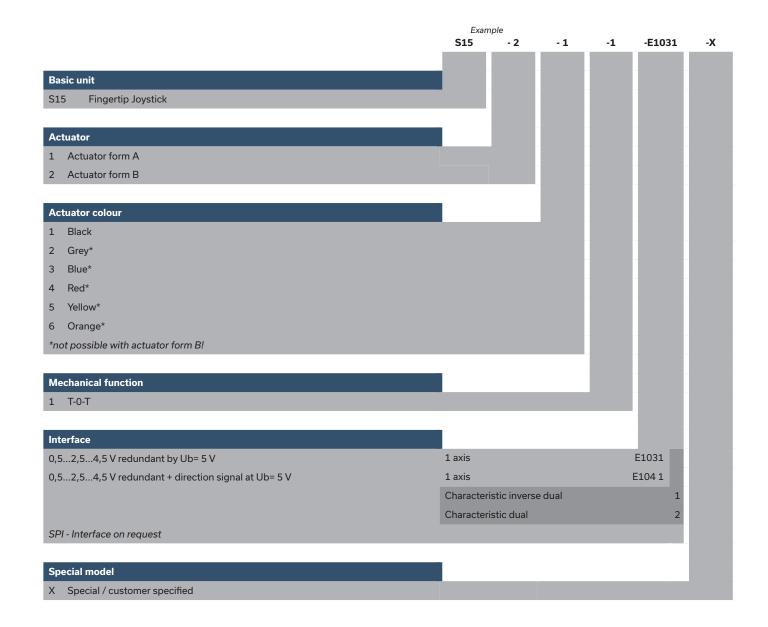
-40°C to +85°C Operating temperature

Degree of protection IP67

PLd compatible (EN ISO 13849, complies Functional safety

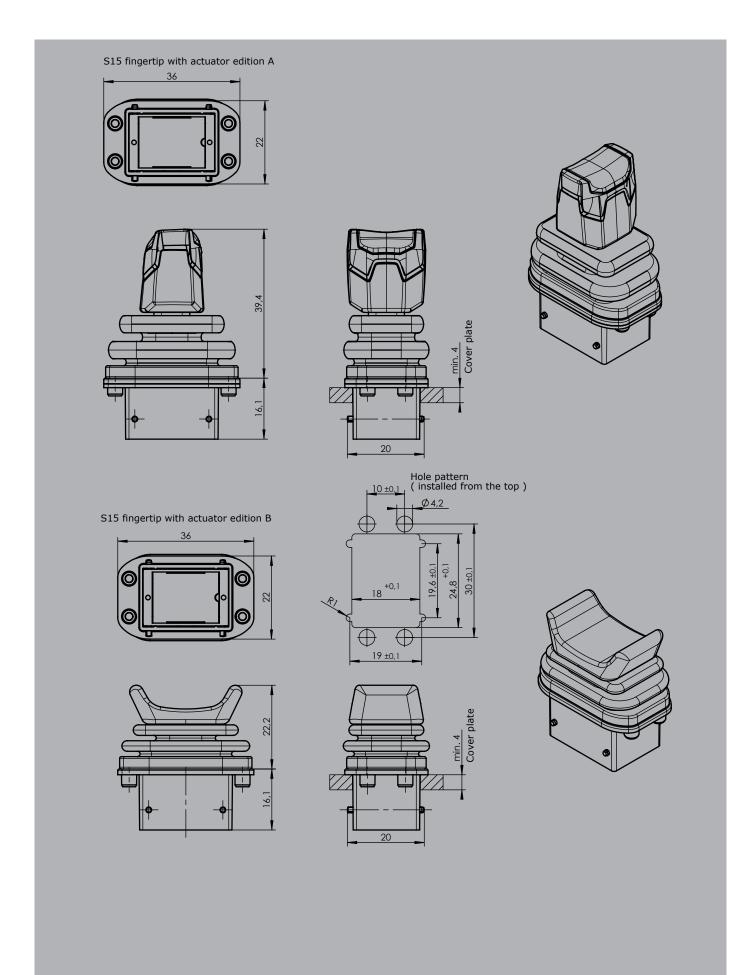
SIL2 to DIN EN IEC 61508)





# Fingertip Joystick S15





### Hall-Cross Switch



The Hall-Cross Switch HK1 is a contactless Mini-Joystick designed for electro-hydraulic applications. Different actuators are available. Optionally a version with Push button is possible.

#### **Technical data**

Mechanical life HK1

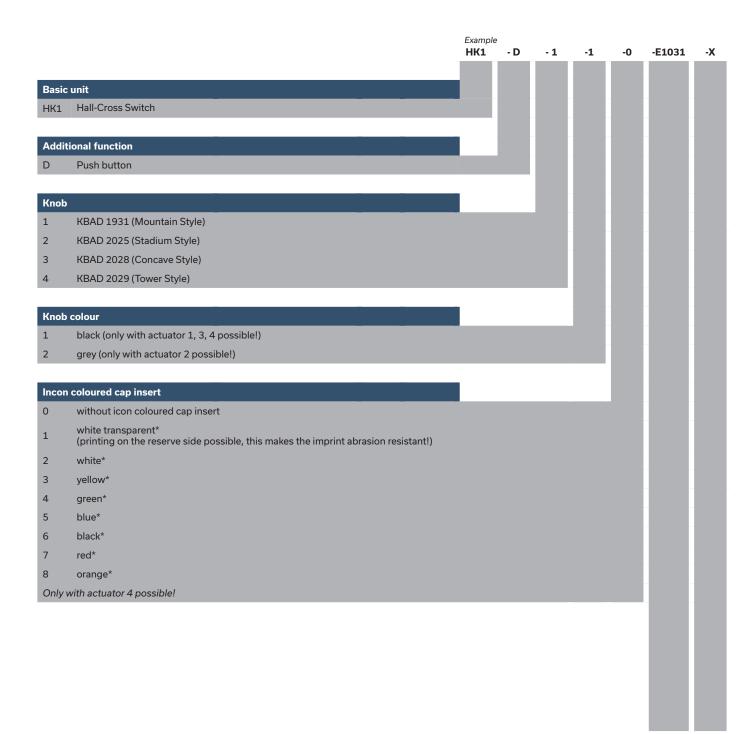
1 million operating cycles

Operating temperature

Degree of protection

-40°C to +85°C IP67 (electronic)





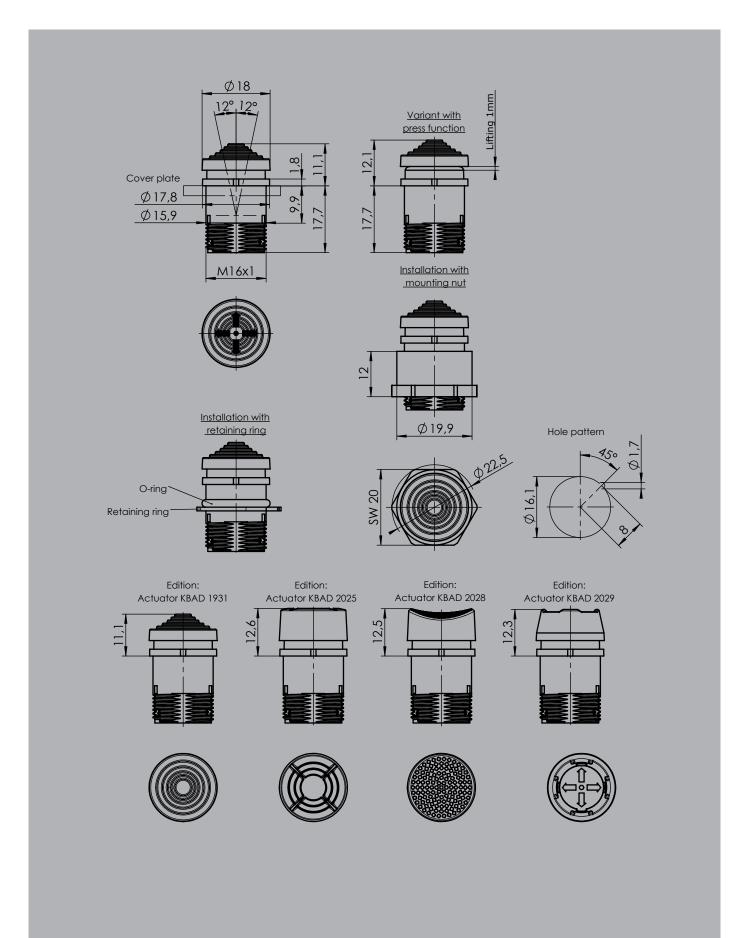






### Hall-Cross Switch





### **Thumbwheel**



The Thumbwheel S12 is designed for electro-hydraulic applications. Long life and high reliability is ensured by the latest contactless hall-technology. By the combination of different actuators, lighting options and colours you can customise the appearance.

#### **Technical data**

Mechanical life S12 5 million operating cycles

-40°C to +85°C Operating temperature

IP67 Degree of protection

PLd compatible (EN ISO 13849, complies Functional safety

SIL2 to DIN EN IEC 61508)



Example **S12** -X - 2 -E1031 - 1 -1

### Basic unit

S12 Thumbwheel S12

S12B Thumbwheel S12 with actuator version B

S12C Thumbwheel S12 with actuator version C

#### **Mounting frame**

with mounting frame

without mounting frame

#### Illumination

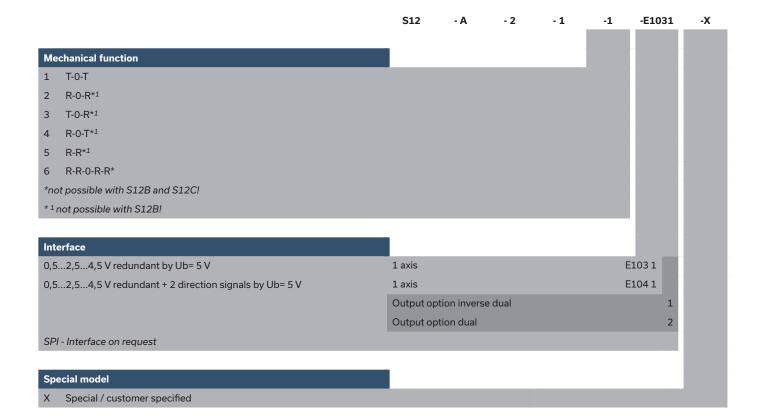
- 1 Unlighted
- 2 Functional lighting 2-colour red-green (separate switchable) U\_LED= 4,5 - 5,5 V\*
- 3 Functional lighting 2-colour white-red (separate switchable) U\_LED= 4,5 - 5,5 V\*
- Functional lighting 2-colour white-green (separate switchable) U\_LED= 4,5 5,5 V\*

\*not possible with S12B and S12C!

Ac	tuator colour			
		S12	S12B	S12C
1	Black	$\checkmark$	$\checkmark$	√
2	Grey	$\checkmark$		
3	Blue	$\checkmark$		
4	Red	$\checkmark$		$\checkmark$
5	Yellow	$\checkmark$		
6	Orange	$\checkmark$		
7	Green	√		

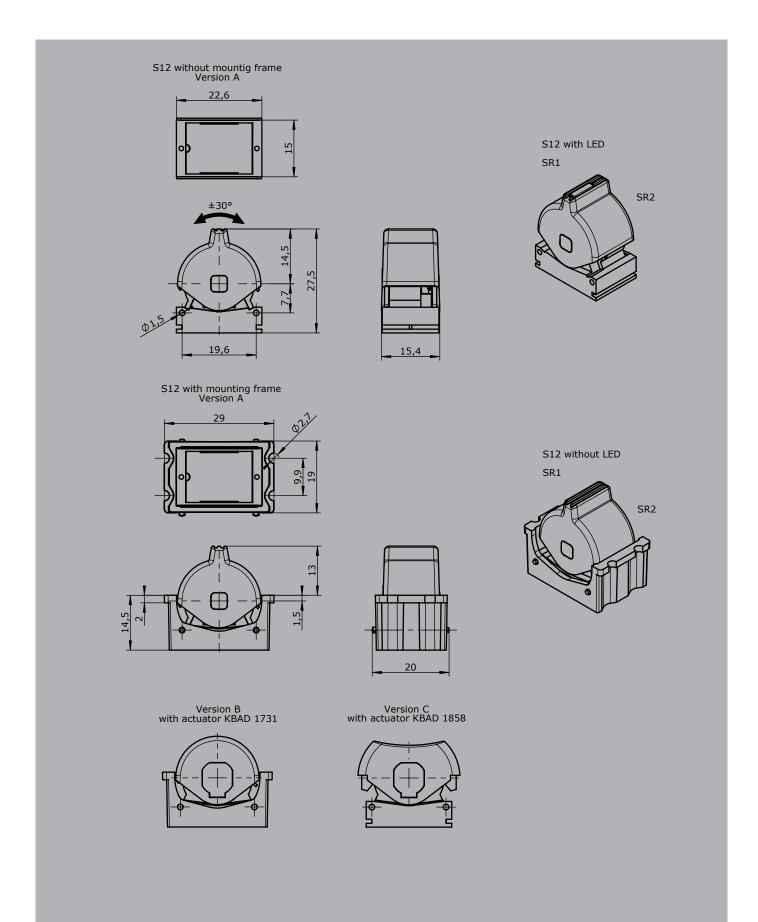






# Thumbwheel S12





### Thumbwheel



The Thumbwheel S16 is designed for electro-hydraulic applications. The S16 can be optimally used with the scroll and push function as a selection device for displays.

#### **Technical data**

Mechanical life S16

5 million operating cycles

Operating temperature

-40°C to +85°C

Degree of protection

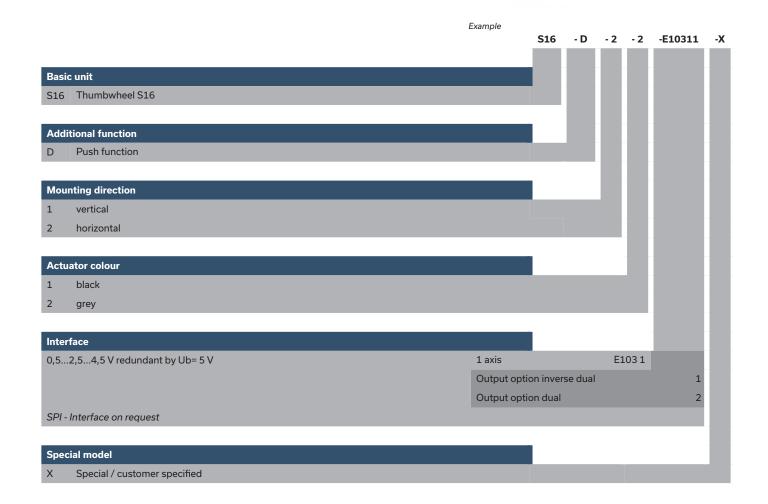
IP67

Functional safety

PLd compatible (EN ISO 13849, complies

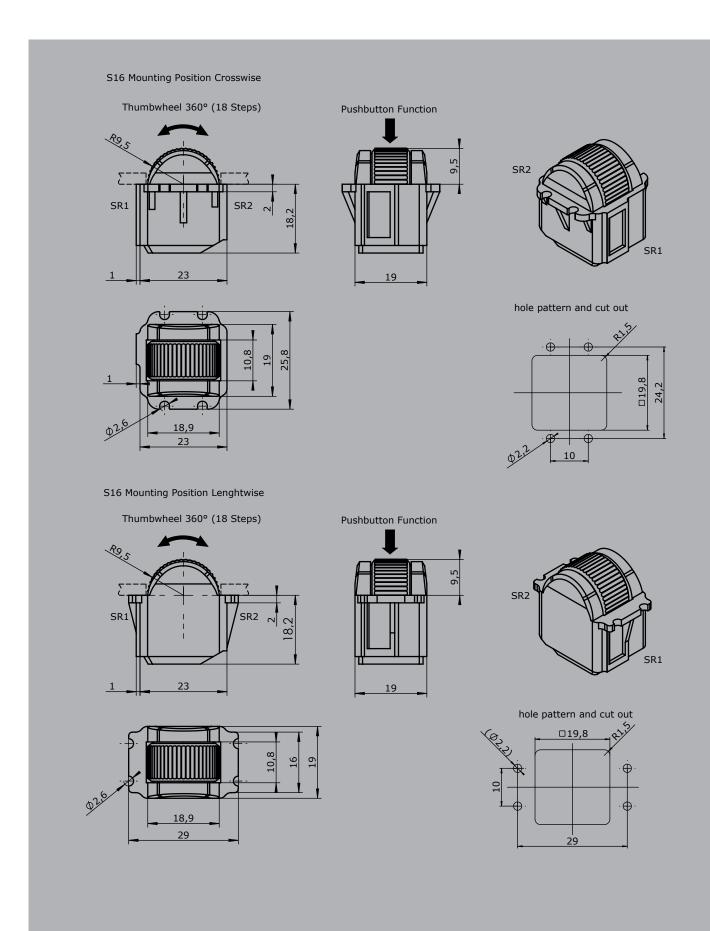
SIL2 to DIN EN IEC 61508)





# Thumbwheel S16





### Hall-Push Button



The Hall-Push Button impressed by its durability and versatility. It is available in five basic versions. By combining different lighting options, colours and symbols, it is possible to customize.

#### Technical data

Mechanical life 10 million operating cycles

Operation temperature -40°C til +85°C

Degree of protection IP67

Functional safety

PLd compatible (EN ISO 13849, complies

SIL2 to DIN EN IEC 61508)



Example



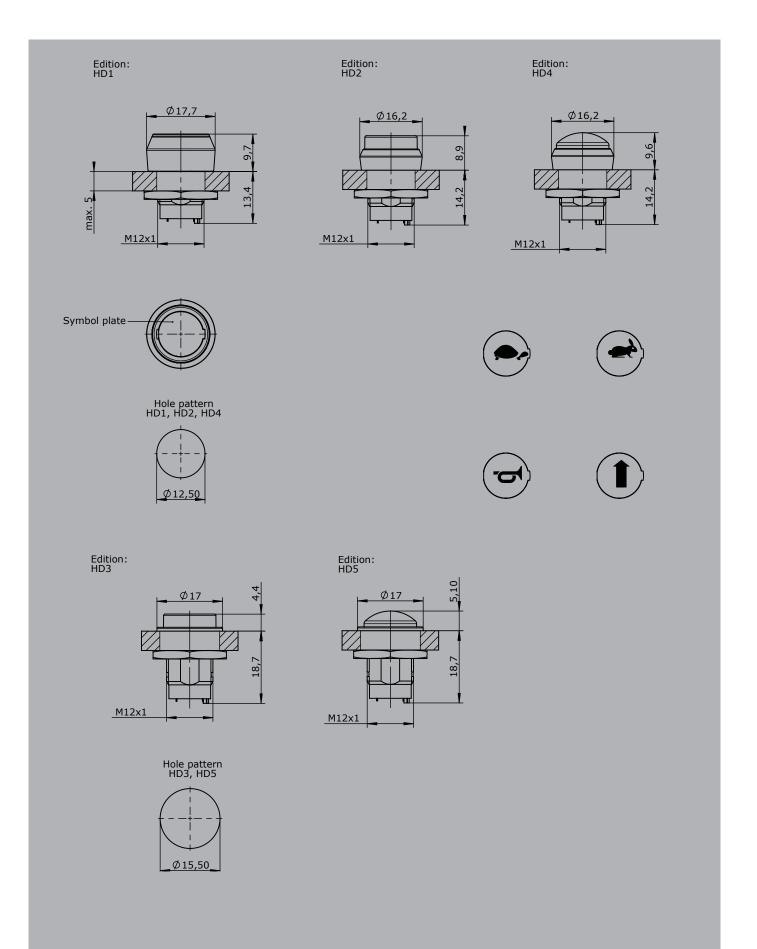






## Hall-Push Button











The Palm Grip B35 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long). The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### **Technical data**

Operating temperature

Degree of protection

Contact complement

-40°C to +85°C

Control element up to IP67

1,5A 24 V DC 13 (\*1 0,1A 24 V DC13)

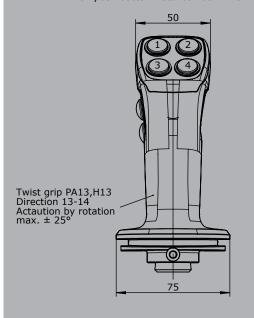


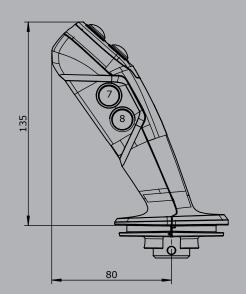
	BS	35	Example -2D	w	К	SE	S12	H13	-X
Basic	c unit								
B35	Palm Grip								
Digita	al actuating element								
D	Push Button KDA21 *1								
	Colour: red, black, yellow, green, blue, white, orange								
HD	Hall-Push Button (see page 151)								
W	Rocker switch momentary (T) or maintained (R), colours: red, black, yellow, blue, wh Mechanical functions: T-0-T, 0-T, R-0-T, R-0-R, 0-R, R-R	ite							
К	Lever switch								
SE	Sensor Button capacitive with external control electronics								
S	Sensor Button capacitive without external control electronics								
	(Consistent with V85 / VV85 with interface E1xx to E6xx, E907 and V25/V27 with int	erfa	aces E3x	k + E4xx	+E907)				
٧	Vibration								
Analo	og actuating element								
S12	Thumbwheel, output 0,52,54,5 V inverse dual (see page 146)								
S16	Thumbwheel, output 0,52,54,5 V inverse dual (see page 149)								
V21	Mini-Joystick, output 0,52,54,5 V inverse dual (see page 137)								
НК	Hall-Cross Switch (see page 143)								
H13	Hall-Rotary Grip, output 0,52,54,5 V inverse dual								
Speci	ial model								
Х	Special / customer specified								

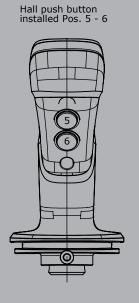




Hall push button installed Pos. 1 - 4 Hall push button installed Pos. 7 - 8



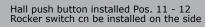


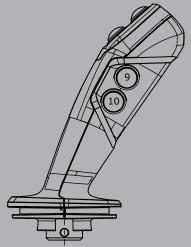


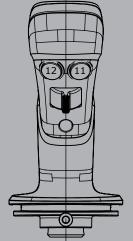
### **B35L**

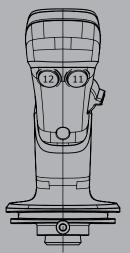
Hall push button installed Pos. 1 - 4 Hall push button installed Pos. 9 - 10











Edition: B35 Rocker switch installed Pos. 1+3 Rocker switch installed Pos. 2+4

Edition: B35
Rocker switch installed Pos. 1+2
Rocker switch installed Pos. 3+4
Rocker switch installed Pos. 2+4

Edition: B35 Rocker switch installed Pos. 1+2 Hall push button installed Pos. 3+4









Technical details may vary based on configuration or application! Technical data subject to change without notice!







The Palm Grip B34 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire  $(0.1 \text{ mm}^2, 450 \text{ mm long})$ . The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### **Technische Daten**

Operating temperature -40°C to +85°C

Special / customer specified

Degree of protection Control element up to IP67

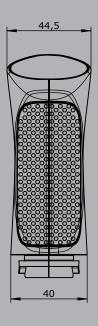
Contact complement 1,5A 24 V DC 13 (\*1 0,1A 24 V DC13)

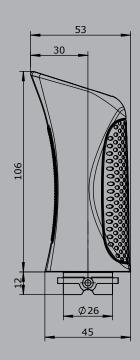


Example B34L -2D w **S12** -X Basic unit B34L Palm Grip left B34R Palm Grip right Digitale actuating element Push Button KDA21 \*1 Colour: red, black, yellow, green, blue, white, orange HD Hall-Push Button (see page 151) Rocker switch momentary (T) or maintained (R), colours: red, black, yellow, blue, white Mechanical functions: T-0-T, 0-T, R-0-T, R-0-R, 0-R, R-R W К Lever switch Analog actuating element S12 Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 146) S16 Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 149) Special model



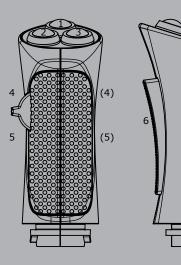
**B34** 



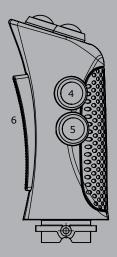


Edition:

Push button installed Pos. 1-3
Rocker switch installed Pos. 4-5
Lever switch installed Pos. 6
Position rocker switch or push button left hand ()



Edition: Push button installed Pos. 1-3,4,5 Lever switch installed Pos. 6



Technical details may vary based on configuration or application! Technical data subject to change without notice!







The Palm Grip B33 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire  $(0,1 \text{ mm}^2, 450 \text{ mm long})$ . The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### **Technical data**

Operating temperature -40°C to +85°C

Special / customer specified

Degree of protection Control element up to IP67

Contact complement \*1 0,1A 24 V DC13



Example B33L -2D **S12** -X Basic unit B33L Palm Grip left B33R Palm Grip right Digitale actuating element Push Button KDA21 \*1 Colour: red, black, yellow, green, blue, white, orange HD Hall-Push Button (see page 151) Analog actuating element S12 Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 146) S16 Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 149) Special model

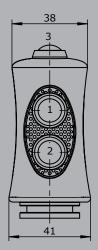


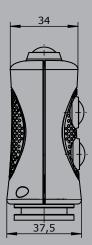


**B33** 

Edition:

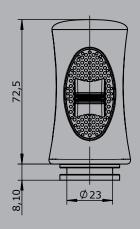
Push button installed Pos. 1,2,3

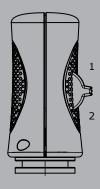




Edition:

Rocker switch installed Pos. 1+2











The Palm Grip B32 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long). The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### **Technical data**

Operating temperature

Degree of protection

Contact complement

-40°C to +85°C

Control element up to IP67

1,5A 24 V DC 13 (\*1 0,1A 24 V DC13)



Example B32L -2D W SE **S12** -X Basic unit B32L Palm Grip left B32R Palm Grip right

#### Digitale actuating element

D Push Button KDA21 \*1

Colour: red, black, yellow, green, blue, white, orange

HD Hall-Push Button (see page 151)

Rocker switch momentary (T) or maintained (R), colours: red, black, yellow, blue, white Mechanical functions: T-0-T, 0-T, R-0-T, R-0-R, 0-R, R-R W

SE Sensor Button capacitive with external control electronics

S Sensor Button capacitive without external control electronics

(Consistent with V85 / VV85 with interface E1xx to E6xx, E907 and V25/V27 with interfaces E3xx + E4xx+E907)

#### **Analog actuating element**

S12 Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 146)

S16 Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 149)

V21 Mini-Joystick, output 0,5...2,5...4,5 V inverse dual (see page 137)

НК Hall-Cross Switch (see page 143)

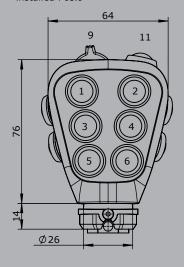
#### Special model

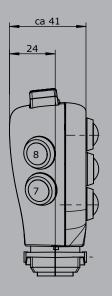
Special / customer specified

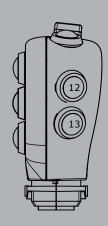


**B32** 

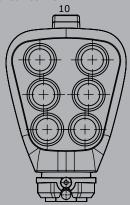




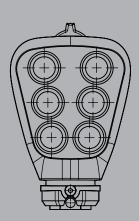




Push button installed Pos. 1 - 8, 12 + 13 Rocker switch lengthwise installed Pos. 10

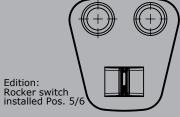


Rocker switch crosswise installed Pos. 10

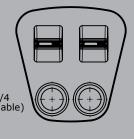


Edition: Multi-axis controller V21 installed Pos. 1/3 (Pos. 9 - 11 not available)















The Palm Grip B31 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long).

#### **Technical data**

Operating temperature

Degree of protection

Contact complement

-40°C to +85°C

Control element up to IP67

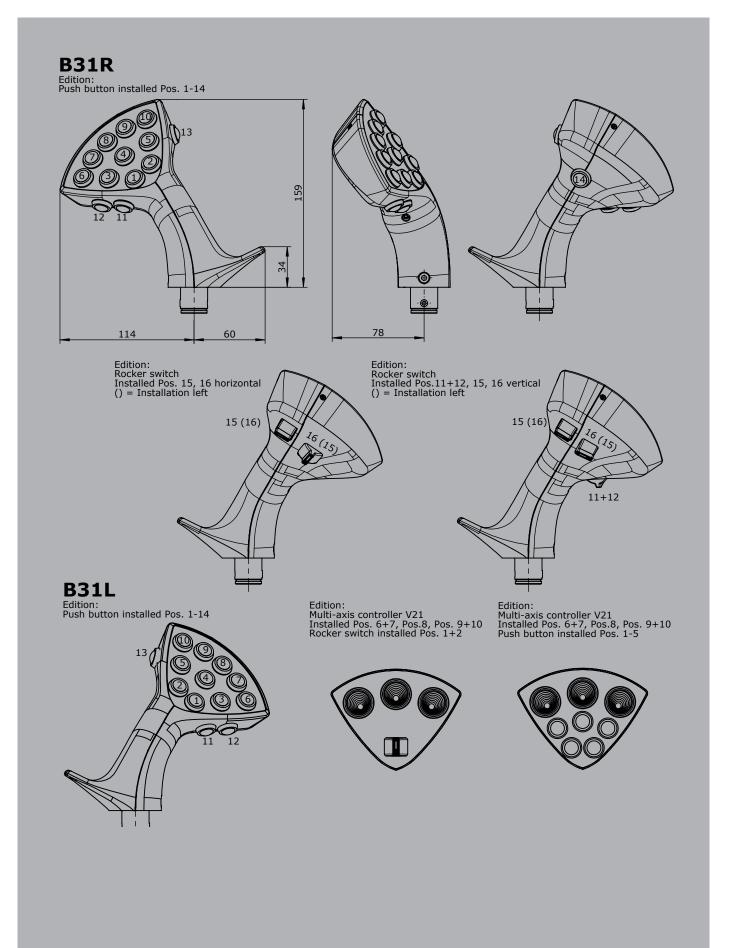
1,5A 24 V DC13 (\*1 0,1A 24 V DC13)



			DO4 D	Exan	•		240	1/04
Basic unit			B31R	-2D	W	HK	S12	V21
	lm Grip left		_					
	lm Grip right							
			_					
Digital actu	uating element							
D Pu	ish Button KDA21 *1							
		w, green, blue, white, orange						
	ll-Push Button (see p							
		ary (T) or maintained (R), colours: red, I-0-T, 0-T, R-0-T, R-0-R, 0-R, R-R	black, yellow, blue	white				
			_					
Analog act	tuating element							
S12 Th	umbwheel, output 0	,52,54,5 V inverse dual (see page 1	1.46)					
S16 Th	umbwheel, output 0	,52,54,5 V inverse dual (see page 1	1.49)					
V21 Mii	ni-Joystick, output 0,	52,54,5 V inverse dual (see page 1	37)					
НК На	III-Cross Switch (see	page 143)						
CAN								
CAN Supply volt	rage	9-32 V DC	_	_		_		_
Supply volt		9-32 V DC 80 mA (24 V DC)	-	•				
Supply volta	rage t consumption rrying capacity	9-32 V DC 80 mA (24 V DC) External digital output for LEDs 5 m/	A - 30 mA (depend	ent on the i	number of	LED`s)		
Supply volta	t consumption	80 mA (24 V DC)					i	ı
Supply voltal	t consumption	80 mA (24 V DC)  External digital output for LEDs 5 m/	pased on) or CANop				i	
Supply volt Idle current Current car Protocol	t consumption	80 mA (24 V DC)  External digital output for LEDs 5 m/ CANopen CiA DS 301, SAE J1939 (b)	pased on) or CANop				i	I
Supply volt Idle current Current car Protocol	t consumption	80 mA (24 V DC)  External digital output for LEDs 5 m/ CANopen CiA DS 301, SAE J1939 (b)	pased on) or CANop					E313 1
Supply volt Idle current Current car Protocol Baud rate	t consumption	80 mA (24 V DC)  External digital output for LEDs 5 m/ CANopen CiA DS 301, SAE J1939 (b)	pased on) or CANop					E313 1
Supply voltildle current car Current car Protocol Baud rate  CAN - 5 analoge	t consumption rrying capacity	80 mA (24 V DC)  External digital output for LEDs 5 m/ CANopen CiA DS 301, SAE J1939 (b)	pased on) or CANop					E313 1
Supply volt. Idle current Current car Protocol Baud rate  CAN - 5 analoge - 24 digital j	t consumption rrying capacity	80 mA (24 V DC) External digital output for LEDs 5 m/ CANopen CiA DS 301, SAE J1939 (b) 20 kBit/s to 1 Mbit/s (standard 250 l)	pased on) or CANop					E313 1
Supply volt. Idle current Current car Protocol Baud rate  CAN - 5 analoge - 24 digital j	t consumption rrying capacity joystick axis joystick functions	80 mA (24 V DC) External digital output for LEDs 5 m/ CANopen CiA DS 301, SAE J1939 (b) 20 kBit/s to 1 Mbit/s (standard 250 l)	pased on) or CANop					
Supply volt. Idle current Current car Protocol Baud rate  CAN - 5 analoge - 24 digital j	t consumption rrying capacity joystick axis joystick functions with 16 LED-outputs	80 mA (24 V DC) External digital output for LEDs 5 m/ CANopen CiA DS 301, SAE J1939 (b) 20 kBit/s to 1 Mbit/s (standard 250 l)	pased on) or CANop					
Supply volt. Idle current Current car Protocol Baud rate  CAN - 5 analoge - 24 digital j Additional v  CANopen S	t consumption rrying capacity joystick axis joystick functions with 16 LED-outputs	80 mA (24 V DC) External digital output for LEDs 5 m/ CANopen CiA DS 301, SAE J1939 (b) 20 kBit/s to 1 Mbit/s (standard 250 l)	pased on) or CANop					2
Supply volt. Idle current Current car Protocol Baud rate  CAN - 5 analoge - 24 digital j Additional v  CANopen S - 5 analog j	t consumption rrying capacity joystick axis joystick functions with 16 LED-outputs	80 mA (24 V DC) External digital output for LEDs 5 m/ CANopen CiA DS 301, SAE J1939 (b) 20 kBit/s to 1 Mbit/s (standard 250 l)	pased on) or CANop					2

Special / customer specified











The Palm Grip B30 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long). The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### **Technical data**

Operating temperature -40°C to +85°C

Degree of protection Control element up to IP67

Contact complement 1,5A 24 V DC 13 (\*1 0,1A 24 V DC13)

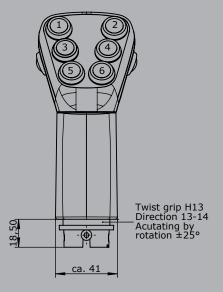


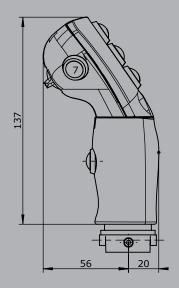
				Example					
	B	30	-2D	W	SR	SE	S12	H13	-X
Basic	ta								
B30	Palm Grip								
Digita	al actuating element								
D	Push Button KDA21 *1								
	Colour: red, black, yellow, green, blue, white, orange								
HD	Hall-Push Button (see page 151)								
W	Rocker switch momentary (T) or maintained (R), colours: red, black, ye white Mechanical functions: T-0-T, 0-T, R-0-T, R-0-R, 0-R, R-R	ellow, b	lue,						
SR	Sliding switch R-O-R								
ST	Sliding switch T-0-T								
SE	Sensor Button capacitive with external control electronics								
S	Sensor Button capacitive without external control electronics								
	(Consistent with V85 / VV85 with interface E1xx to E6xx, E907 and V25	5/V27 \	with inte	rfaces E3xx	( + E4xx+E	907)			
Analo	og actuating element								
S12	Thumbwheel, output 0,52,54,5 V inverse dual (see page 146)								
S16	Thumbwheel, output 0,52,54,5 V inverse dual (see page 149)								
V21	Mini-Joystick, output 0,52,54,5 V inverse dual (see page 137)								
НК	Hall-Cross Switch (see page 143)								
H13	Hall-Rotary Grip								
	Output 0,52,54,5 V inverse dual								
	_								
Speci	ial model								
Χ	Special / customer specified								

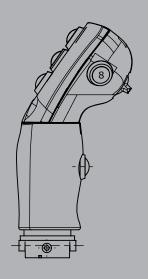


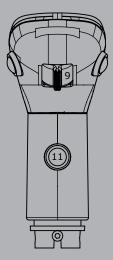


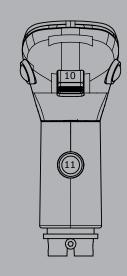
Push button installed Pos. 1 - 8 +11 Rocker switch installed Pos. 9+10















Edition: installed Pos. 3+1 Sliding switch installed Pos. 2+4 Rocker switch



Edition: installed Pos. 2+4 Multi-axis controller V21 installed Pos. 5+6 Rocker switch









The Palm Grip B29 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire  $(0,1 \text{ mm}^2, 450 \text{ mm long})$ . The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### **Technical data**

Operating temperature

Degree of protection

Contact complement

-40°C to +85°C

Control element up to IP67

0,1A 24 V DC13



Example B29 -2D -X

#### Basic unit

B29 Palm Grip

#### Digital actuating element

D Push Button KDA21

Colour: red, black, yellow, green, blue, white, orange

HD Hall-Push Button (see page 151)

SE Sensor Button capacitive with external control electronics

S Sensor Button capacitive without external control electronics

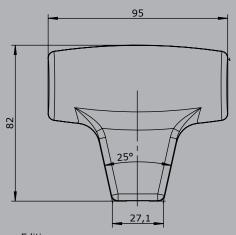
 $(Consistent\ with\ V85\ /\ VV85\ with\ interface\ E1xx\ to\ E6xx,\ E907\ and\ V25/V27\ with\ interfaces\ E3xx\ +\ E4xx+E907)$ 

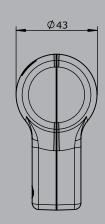
#### Special model

X Special / customer specified

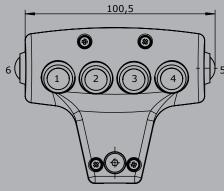


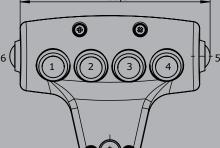
### **B29**



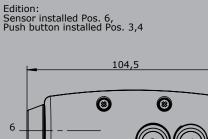


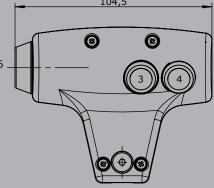
Edition: Push button installed Pos. 1-6

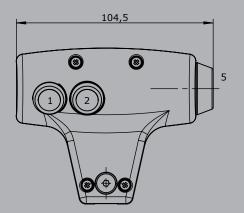




Edition: Sensor installed Pos. 5, Push button installed Pos. 1,2













The Palm Grip B28 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire  $(0,1 \text{ mm}^2, 450 \text{ mm long})$ . The mounting piece for the drive rod can be supplied with a tapped hole 10 mm (standard).

#### **Technical data**

Operating temperature -40°C to +85°C
Degree of protection up to IP54

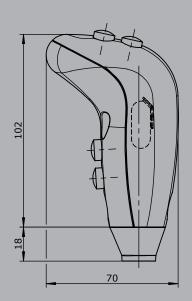
Special / customer specified

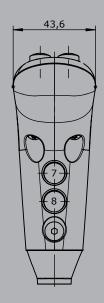


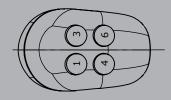
		E	Example		
		B28	-2D	SE	-X
Basic	unit				
B28	Palm Grip				
Digit	al actuating element				
D	Push Button (1,5A 24 V DC13)				
	Colour: red, black, yellow, green, blue, grey				
SE	Sensor Button capacitive with external control electronics				
S	Sensor Button capacitive without external control electronics				
	(Consistent with V85 / VV85 with interface E1xx to E6xx, E907 and V2	25/V27 with interfac	es E3xx + E4xx+E90	07)	
Spec	ial model				
	<u> </u>				



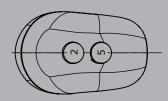
Edition: Push button installed Pos. 1,3,4,6,7,8 Sensor button function on left or right available



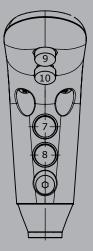




Edition: Push button installed Pos. 2,5,7,8 Sensor button function on left or right available



Edition: Push button installed Pos. 7,8,9,10 Sensor button function on left or right available









The Palm Grip B26 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long). The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### **Technical data**

Operating temperature -40°C to +85°C

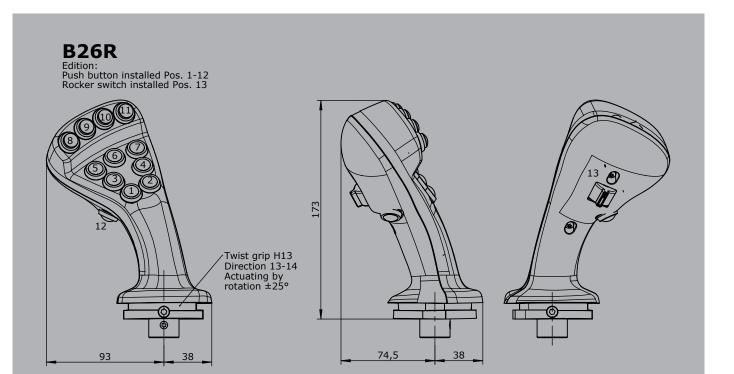
Degree of protection Control element up to IP67

Contact complement 1,5A 24 V DC 13 (\*1 0,1A 24 V DC13)



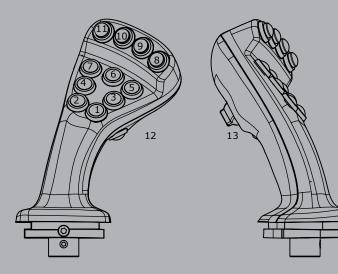
				mple					
		B26L	-2D	HD	W	S12	V21	H13	
Basic ı	unit								
B26L	Palm Grip left								
B26R	Palm Grip right								
Digital	l actuating element								
D	Push Button KDA21 *1								
	Colour: red, black, yellow, green, blue, white, orange								
HD	Hall-Push Button (see page 151)								
W	Rocker switch momentary (T) or maintained (R), colours: red, black, yellow Mechanical functions: T-0-T, 0-T, R-0-T, R-0-R, 0-R, R-R	ı, blue, v	white						
SR	Sliding switch R-O-R								
ST	Sliding Button T-O-T								
SE	Sensor Button capacitive with external control electronics								
S	Sensor Button capacitive without external control electronics								
	(Consistent with V85 / VV85 with interface E1xx to E6xx, E907 and V25/V2	27 with i	interface	s E3xx + E	4xx+E90	7)			
V	Vibration								
Analog	g actuating element								
S12	Thumbwheel, output 0,52,54,5 V inverse dual (see page 146)								
S16	Thumbwheel, output 0,52,54,5 V inverse dual (see page 149)								
V21	Mini-Joystick, output 0,52,54,5 V inverse dual (see page 137)								
НК	Hall-Cross Switch (see page 143)								
H13	Hall-Rotary Grip								
	Output 0,52,54,5 V inverse dual								
Specia	al model								
Χ	Special / customer specified								



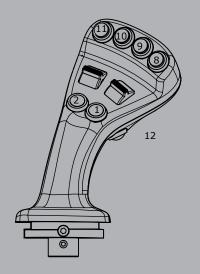


### **B26L**

Edition: Push button installed Pos. 1-12 Rocker switch installed Pos. 13



Edition: Push button installed Pos. 1+2, 8-12 Rocker switch installed Pos. 3+5, 4+7



Technical details may vary based on configuration or application! Technical data subject to change without notice!







The Palm Grip B25 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long). The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### **Technical data**

-40°C to +85°C Operating temperature

Degree of protection Control element up to IP67

Contact complement 1,5A 24 V DC 13 (\*1 0,1A 24 V DC13)



Example

W

B<sub>25</sub>L -2D SE V21 H13 -X Basic unit B25L Palm Grip left B25R Palm Grip right Digital actuating element Push Button KDA21 \*1 D Colour: red, black, yellow, green, blue, white, orange HD Hall-Push Button (see page 151) Rocker switch momentary (T) or maintained (R), colours: red, black, yellow, blue, white W Mechanical functions: T-0-T, 0-T, R-0-T, R-0-R, 0-R, R-R К SR Sliding switch R-O-R ST Sliding switch T-0-T SE Sensor Button capacitive with external control electronics S Sensor Button capacitive without external control electronics (Consistent with V85 / VV85 with interface E1xx to E6xx, E907 and V25/V27 with interfaces E3xx + E4xx+E907) Vibration Analog actuating element Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 146) S16 Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 149) V21 Mini-Joystick, output 0,5...2,5...4,5 V inverse dual (see page 137) НК Hall-Cross Switch (see page 143) H13 Hall-Rotary Grip, Output 0,5...2,5...4,5 V inverse dual CAN Supply voltage 9-32 V DC Idle current consumption 80 mA (24 V DC) Current carrying capacity External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs) Protocol CANopen CiA DS 301, SAE J1939 (based on) or CANopen Safety EN50325-5 Baud rate 20 kBit/s to 1 Mbit/s (standard 250 kBit/s) CAN E313 1 CANopen Safety E4121 - 5 analoge joystick axis - 5 analog joystick axis

- 24 digital joystick functions

2 Additional with 16 LED-outputs

Technical details may vary based on configuration or application! Technical data subject to change without notice!

- 24 digital joystick functions

Special model

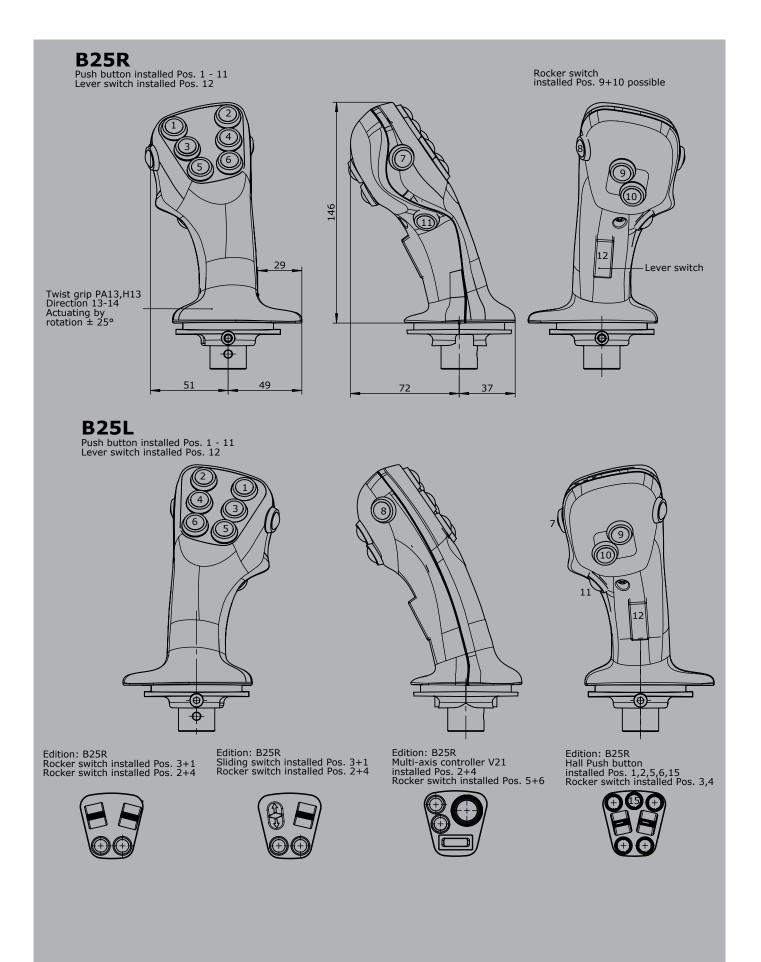
Χ

Additional with 16 LED-outputs

Special / customer specified

2











The Palm Grip B24 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The superior grip surface is framed by an illuminated coloured ring element. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long). The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### **Technical data**

Operating temperature -40°C to +85°C

Degree of protection Control element up to IP67

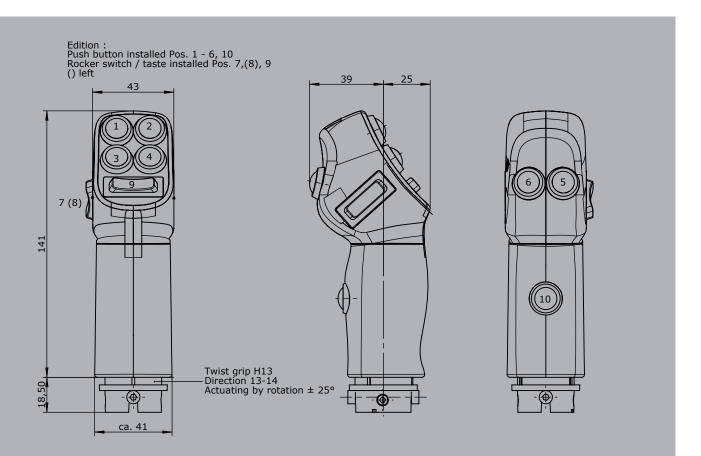
Contact complement 1,5A 24 V DC13 (\*1 0,1A 24 V DC13)



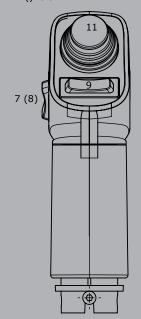
Example -IWH **B24** -D 2W V21 -X **Basic unit** B24 Palm Grip Digital actuating element Push Button KDA21 \*Б Colour: red, black, yellow, green, blue, white, orange W Rocker switch T-0-T W Rocker switch 0-T W Rocker switch R-0-T W Rocker switch R-0-R W Rocker switch 0-R W Rocker switch R-R SE Sensor Button capacitive with external control electronics S Sensor Button capacitive without external control electronics (Consistent with V85 / VV85 with interface E1xx to E6xx, E907 and V25/V27 with interfaces E3xx + E4xx+E907) Analog actuating element V21 Mini-Joystick, output 0,5...2,5...4,5 V inverse dual (see page 137) H13 Hall-Rotary Grip Output 0,5...2,5...4,5 V inverse dual **Additional option IWH** Colour ring white, illuminated **IRD** Colour ring red, illuminated IBL Colour ring blue, illuminated WH Colour ring white RD Colour ring red BL Colour ring blue GN Colour ring green Colour ring yellow YΕ Special model

Special / customer specified





Edition:
Push button installed Pos. 5,6,10
Rocker switch / taste Pos. 7,(8), 9
multi-axis controller V21 Pos. 11
() left









The Palm Grip B23 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long). The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### Technical data

Operating temperature -40°C to +85°C

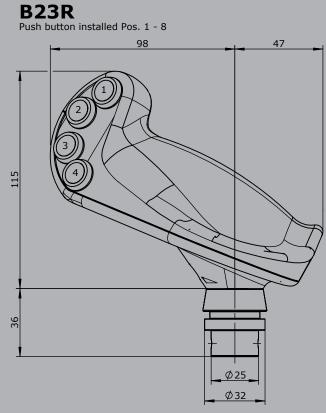
Degree of protection Control element up to IP67

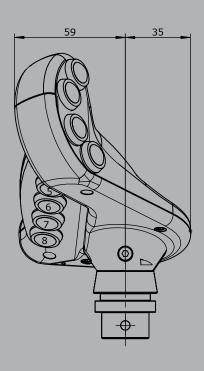
Contact complement 1,5A 24 V DC13 (\*1 0,1A 24 V DC13)

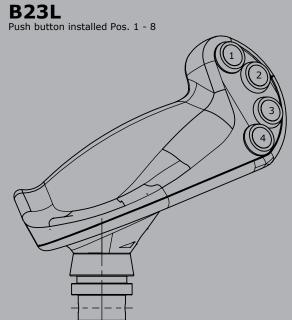


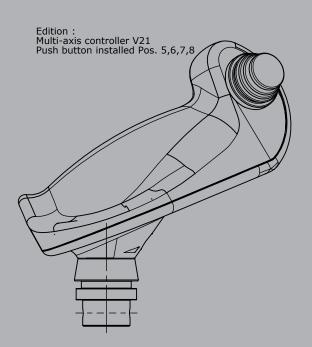
			Example	e		
		B23R	-2D	w	V21	-X
Basic	unit					
B23L	Palm Grip left					
B23R	Palm Grip right					
Digita	l actuating element					
D	Push Button KDA21 *1					
	Colour: red, black, yellow, green, blue, white, orange					
HD	Hall-Push Button (see page 151)					
W	Rocker switch momentary (T) or maintained (R), colours: Mechanical functions: T-0-T, 0-T, R-0-T, R-0-R, 0-R, R-R	red, black, yellow,	blue, white			
Analo	g actuating element					
S12	Thumbwheel, output 0,52,54,5 V inverse dual (see pa	nge 146)				
S16	Thumbwheel, output 0,52,54,5 V inverse dual (see pa	nge 149)				
V21	Mini-Joystick, output 0,52,54,5 V inverse dual (see page	ge 137)				
НК	Hall-Cross Switch (see page 143)					
Specia	al model					
Χ	Special / customer specified					

















The Palm Grip B22 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long). The mounting piece for the drive rod can be supplied with a tapped hole 7 mm.

#### Technical data

Operating temperature -40°C to +85°C

Degree of protection Control element up to IP67

Contact complement 1,5A 24 V DC13 (\*1 0,1A 24 V DC13)

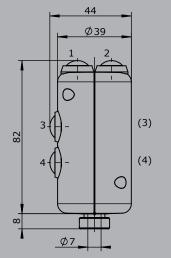


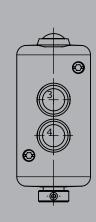
			Example		
		B22AL	-4D	W	-X
Basic uni	it				
322L	Palm Grip left				
322R	Palm Grip right				
B22AL	Palm Grip left with support				
B22AR	Palm Grip right with support				
Digital ad	ctuating element				
)	Push Button KDA21 *1				
	Colour: red, black, yellow, green, blue, white, orange				
HD	Hall-Push Button (see page 151)				
<b>N</b> *	Rocker switch T-0-T				
<b>N</b> *	Rocker switch 0-T				
<b>N</b> *	Rocker switch R-0-T				
<b>N</b> *	Rocker switch R-0-R				
<b>N</b> *	Rocker switch 0-R				
<b>N</b> *	Rocker switch R-R				
	*Only possible with version with support!				
SE	Sensor Button capacitive with external control electronics	;			
5	Sensor Button capacitive without external control electron	nics			
	(Consistent with V85 / VV85 with interface E1xx to E6xx,	F907 and V25/V27 w	vith interfaces F3xx + F	4xx+E907)	



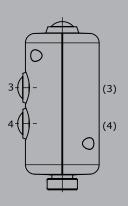
**B22** 

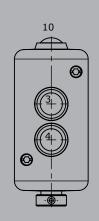
Edition: Push button installed Pos. 1,2,3,4 Position push button left hand ()





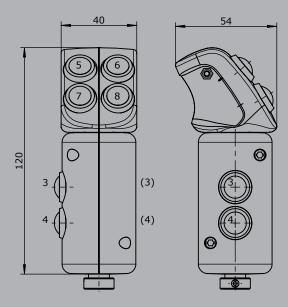
Edition: Push button installed Pos. 3,4,10 Position push button left hand ()



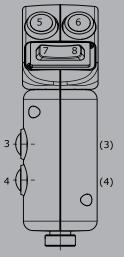


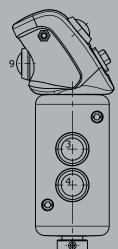
**B22A** 

Editon: Push button installed Pos. 3,4,5,6,7,8 Position push button left hand ()



Edition: Push button installed Pos. 3,4,5,6,9 Rocker switch installed Pos. 7-8 Position push button left hand ()











The Palm Grip B20 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long). The mounting piece for the drive rod can be supplied with a tapped hole 12 mm.

#### **Technical data**

Operating temperature

Degree of protection

Contact complement

-40°C to +85°C

Control element up to IP67

1,5A 24 V DC13 (\*1 0,1A 24 V DC13)



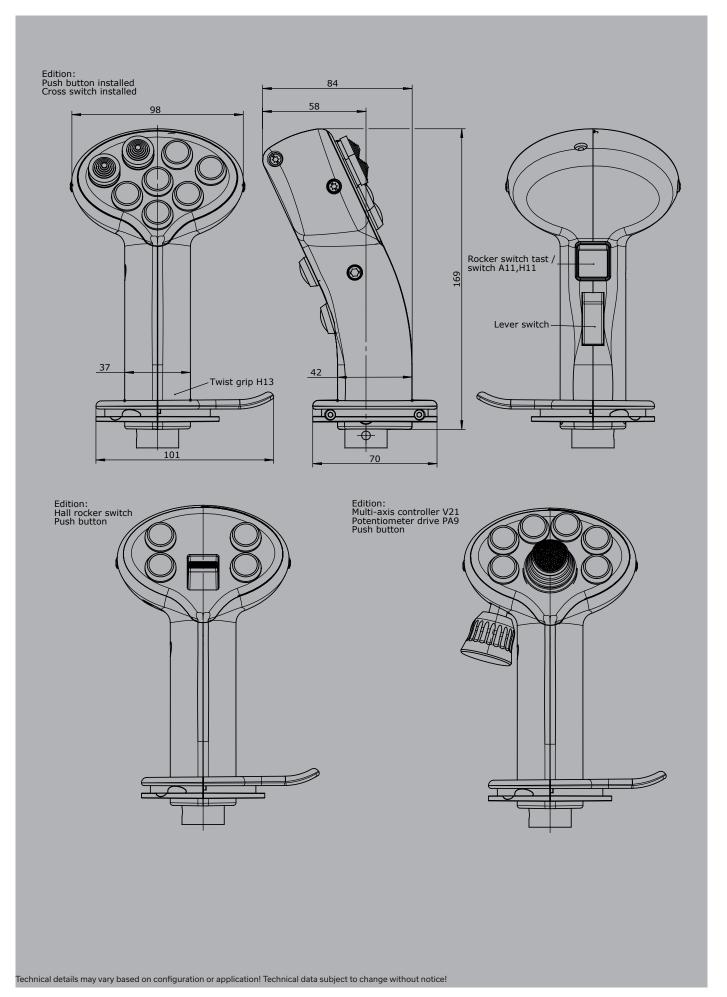
Example B<sub>2</sub>0L -2D w К V21 H13 -X Basic unit B20L Palm Grip left with hand pad B20R Palm Grip right with hand pad Digital actuating element Push Button KDA21 \*1 Colour: red, black, yellow, green, blue, white, orange HD Hall-Push Button (see page 151) Rocker switch momentary (T) or maintained (R), colours: red, black, yellow, blue, white Mechanical functions: T-0-T, 0-T, R-0-T, R-0-R, 0-R, R-R W К SE Sensor Button capacitive with external control electronics S Sensor Button capacitive without external control electronics (Consistent with V85 / VV85 with interface E1xx to E6xx, E907 and V25/V27 with interfaces E3xx + E4xx+E907) Analog actuating element S12 Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 146) S16 Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 149) V21 Mini-Joystick, output 0,5...2,5...4,5 V inverse dual (see page 137) НК Hall-Cross Switch (see page 143) P9 Thumbwheel with potentiometer H13 Hall-Rotary Grip Output 0,5...2,5...4,5 V inverse dual Special model

AL		_1_	~~	
At	r: I	04 E	en	16

Special / customer specified

-			
ı	Z01	Bellow KMD 109	10300009
ı	Z02	Bellow KMD 190	10300093
ı	Z03	Rosette KBF 905 with 4 screws M5 x 15 necessary for bellow KMD 190	5209900404











The Palm Grip B14/B15 has different equipment options for many requirements. It is compatible with our Multi-axis and Single-axis controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long). The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

### Technical data

Operation temperature -40°C to +85°C

Degree of protection Control element up to IP67

Contact complement 0,1A 24 V DC13



Example

B14 -2D -X

#### Basic unit

B14 Palm Grip left

B15 Palm Grip right

#### Digital actuating element

D Push Button KDA21 (0,1A 24 V DC13)

Colour: red, black, yellow, green, blue, white, orange

#### Special model

X Special / customer specified

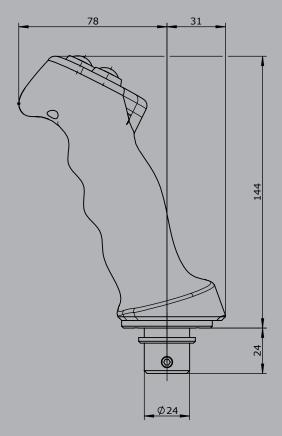
# Palm Grip B14/B15



**B14**Push button installed Pos. 1,2



**B15**Push button installed Pos. 1,2











The Palm Grip B10 has different equipment options for many requirements. It is compatible with our Double-handle controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (0,1 mm², 450 mm long). The mounting piece for the drive rod can be supplied with a tapped hole 10 mm.

#### **Technical data**

Operating temperature

Degree of protection

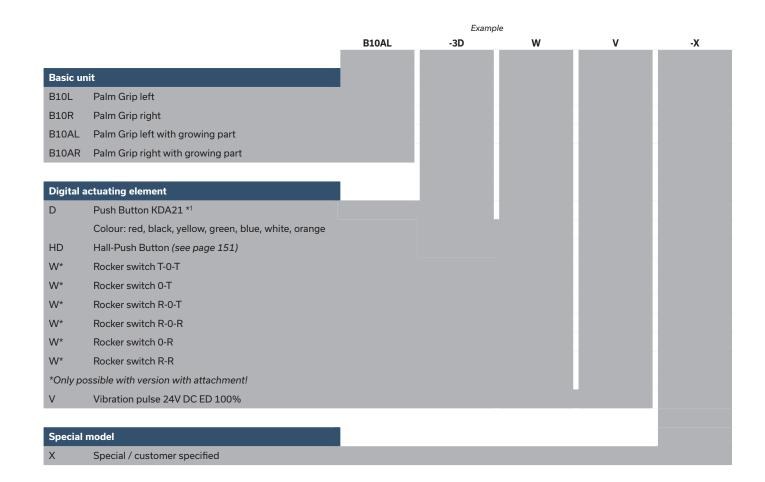
Contact complement

-40°C to +85°C

Control element up to IP67

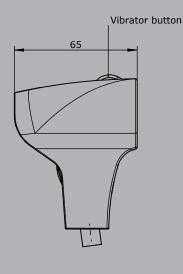
1,5A 24 V DC13 (\*1 0,1A 24 V DC13)

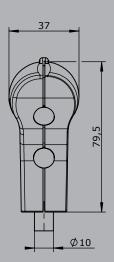




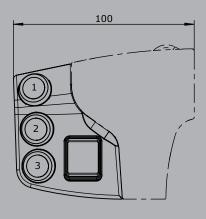


### **B10**

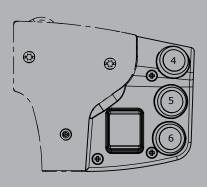




**B10A**Edition installed left:
Push button installed Pos. 1,2,3
Rocker switch



Edition installed right: Push button installed Pos. 4,5,6 Rocker switch









The Palm Grip B9 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire  $(0.1 \text{ mm}^2, 450 \text{ mm} \text{ long})$ . The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### **Technical data**

Operating temperature -40°C to +85°C

Degree of protection IP54

Contact complement 1,5A 24 V DC13



	1	B9	-2D	КТ	A13	PA11	PA13	-X
Basic (	unit							
B9	Palm Grip							
Digital	l actuating element							
D	Push Button							
	Colour: red, black, yellow, green, blue, white							
KT	Cross switch T-0-T / T-0-T							
KR	Cross switch R-0-R / R-0-R							
A11	Rocker switch T-0-T Pos. 11 + 12							
A11	Rocker switch R-0-R Pos. 11 + 12							
A13	Rotary Grip T-0-T							
Analog	g actuating element							
V21	Mini-Joystick, output 0,52,54,5 V inverse dual (see page 137)							
PA11	Rocker analog Pos. 11 + 12							
	Potentiometer T394 2 x 5 kOhm with direction contacts							
H11	Rocker analog Pos. 11 + 12							
	Hall-Potentiometer							
	Output 0,52,54,5 V inverse dual							
PA13	Rotary Grip							
	Potentiometer T375 2 x 5 kOhm with direction contacts							
H13	Hall-Rotary Grip							
	Output 0,52,54,5 V inverse dual							

At	ta	ch	III	er	nts

Special / customer specified

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ш	n	Δ	n	n	

Zuber	Zubenor					
Z01	Bellow KMD 109	10300009				
Z02	Bellow KMD 190	10300093				
703	Rosette KRE 905 with 4 screws M5x15 necessary for hellow KMD 190	5209900404				

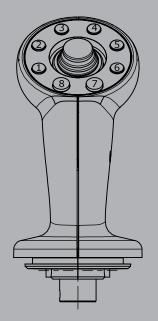


Edition:
Push button installed Pos. 1 - 8
Cross switch tast

Rocker PAII, AII, HII
Direction 11-12

Twist grip PAI3, HI3
Direction 13-14
Actuating by rotating ± 25°

Edition:
Push button installed Pos. 1 - 8
Multi-axis controller V21









The Palm Grip B7 / B8 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire  $(0,1~\text{mm}^2,450~\text{mm}\,\text{long})$ . The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### **Technical data**

Operating temperature

Degree of protection

Contact complement

-40°C to +85°C

Control element up to IP67

1,5A 24 V DC13 (\*1 0,1A 24 V DC13)



Example

		В/	-20	VV	ĸ	3E	39	PA13	-X
Basic	unit								
B7	Palm Grip left								

#### Digital actuating element

Palm Grip right

D Push Button

В8

Colour: red, black, yellow, green, white, orange

D Push Button KDA21 \*1

Colour: red, black, yellow, green, blue, white, orange

HD Hall-Push Button (see page 151)

Rocker switch momentary (T) or maintained (R), colours: red, black, yellow, blue,

W white

Mechanical functions: T-0-T, 0-T, R-0-T, R-0-R, 0-R, R-R

K Lever switch

A13 Rotary Grip T-0-T

SE Sensor Button capacitive with external control electronics

S Sensor Button capacitive without external control electronics

 $(Consistent\ with\ V85\ /\ VV85\ with\ interface\ E1xx\ to\ E6xx,\ E907\ and\ V25/V27\ with\ interfaces\ E3xx\ +\ E4xx+E907)$ 

V Vibrator

Impulse 24 V DC ED 100%

#### Analog actuating element

S12 Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 146)

S16 Thumbwheel, output 0,5...2,5...4,5 V inverse dual (see page 149)

V21 Mini-Joystick, output 0,5...2,5...4,5 V inverse dual (see page 137)

HK Hall-Cross Switch (see page 143)

PA13 Rotary Grip

Potentiometer T375 2 x 5 kOhm with direction contacts

H13 Hall-Rotary Grip

Output 0,5...2,5...4,5 V inverse dual

#### Special model

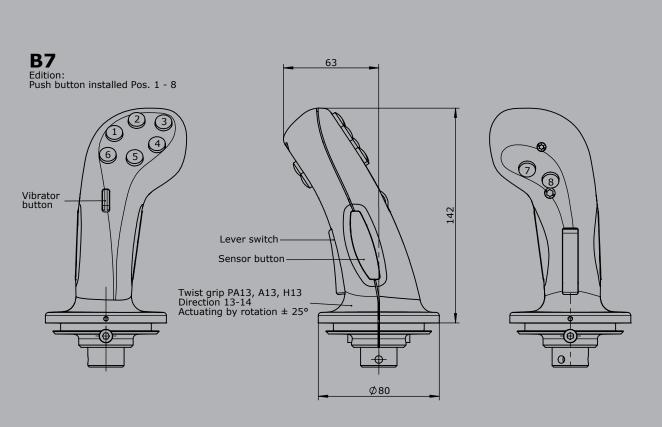
X Special / customer specified

A .		100			٠.
JΑ	tac	911	ш	ЭH	TE

Z01	Bellow KMD 109	10300009
Z02	Bellow KMD 190	10300093
Z03	Rosette KBF 905 with 4 screws M5x15 necessary for bellow KMD 190	5209900404



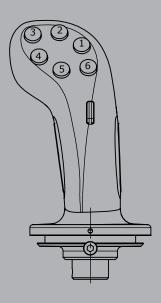


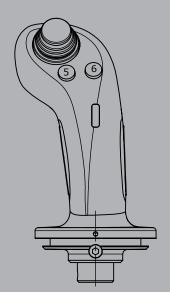


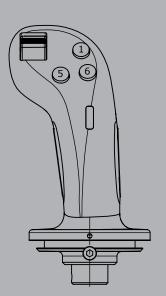
**B8**Editon:
Push button installed Pos. 1 - 8

Edition: Multi-axis controller V21 Push button installed Pos. 5,6,7,8

Edition: Hall Rocker switch Push button installed Pos. 1,5,6,8







Technical details may vary based on configuration or application! Technical data subject to change without notice!







The Palm Grip B6 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible cable (4 respectively 8 x 0,25 mm², 450 mm long). The mounting piece can be supplied with a tapped hole M10 (standard) or M8.

#### **Technical data**

Operating temperature -40°C to +85°C

Degree of protection IP54

Contact complement 1,5A 24 V DC13

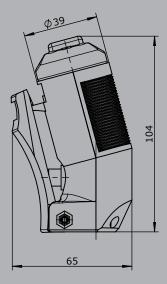


		B6	-2D	К	-X
Bas	ic unit				
В6	Palm Grip				
Digi	ital actuating element				
D	Push Button top				
W	Rocker switch top T-0-T				
W	Rocker switch top R-0-T				
W	Rocker switch top R-0-R				
K*	Lever switch				
	* Included with the delivery of Palm Grip B6!				
Spe	cial model				
Χ	Special / customer specified				

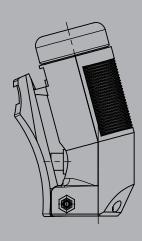




**B6**Edition:
Lever switch side
Rocker switch installed top



Edition: Lever switch side Push button top



Technical details may vary based on configuration or application! Technical data subject to change without notice!







The Palm Grip B5 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire (4 respectively  $8 \times 0.25 \text{ mm}^2$ , 450 mm long). The mounting piece can be supplied with a tapped hole M10 (standard) or M8.

#### **Technical data**

Operating temperature -40°C to +85°C

Degree of protection IP54

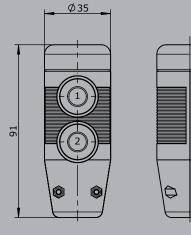
Contact complement 3A 24 V DC13 (\*1 1,5A 24 V DC13)



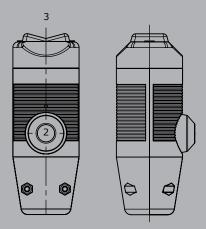
		Example			
		B5	-2D	W	-X
Basi	c unit				
B5	Palm Grip				
Digi	tal actuating element				
D	Push Button top				
D	Push Button side *5				
W	Rocker switch top T-0-T				
W	Rocker switch top R-0-T				
W	Rocker switch top R-0-R				
Т	Push Button top mechanical operation (Only possible in combination with Multi-Axis Controller or single-axis controller!)				
Spec	cial model				
Χ	Special / customer specified				



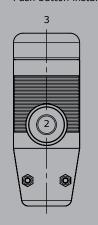
Edition: Push button installed Pos. 1,2

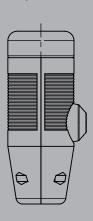


Edition: Rocker switch installed Pos. 3 Push button installed Pos. 2



Edition: Push button installed Pos. 2,3





0







The Palm Grip B3 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible single wire  $(0,1~\text{mm}^2,450~\text{mm} \,\text{long})$ . The mounting piece can be supplied with a tapped hole 12 mm (standard) or 10 mm.

#### Technical data

Operating temperature

Degree of protection

-40°C to +85°C

Control element up to IP67

Contact complement 1,5A 24 V DC 13 (\*1 0,1A 24 V DC13)



				Example					
		В3	-2D	w	К	SE	PA11	PA13	-X
Basic ı									
B3	Palm Grip								
	actuating element								
D	Push Button								
	Colour: red, black, yellow, green, blue, grey								
D	Push Button KDA21 *1								
	Colour: red, black, yellow, green, blue, white, orange								
W	Rocker switch T-0-T								
W	Rocker switch 0-T								
W	Rocker switch R-0-T								
W	Rocker switch R-0-R								
W	Rocker switch 0-R								
W	Rocker switch R-R								
К	Lever switch								
SR	Sliding switch								
ST	Sliding switch								
ZD	Push Button with 2 steps								
A12	Push Button Pos. 11-12								
A11	Thumbwheel T-0-T								
A11	Thumbwheel R-0-R								
	L left, R right								
A13	Rotary Grip T-0-T								
	Sensor Button capacitive								
SE	The state of the s								
SE S	Sensor Button capacitive without external control electronics								
		nd V25/V2	27 with int	erfaces E3	Sxx + E4xx	(+E907)			

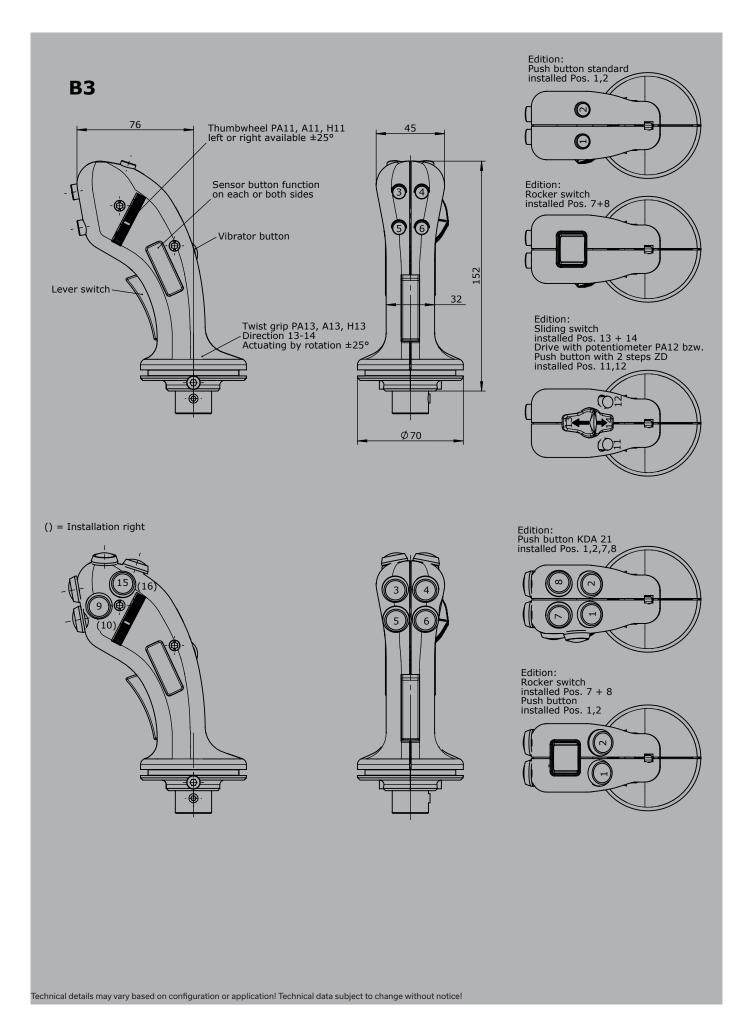




		B3L	-2D	W	К	SE	PA11R	PA13	-X
Andre	and a street and a second						-		
	actuating element								
PA11	Thumbwheel								
	Potentiometer T375 2 x 5 kOhm with direction contacts								
H11	Thumbwheel								
	Hall-Potentiometer								
	Output 0,52,54,5 V inverse dual								
	L left, R right								
PA12	Push Button analog Pos. 11+12								
	Potentiometer T375 2 x 5 kOhm with direction contacts								
H12	Push Button analog Pos. 11+12								
	Hall-Potentiometer								
	Output 0,52,54,5 V inverse dual								
PA13	Rotary handle								
	Potentiometer T375 2 x 5 kOhm with direction contacts								
H13	Hall-Rotary handle								
	Output 0,52,54,5 V inverse dual								
Special	model								
X	Special / customer specified								

Attachments						
Z01	Bellow KMD 109	10300009				
Z02	Bellow KMD 190	10300093				
Z03	Rosette KBF 905 with 4 screws M5 x 15 necessary for bellow KMD 190	520990004				











The Palm Grip B2 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible cable (8 x 0,25 mm $^2$ , 450 mm long). He can be tilted in any direction by 20 degrees and can lock in this position. The mounting piece can be supplied with a tapped hole M10 (standard) or M8.

#### **Technical data**

Operating temperature -40°C to +85°C

Degree of protection IP54

Contact complement 1,5A 24 V DC13 (\*1 0,1A 24 V DC13)



 B2
 -2D
 PA15
 -X

 Basic unit

 B2
 Palm Grip

Example

#### Digital actuating element

D Push Button KDA/70

D Push Button KDA21 \*1

Colour: red, black, yellow, green, blue, white, orange

HD Hall-Push Button (see page 151)

A15 2 push Button Pos. 1 + 2 interlocked

#### **Analog actuating element**

PA15 Push Button analog Pos. 1 + 2

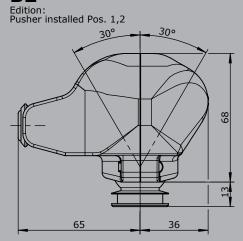
2 potentiometer T301 2 x 5 kOhm with direction contacts

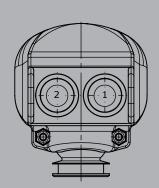
#### Special model

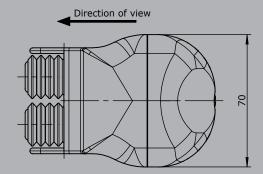
X Special / customer specified



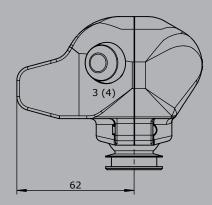
**B2** 



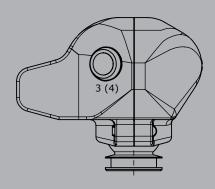




Edition: Push button KDA / 70 installed Pos. 1,2,3,4



Edition: Push button KDA 21 installed 1,2,3,4









The Palm Grip B1 has different equipment options for many requirements. It is compatible with our Multi-Axis Controller or mounted on hydraulic drives. The Palm Grip has a highly flexible cable (4 respectively 8 x 0,25 mm², 450 mm long). The mounting piece can be supplied with a tapped hole M10 (standard) or M8.

#### **Technical data**

Operating temperature -40°C to +85°C

Degree of protection IP54

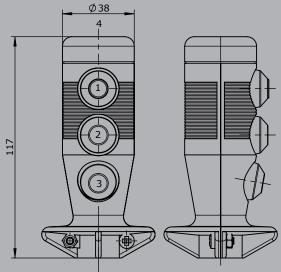
Contact complement 3A 24 V DC13 (\*1 1,5A 24 V DC13)



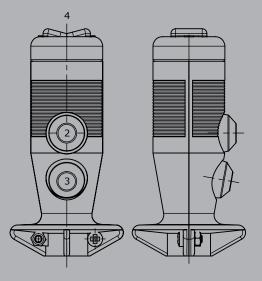
			Example		
		B1	-2D	W	-X
Bas	ic unit				
B1	Palm Grip				
		ı			
Dig	ital actuating element				
D	Push Button top				
D	Push Button side *1				
W	Rocker switch top T-0-T				
W	Rocker switch top R-0-T				
W	Rocker switch top R-0-R				
Т	Push Button top with mechanical operation				
	(Only possible with Multi-Axis Controller or single-axis controller!)				
К	Lever switch				
КТ	Lever switch mechanical operation				
	(Only possible with Multi-Axis Controller or single-axis controller!)				
Spe	cial model				
Х	Special / customer specified				



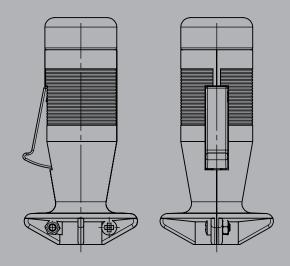
Edition: Push button installed Pos. 1,2,3,4



Edition: Rocker switch installed Pos. 4 Push button installed Pos. 2,3



Edition: Lever switch installed side



### Control Console



We designed the Control Console C1 to give our customers the maximum freedom of design and conguration options. The design has paid attention to a compact format, which can be extended with additional modules. The modular design allows individual assembly with joysticks, displays and command devices. The Control Console C1 is thus able to adapt perfectly to your product and your branding.

Standard colour: Housing bottom part: anthracite RAL 7016 Housing upper part: light grey RAL 7035

Insert plate: anthracite RAL 7016

#### Technical data:

Operation temperature -40°C to +85°C Horizontal adjustment +/-30 mm

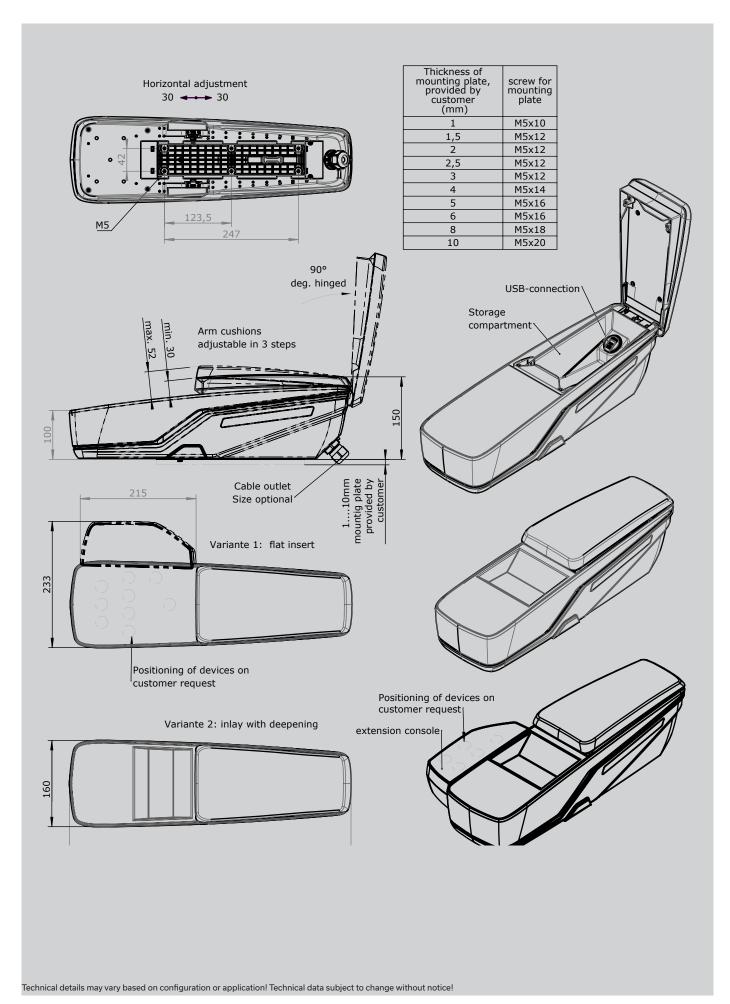


Example USB C1 -1 -1 -1 -0 -L1 **V27 KLS** X **Control Console** C1 160 x 520 mm Insert plate 1 Insert plate (flat) variant 1 2 Insert plate (with recess) variant 2 Colour housing upper part Light grey RAL 7035 1 Χ Desired colour (on request!) Colour decor stripes Desired colour (on request!) Illumination decor stripes 0 No illumination RGB-illumination left 1 2 RGB-illumination right 3 RGB-illumination left + right **Attachements USB** USB-plugin socket 2-fold, 2 x 2,5 A L1 Logo left 12 Logo right 13 Logo left incl. lighting L4 Logo right incl. lighting E1 Extension housing right D1 Display holder (Display on request) Mounting for equipment boxes ٧ Multi-Axis Controller (see page 1) Control-Switch (see page 113) More Control Elements (see page 137 and 243) Wiring KLS On connector or joystick per core KLK One side on cable per core Special model

Special / customer specified

### **Control Console**





### Foot Pedal



The Foot Pedal P20 is a rugged switching device for electro-hydraulic. A long service life and high reliability is ensured by the latest contactless hall-technology. Due to the modular construction and the different electrical interfaces it is universally applicable...

#### **Technical data**

Mechanical life P20

Operation temperature

Degree of protection P20

Functional safety

10 million operating cycles

-40°C to +85°C

IP67 (electronic)

PLd compatible (EN ISO 13849, complies SIL2 to DIN EN IEC 61508)





					Example			
			P20	-1	-ZZ	-E1041	-S	-X
	unit							
P20	Foot	Pedal						
<u> </u>			_					
Peda 1	11	Pedal shape A 0-15°						
2		Pedal shape B 0-25°						
3		Pedal shape C 15°-0-15°						
4		Pedal shape C 0-15°  Gearshift mounted on the left side						
	HL				_			
	HR	Gearshift mounted on the right side						
Ci								
Z	ng retui	ng return						
ZZ								
<b>ZZ</b>	Sprii	ng return redundant						
Inter	faces (d	description see on the following pages)						
E	0xx	Switching output						
E	1xx	Voltage output						
E	2xx	Current output						
E	Зхх	CAN-interface						
Е	4xx	CANopen Safety interface						
Plug	connec	ctors						
S	Stan	dard plug connectors (see page 120)						
Spec	ial mod	del						
Χ	Spec	ial / customer specified						





Digital output			
Supply voltage	9-32 V DC		
Current carrying capacity	Direction signal 150 mA		
	Zero position signal 500 mA		
Wiring	Cable 500mm long without plug connector		
	Optional with plug connector (standard plug connectors see page 120)		S
2 direction signals + 1 zero position signal (galvanically isolated)			
1 direction signal + 1 zero posit	E003 1		

Voltage output (not stabilized	)				
Supply voltage	4,75-5,25 V DC				
Current carrying capacity	Direction signal 8 mA				
Wiring	Cable 500mm long without plug connector				
Optional with plug connector (standard plug connectors see page 120)				S	
0,52,54,5 V redundant + 2 direction signals			E104 1		
0,52,54,5 V redundant + 1 c	lirection signal		E145 1		
		Output options			
		Characteristic:			
		Inverse dual		1	
		Dual		2	
		Inverse dual with dead zone +/- 3° (stand	lard)	3	
		Dual with dead zone +/- 3°		4	

Voltage output					
Supply voltage	9-32 V DC (*11,5-32 V)				
Current carrying capacity	Direction signal 150 mA				
	Zero position signal 500 mA				
Wiring	Cable 500mm long without plug connector				
	Optional with plug connector (standard plug connectors see page 120)			S	
0,52,54,5 V redundant + 2	2 direction signals + 1 zero position signal (galvanically isolated)		E112 1		
0,52,54,5 V redundant + 1	1 direction signal + 1 zero position signal (galvanically isolated)		E146 1		
0 5 10 V redundant + 2 dire	ection signals + 1 zero position signal (galvanically isolated), supply voltage 11,5 -	- 32 V DC	E132 1		
	ection signal + 1 zero position signal (galvanically isolated), supply voltage 11,5 - 3		E147 1		
10010 V + 2 direction signals + 1 zero position signal (galvanically isolated), supply voltage 11,5 - 32 V DC,					
sensor redundant with error r					
	Output options				
	Characteristic:				
	Inverse dual *1			1	
	Dual *1			2	
	Inverse dual with dea	ad zone +/- 3° *1 (s	tandard)	3	
	Dual with dead zone	+/- 3° *1		4	
	*1 not combinable wi	ith output E136X			
	Single *2			5	
	Single with dead zon	ne +/- 3° *2 (standa	rd)	6	
	*2 not combinable wi	ith output E1121 a	nd E1321,		
	E1461 und E1471				
Voltage output with other val	lue on request!				





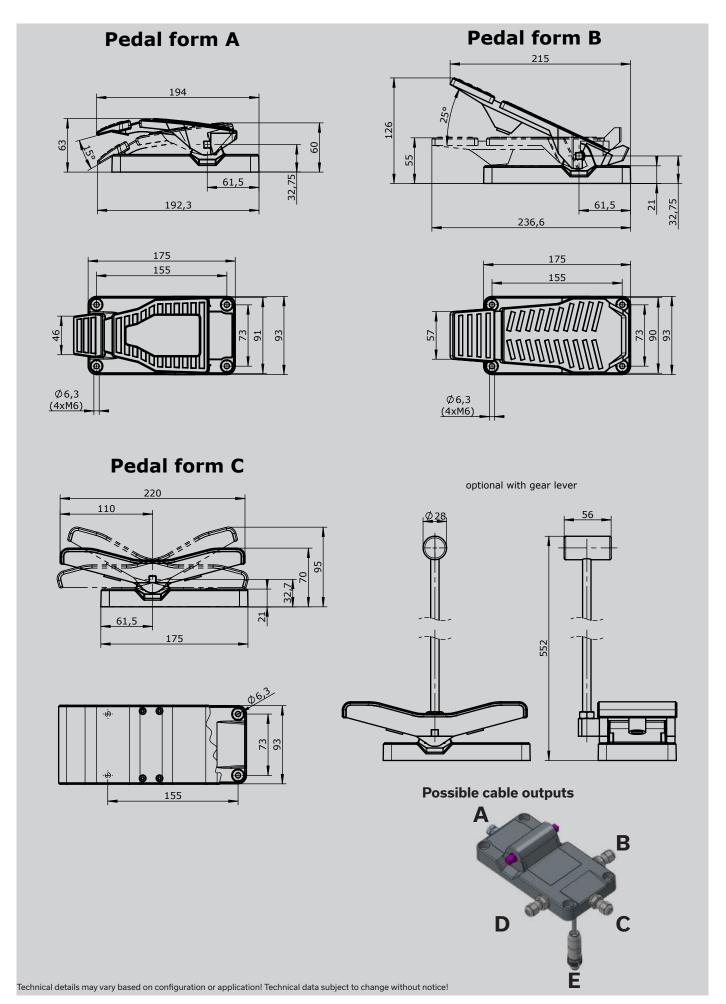
Current output			
Supply voltage	9-32 V DC		
Current carrying capacity	Direction signal 150 mA		
	Zero position signal 500 mA		
Wiring	Cable 500 mm long without plug connector		
	Optional with plug connector (standard plug connectors see page 120)		S
01020 mA + 2 direction sign	nals + 1 zero position signal (galvanically isolated), sensor redundant with error monitoring	E206 1	
and error signal			_
020 mA + 1 direction signal +	1 zero position signal (galvanically isolated), sensor redundant with error monitoring signal	E2221	
and error signal			
20020 mA + 2 direction sign	nals + 1 zero position signal (galvanically isolated), sensor redundant with error monitoring	E208 1	
and error signal			
41220 mA + 2 direction sign	nals + 1 zero position signal (galvanically isolated), sensor redundant with error monitoring	E2141	
and error signal			
420 mA + 1 direction signal +	1 zero position signal (galvanically isolated), sensor redundant with error monitoring	E223 1	
and error signal			
20420 mA + 2 direction sign	hals + 1 zero position signal (galvanically isolated), sensor redundant with error monitoring	E2161	
and error signal			
	Output options		
	Single		5
	Single with dead zone +/- 3° (standard)		6
Current output with other value	on request!		

CAN			
Supply voltage	9-36 V DC		
Idle current consumption	120 mA		
Current carrying capacity	Direction signal 100 mA		
Protocol	CANopen CiA DS 301 or SAE J 1939 (based on)		
Baud rate	125 kBit/s to 1 Mbit/s (standard 250 kBit/s)		
Wiring	CAN (IN) cable 500 mm with plug connector M12 (male)		
	CAN (OUT) cable 500 mm with plug connector M12 (female)		
CAN P20		E307 1	
With additional digital output s	separately wired (not via CAN)		
- 1 direction signal			2

CANopen Safety		
Supply voltage	9-36 V DC	
Idle current consumption	120 mA	
Current carrying capacity	Direction signal 100 mA	
Protocol	CANopen Safety EN50325-5	
Baud rate	125 kBit/s bis 1 MBit/s (standard 250 kBit/s)	
Wiring	CAN (IN) cable 500 mm with plug connector M12 (male)	
	CAN (OUT) cable 500 mm with plug connector M12 (female)	
CANopen Safety P20		E407 1
With additional digital outputs separately wired (not via CAN)		
- 1 direction signal		2

Attachments			
Z01 Mating connector M12 male insert with 2 m cable	20201140		
Z02 Mating connector M12 female insert with 2 m cable	20202298		





### Foot Pedal P10 / P11 / P12





The Foot Pedal P10 / P11 / P12 is a rugged switching device for electro-hydraulic. The modular design enables the switching device to be used universally. The P10/P11/P12 is resistant to oil, maritime, climate, ozone and UV radiation.

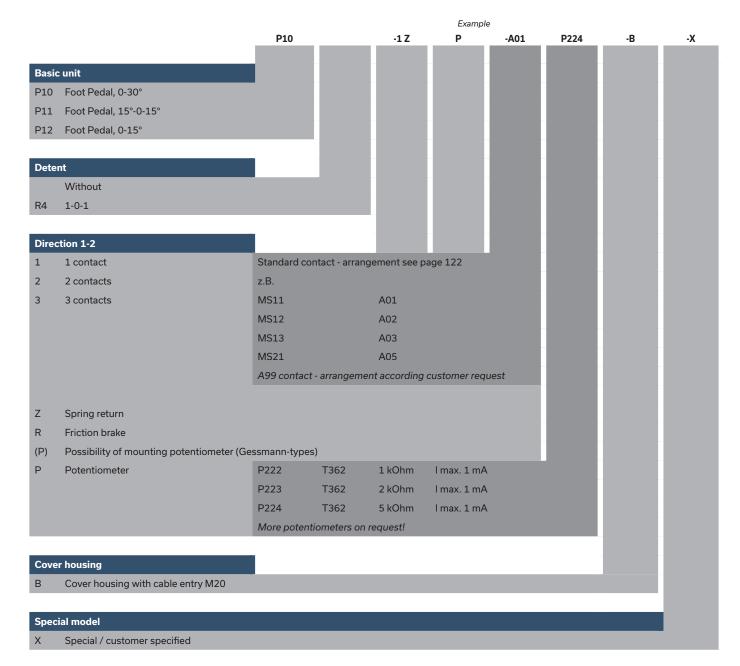
#### Technical data

Mechanical life P10 8 million operating cycles

Operation temperature -40°C to +85°C

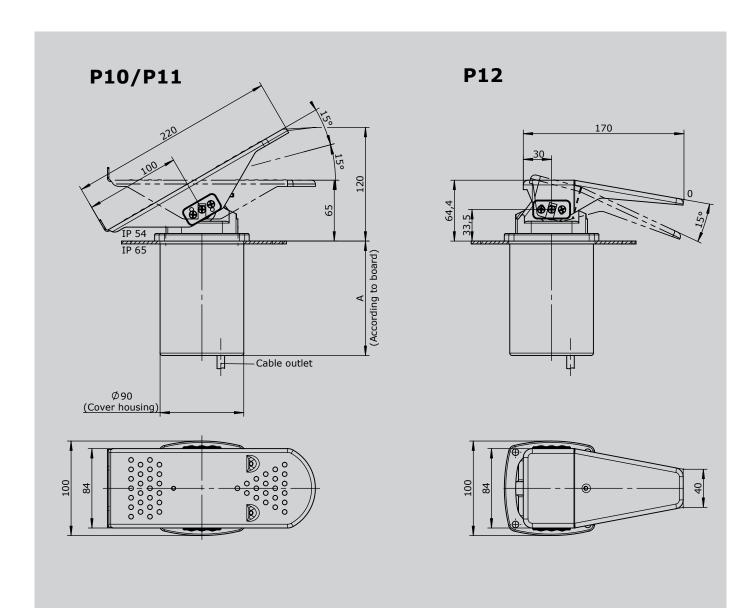
Degree of protection P10 IP66

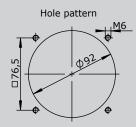












### Foot Pedal P8 / PP8



The Foot Pedal P8 / PP8 is a rugged switching devices for footing applications. The Foot Pedal is resistant to oil, maritime conditions e.g. offshore /vessels, UV radiation typically from the sun.

#### **Technical data**

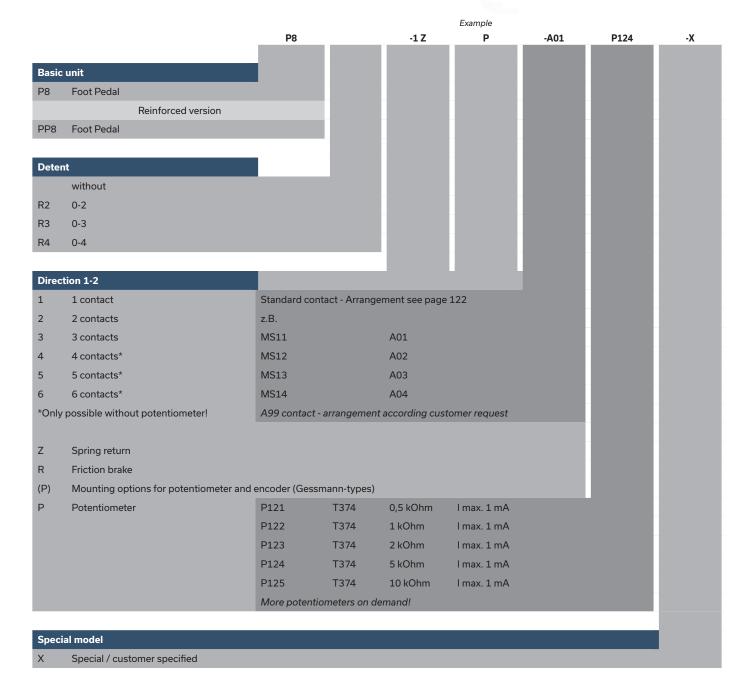
Mechanical life P86 million operating cyclesMechanical life PP810 million operating cycles

Operation temperature -40°C to +85°C

Degree of protection P8 IP54
Degree of protection PP8 IP65

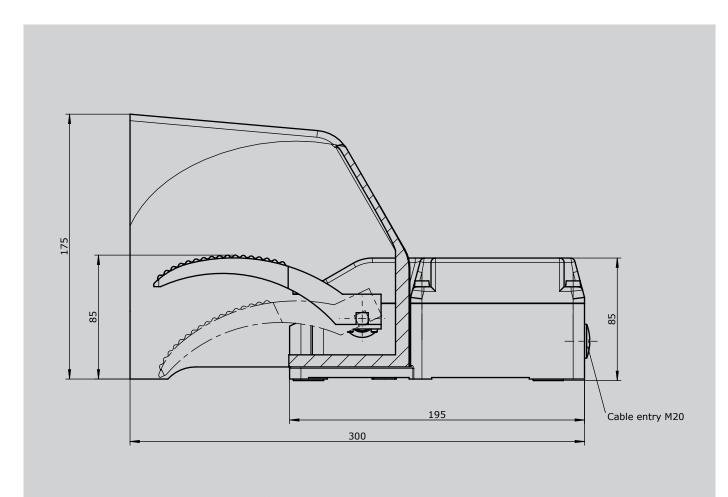
Colour RAL 7032 pebble-grey

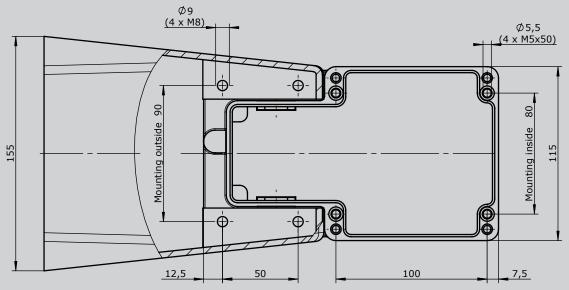












## Foot Pedal P7 / PP7



The Foot Pedal P7 / PP7 is a rugged switching devices for footing applications. The Foot Pedal is resistant to oil, maritime conditions e.g. offshore /vessels, UV radiation typically from the sun.

### **Technical data**

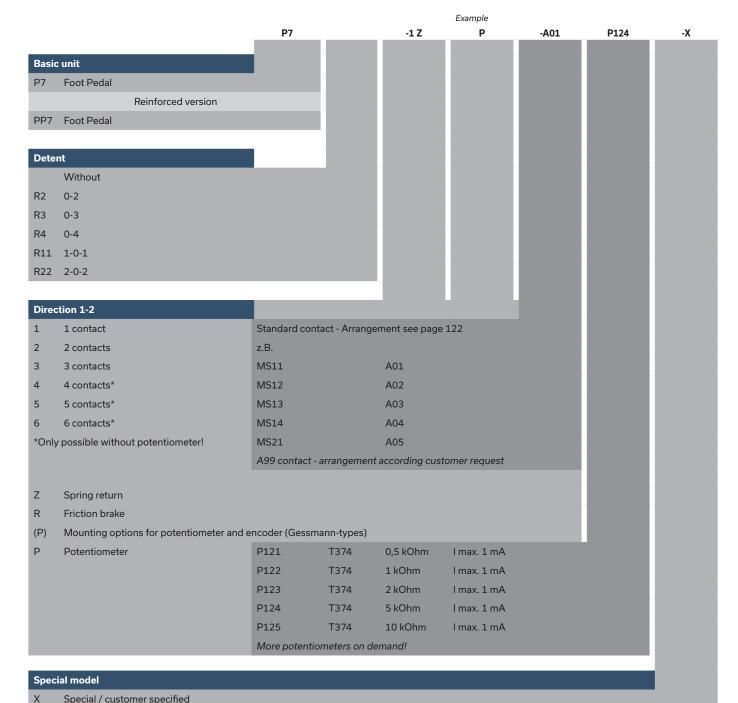
Mechanical life P76 million operating cyclesMechanical life PP710 million operating cycles

Operation temperature -40°C to +85°C

Degree of protection P7 IP54
Degree of protection PP7 IP65

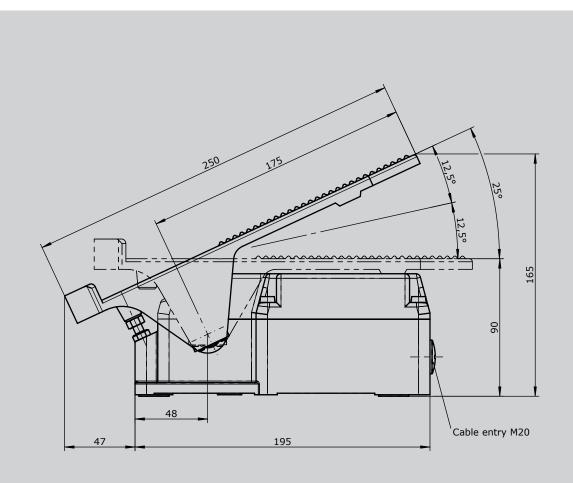
Colour RAL 7032 pebble-grey

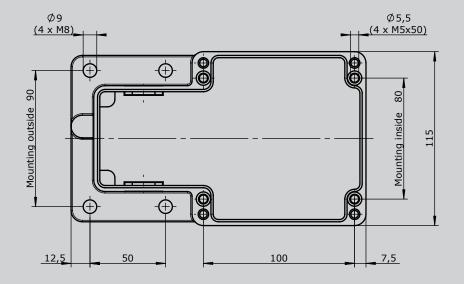












### **Control Unit** KST 31 swiveling





The KST31 is an ergonomically designed swiveling control chair which provides a high degree of comfort. The consoles, mounted to the Driver's Seat, swing with the seat. The consoles can be positioned to perfectly match any person by means of length, height and inclination adjustment. The standard version includes:

#### Consoles:

The plastic consoles can be equipped with custom command and indicating devices.

### Driver's Seat:

The comfortable Driver's Seat KFS 11 is equipped with a spring loaded hydraulic vibration absorption system, including weight adjustment, air-permeable textile cover, arm rests and head rest.

### Cross-member with swivel base:

The cover of the sheet steel cross-member including the Driver's Seat is forward foldable. Thereby all wirings, terminals and bushings are easily accessible during commissioning and maintenance. Swivel base has zero-tolerance bearings and rotation can be locked in 3° steps.

### Surface treatment:

Base coat and textured varnish

Standard colour RAL 7035 light grey in combination with RAL 7016 anthracite



Example

KST311 -U2 -M1 -F3 -LK / KFS 11 / V85 / V85 / KL / X

Basic unit	
KST311	Consoles 160x520 mm with insert plate (flat) variant 1
KST312	Consoles 160x520 mm with insert plate (with apsorption)
	variant 2

Base unit	
U2	Swiveling 180° left, 90° right with detent inc

U3 Electric swiveling 180° left, 90° right

U4 Non swiveling

A	
Attac	hments

M1	Monitor mounting with monitor housing
M2	Monitor mounting with monitor mounting bracket
МЗ	Monitor mounting without monitor housing/-mounting bracket
USB	USB-plug socket 2-fold, 1 x 1,5 A (mounted in the left storage compartment)
F3	Footrest KBF/716
Н	Heater 2 x 2 kW with ventilator
LK	Plate for horizontal manual adjustment for control units +/- 250 mm

cl. 2-step release

### Driver's Seat

KFS11\* (Included in the delivery!)

KFS9\*

KFS10\*

KFS12\*

\*Description see Driver's Seat page 251

V2021/1 01.01.2021





KST311 -U2 -M1 -F3 -LK / KFS 11 / V85 / V85 / KL / X

### Mounting for equipment boxes

- V... Multi-Axis Controller (see section joysticks)
- S... Single-Axis Controller (see section joysticks)
- D... Double-Handle Controller (see section joysticks)
- N... Control-Switch (see page 113)
- ... More command and indicating devices (see page 137 and 243)

### Wiring

KL Without wiring, but terminal block built in each terminal

KLV On terminal block 4 mm with single wire 1 mm<sup>2</sup> each terminal

KLV On SPS (SPS provision) with single wire 1 mm<sup>2</sup> each terminal

KLVA External wiring single wire highly flexible 1,5 mm², 5 m long each terminal

Additional-/ reduction price per meter

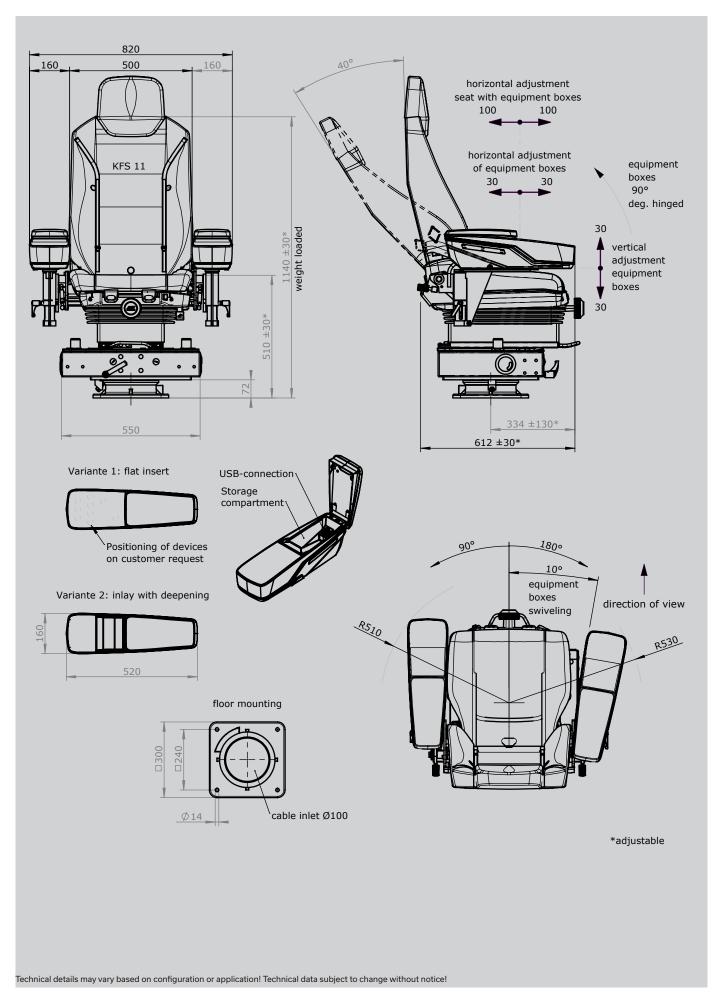
### Special model

X Special / customer specified

X Special painted







# **Control Unit** KST 30 swiveling





The KST30 is an ergonomically designed swiveling chair which provides a high degree of comfort. The inner consoles, mounted to the Driver's Seat, swing with the seat. The consoles can be positioned to perfectly match any person by means of length, height and inclination adjustment. For console version 1 the whole control unit can be expanded by additional fixed outer consoles.

The standard version includes:

### Inner consoles:

The plastic consoles can be height-adjusted to match joysticks of any size. In addition consoles can be equipped with custom command and indicating devices.

#### Outer consoles:

The outer metal consoles feature foldable top covers, including mechanical fixation to keep cover in open position. Internal terminal strips can easily be accessed be removeable side covers. Command and indicating devices can be added based on customer's choice. Also special sizes and shapes of outer consoles are available on request.

### Driver's Seat:

The comfortable Driver's Seat KFS 11 is equipped with a spring loaded hydraulic vibration absorption system, including weight adjustment, air-permeable textile cover, arm rests and head rest.

### Cross-member with swivel base:

The cover of the sheet steel cross-member including the Driver's Seat is forward foldable. Thereby all wirings, terminals and bushings are easily accessible during commissioning and maintenance. Swivel base has zero-tolerance bearings and rotation can be locked in 3° steps.

### Surface treatment:

Base coat and textured varnish

Standard colour RAL 7035 light grey in combination with RAL 7015 slate-grey



		KST3011	-U2	-M1	-F3	-LK	1	KFS 11	/	V85	/	V85	/	KL	/	Х
Basic unit																۱
KST3001	With inner equipment boxes version 1															ı
KST3011	With inner eqiupment boxes version 1 and outside eqiupment boxes 160 mm wide															
KST3031	With inner eqiupment boxes version 1 and outside eqiupment boxes 270 mm wide															
KST3041	With inner eqiupment boxes version 1 and outside eqiupment boxes 320 mm wide															
	Special equipment boxes form on request!															
Base unit	Curicaling 1900 left 000 right with detent incl	atan ralaa														ı
	Swiveling 180° left, 90° right with detent incl.	z-step releas	е													ı
U3	Electric swiveling 180° left, 90° right															
U4	Non swiveling															ı
Attachmer	its	l														1
M1	Monitor mounting with monitor housing						'									1
M2	Monitor mounting with monitor mounting brad	cket														ı
M3	Monitor mounting without monitor housing/-	mounting br	acket													ı
F3	Footrest KBF/716															ı
LK	Plate for horizontal manual adjustment for cor	ntrol units +/-	· 250 m	ım												ı
Driver's Se	eat															ı
KFS11*	(Included in the delivery!)															ı
KFS9*																ı
KFS10*																
KFS12*																
	n see Driver's Seat page 251															

Example





KST3011 -U2 KFS 11 / V85 KL -M1 -F3 -LK / V85 Mounting for equipment boxes V... Multi-Axis Controller (see section joysticks) S... Single-Axis Controller (see section joysticks) D... Double-Handle Controller (see section joysticks) N... Control-Switch (see page 113) More command and indicating devices (see page 137 and 243) Wiring KL Without wiring, but terminal block built in each terminal KLV On terminal block 4 mm with single wire 1 mm<sup>2</sup> each terminal KLV On SPS (SPS provision) with single wire 1 mm² each terminal External wiring single wire highly flexible 1,5 mm<sup>2</sup>, 5 m long each terminal KLVA Additional-/ reduction price per meter Special model

Χ

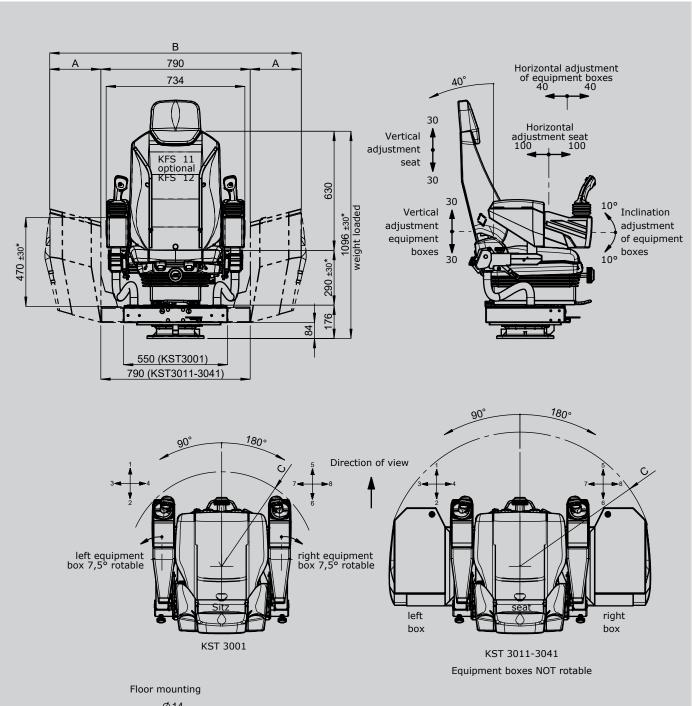
Χ

Special / customer specified

Special painted







Floor mot	ıntıng
	14_
0300	cable inlet Ø100

\* adjustable

Туре	Dim. A	Dim. B	Dim. C
KST 3001	-	-	500
KST 3011	160	1110	610
KST 3031	270	1330	710
KST 3041	320	1430	755

### **Control Unit** KST 19 swiveling





The KST19 is an ergonomically designed swiveling control chair which provides a high degree of comfort.

### Equipment boxes:

The equipment boxes are vertically and horizontally adjustable. The arrangement of the joysticks, indicators and control devices is customised according to customer specifications. Cabling is carried out through a cross-member in the traverse. (Terminal block)

### Driver's Seat:

As standard the KST19 is fitted with a KFS10 seat. The seat itself is fitted with a pneumatic vibration absorption system complete with weight adjustment to ensure that the comfort level is fitted with armrests and a headrest. There is the option to have the seat covered with air-permeable artificial leather.

### Cross-member with swivel base:

The swivel base is zero-clearance bearing and can be locked either by a detent (standard) in 3° steps or stepless by a friction brake.

#### Surface treatment:

Base coat and textured varnish

Standard colour RAL 7035 light grey, equipment boxes RAL 7016 anthracite



Example

KST19 -U1 -M1 -F3 -LK / KFS 10	/	V85	/	V85	/	KL	/	Х
--------------------------------	---	-----	---	-----	---	----	---	---

### Basic unit

KST19 With equipment boxes

### Base unit

U1	Curingling 1000 left 000 right with frigition health
OI	Swiveling 180° left, 90° right with friction brake

Swiveling 180° left, 90° right with detent incl. 2-step release U2

Non swiveling

### **Attachments**

M4

M1	Monitor mounting with mon	itor housing
----	---------------------------	--------------

M2 Monitor mounting with monitor mounting bracket

МЗ Monitor mounting without monitor housing/-mounting bracket Monitor mounting (Monitor < 5 kg) with monitor housing

M5 Monitor mounting (Monitor < 5 kg) with mounting adapter

F3 Footrest KBF/716

Н Heater 2 x 2 kW with ventilator

LK Plate for horizontal manual adjustment for control units +/- 250 mm

### **Driver's Seat**

KFS10\* (Included in the delivery!)

\*Description see Driver's Seat page 251





KST19 -U1 -M1 -F3 -LK / KFS10 / V85 / V85 / KL / X

### Mounting for equipment boxes

- V... Multi-Axis Controller (see section joysticks)
- S... Single-Axis Controller (see section joysticks)
- D... Double-Handle Controller (see section joysticks)
- N... Control-Switch (see page 113)
- ... More command and indicating devices (see page 137 and 243)

### Wiring

- KL Without wiring, but terminal block built in each terminal
- KLV On terminal block 4 mm² with single wire 1 mm² each terminal
- KLV On SPS (SPS provision) with single wire 1 mm² each terminal

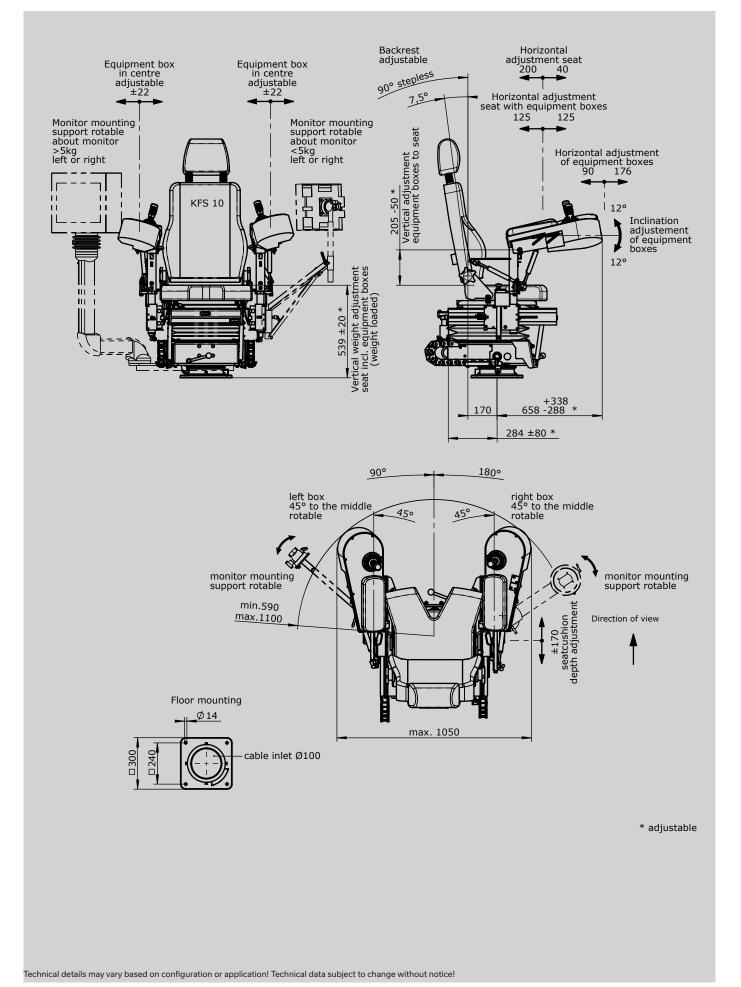
### Special model

- X Special / customer specified
- X<sup>2</sup> Special painted

### Option







### Control Unit KST 10 swiveling





The KST10 is an ergonomically designed swiveling control chair which provides a high degree of comfort.

#### Equipment boxes:

The equipment boxes are vertically and horizontally adjustable. The arrangement of the joysticks, indicators and control devices is customised according to customer specifications. Cabling is carried out through a cross-member in the traverse. (Terminal block)

Special boxes available upon request.

### Driver's Seat:

As standard the KST10 is fitted with a KFS11 seat. The seat itself is fitted with a hydraulic vibration absorption system complete with weight adjustment to ensure that the comfort level is fitted with armrests and a headrest. There is the option to have the seat covered with air-permeable artificial leather.

### Cross-member with swivel base:

The cover of the sheet steel cross-member including the Driver's Seat is forward foldable. Thereby all wirings, terminals and bushings are easily accessible during commissioning and maintenance. The swivel base is zero-clearance bearing and can be locked either by a detent (standard) in 3° steps or stepless by a friction brake.

Surface treatment: Base coat and textured varnish Standard colour RAL 9011 black



-M1 -F3 -LK **KFS 11** / V85 V85.1 / KL **Basic unit** KST10 With equipment boxes Base unit U1 Swiveling 180° left, 90° right with friction brake Swiveling 180° left, 90° right with detent incl. 2-step release U2 (standard) U3 Electric swiveling 180° left, 90° right U4 Non swiveling U5 Without base frame **Attachments** M1 Monitor mounting with monitor housing M2 Monitor mounting with monitor mounting bracket МЗ Monitor mounting without monitor housing/-mounting bracket F3 Footrest KBF/716 Н Heater 2 x 2 kW with ventilator LK Plate for horizontal manual adjustment of control units +/- 250 mm **Driver's Seat** KFS11\* (Included in the delivery!) KFS9\* KFS10\* KFS12\* \*Description see Driver's Seat page 251

Example

/

-U1

KST10





KST10 -U1 -M1 -F3 -LK / KFS 11 / V64 / V64.1 / KL / X

### Mounting for equipment boxes

V... Multi-Axis Controller (see section joysticks)

S... Single-Axis Controller (see section joysticks)

D... Double-Handle Controller (see section joysticks)

N... Control-Switch (see page 113)

... More command and indicating devices (see page 137 and 243)

### Wiring

KL Without wiring, but terminal block built in each terminal

KLV On terminal block 4 mm<sup>2</sup> with single wire 1 mm<sup>2</sup> each terminal

KLV On SPS (SPS provision) with single wire 1 mm<sup>2</sup> each terminal

### Special model

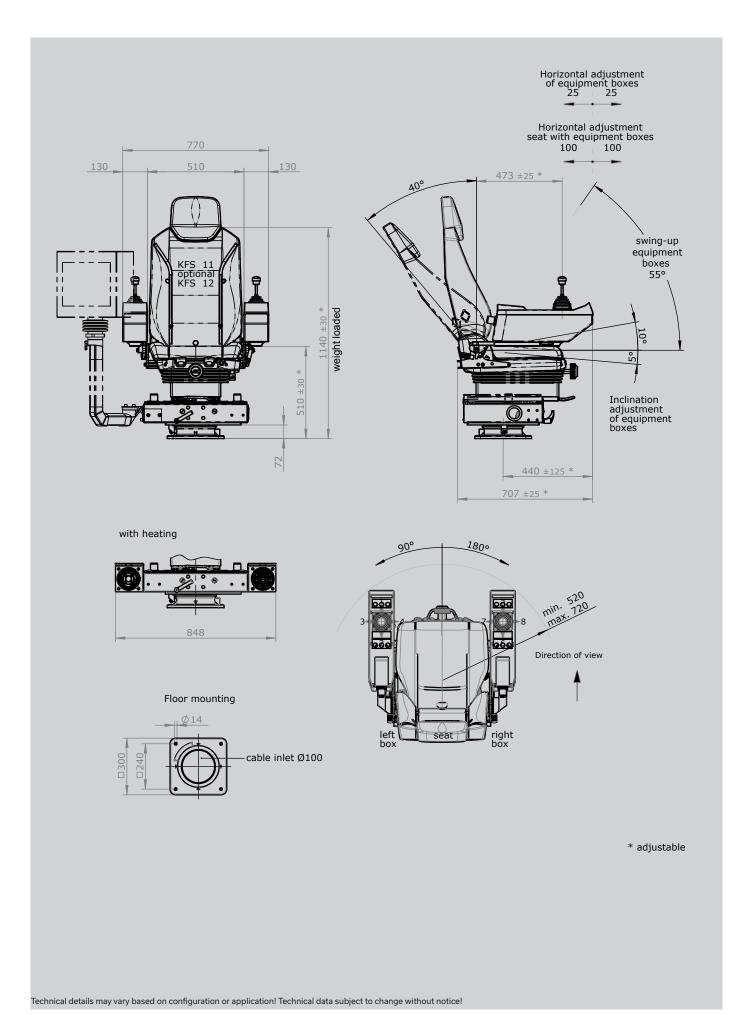
X Special / customer specified

X<sup>2</sup> Special painted

### Option







# **Control Unit** KST 4 swiveling





The KST4 is an ergonomically designed swiveling control chair which provides a high degree of comfort.

### Equipment boxes:

The sheet steel equipment boxes are vertically and horizontally adjustable. The arrangement of the joysticks, indicators and control devices is customised according to customer specifications. Cabling is carried out through a cross-member in the traverse. (Terminal block) Special boxes available upon request.

### Driver's Seat:

As standard the KST4 is fitted with a KFS11 seat. The seat itself is fitted with a hydraulic vibration absorption system complete with weight adjustment to ensure that the comfort level is fitted with armrests and a headrest. There is the option to have the seat covered with air-permeable artificial leather.

### Cross-member with swivel base:

The cover of the sheet steel cross-member including the Driver's Seat is forward foldable. Thereby all wirings, terminals and bushings are easily accessible during commissioning and maintenance. The swivel base is zero-clearance bearing and can be locked either by a detent (standard) in 3° steps or stepless by a friction brake.

Surface treatment: Base coat and textured varnish Standard colour RAL 9011 black



	K3141	-01	-IAI T	.L2	-LIN	/	VL2 II	/	V 04	/	V04.1	/	ΝL	/	^
										-					
Desire and the	_														

Basic unit	
KST41	With equipment boxes 160 x 420 mm
KST42	With equipment boxes 200 x 420 mm

Base unit	
U1	Swiveling 180° left, 90° right with friction brake
U2	Swiveling 180° left, 90° right with detent incl. 2-step releas (standard)
U3	Electric swiveling 180° left, 90° right
U4	Non swiveling
U5	Without base frame

Actualiments	
M1	Monitor mounting with monitor housing
M2	Monitor mounting with monitor mounting bracket
M3	Monitor mounting without monitor housing/-mounting bracket
F3	Footrest KBF/716

LK	Plate for horizontal manual adjustment of Control Units +/- 250 mm

Driv	حاسمه	C	
יותע	rer s	Steam	L

225

KFS11*	(Included	in the	delivery!)
--------	-----------	--------	------------

Heater 2 x 2 kW with ventilator

111 012
KFS12*
KFS10*
KFS9*



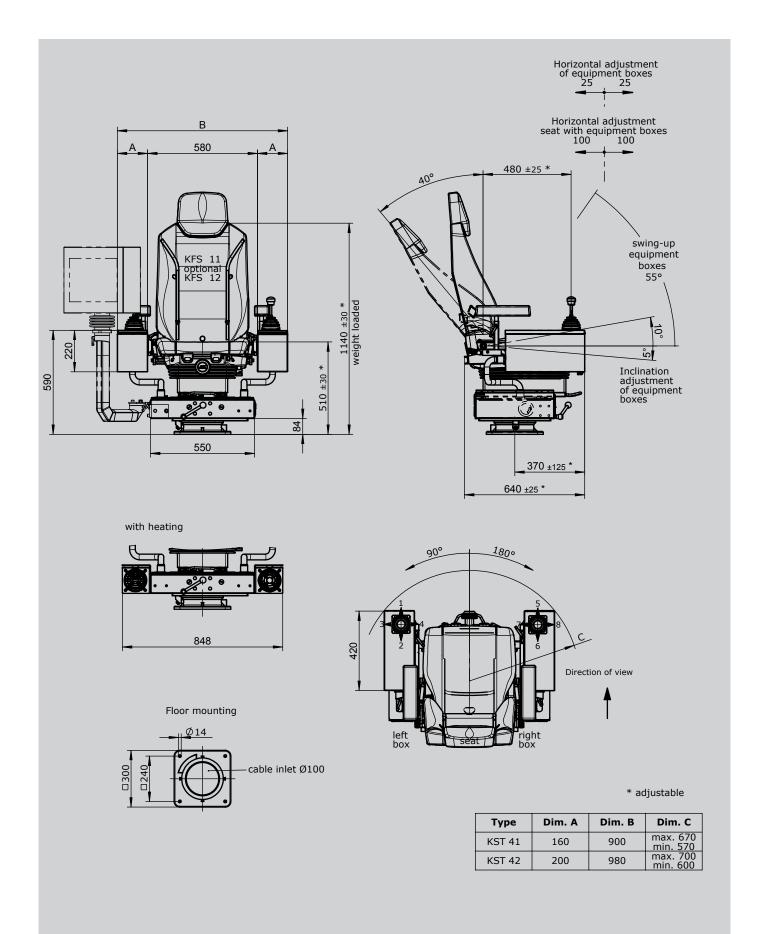


KST41 -U1 -M1 -F3 -LK KFS 11 / V64 / V64.1 KL Mounting for equipment boxes V... Multi-Axis Controller (see section joysticks) S... Single-Axis Controller (see section joysticks) D... Double-Handle Controller (see section joysticks) N... Control-Switch (see page 113) More command and indicating devices (see page 137 and 243) Wiring KL Without wiring, each terminal block built in each terminal KLV On terminal block 4 mm<sup>2</sup> with single wire 1 mm<sup>2</sup> each terminal KLV On SPS (SPS provision) with single wire 1  $\mbox{mm}^2$  each terminal KLVA External wiring single wire highly flexible 1,5  $\mathrm{mm^2}$ , 5 m long each terminal Special model Χ Special / customer specified  $X^2$ Special painted

### Option







# **Control Unit** KST 5 swiveling





The KST5 is an ergonomically designed swiveling control chair which provides a high degree of comfort.

### Equipment boxes:

The equipment boxes are made from sheet steel and as standard have a hinged lid with locking feature. This allows for easy inspection and maintenance. The side of the equipment boxes is as standard fitted with an inspection plate which again is lockable. The arrangement of the joystick, indicators and control devices is cutomised according to customer specifications. This combined with the custom sized and profiled equipment boxes that are available means that the KST5 is very flexible and customisable solution.

### Driver's Seat:

As standard the KST5 is fitted with a KFS11 seat. The seat itself is fitted with a hydraulic vibration absorption system complete with weight adjustment to ensure that the comfort level is fitted with armrests and a headrest. There is the option to have the seat covered with air-permeable artificial leather.

### Cross-member with swivel base:

The cover of the sheet steel cross-member including the Driver's Seat is forward foldable. Thereby all wirings, terminals and bushings are easily accessible during commissioning and maintenance. The swivel base is zero-clearance bearing and can be locked either by a detent (standard) in 3° steps or stepless by a friction brake.

### Surface treatment:

Base coat and textured varnish Standard colour RAL 7035 light grey



V64

V64.1

KL

	Example	е		
-U1	-M1	-F3	-LK	/

**KFS 11** 

Basic unit		
KST51	With equipment boxes 200 x 580 mm	
KST52	With equipment boxes 270 x 580 mm	
KST54	With equipment hoxes 320 x 580 mm	

KST51

### Base unit

U1	Swiveling 180° left, 90° right with friction brake
U2	Swiveling 180° left, 90° right with detent incl. 2-step release (standard)
U3	Electric swiveling 180° left, 90° right
ш	Non swiveling

Special boxes for request!

### **Attachments**

M1	Monitor mounting with monitor housing	
M2	Monitor mounting with monitor mounting bracket	
МЗ	Monitor mounting without monitor housing/-mounting bracket	
F3	Footrest KBF/716	
Н	Heater 2 x 2 kW with ventilator 240V AC	
LS	Plate for horizontal manual adjustment for control units +/- 75 mm	
LK	Plate for horizontal manual adjustment for control units +/- 250 mm	
Label without engraving for Multi-axis-/ Single-Axis Controller		
Label wi	Label with engraving for Multi-axis-/ Single-Axis Controller	



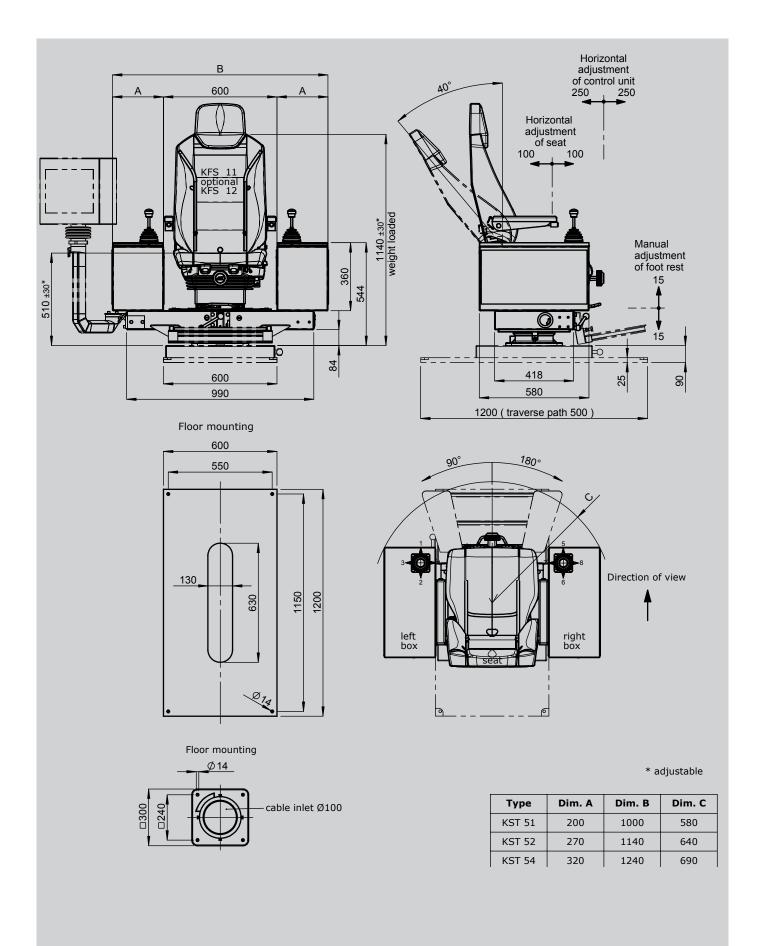


KST51 -U1 KFS 11 V64 V64.1 -M1 -F3 -LK / KL **Driver's Seat** KFS11\* (Included in the delivery!) KFS9\* KFS10\* KFS12\* \*Description see Driver's Seat page 251 Mounting for equipment boxes V... Multi-Axis Controller (see section joysticks) S... Single-Axis Controller (see section joysticks) D... Double-Handle Controller (see section joysticks) N... Control-Switch (see page 113) More command and indicating devices (see page 137 and 243) Wiring KL Without, but terminal block built each terminal KLV On terminal block 4 mm<sup>2</sup> with single wire 1 mm<sup>2</sup> each terminal KLV On SPS (SPS provision) with single wire 1 mm² each terminal KLVA External wiring single wire highly flexible 1,5 mm<sup>2</sup>, 5 m long each terminal Special model Special / customer specified X1 Special painted

Option







# **Control Unit** KST 6 swiveling





The KST6 is an ergonomically designed swiveling control chair which provides a high degree of comfort.

### Equipment boxes:

The equipment boxes are vertically and horizontally adjustable. The arrangement of the joysticks, indicators and control devices is customised according to customer specifications. Cabling is carried out through a cross-member in the traverse. (Terminal block)

### Driver's Seat:

As standard the KST6 is fitted with a KFS11 seat. The seat itself is fitted with a hydraulic vibration absorption system complete with weight adjustment to ensure that the comfort level is fitted with armrests and a headrest. There is the option to have the seat covered with air-permeable artificial leather.

### Cross-member with swivel base:

The cover of the sheet steel cross-member including the Driver's Seat is forward foldable. Thereby all wirings, terminals and bushings are easily accessible during commissioning and maintenance. The swivel base is zero-clearance bearing and can be locked either by a detent (standard) in 3° steps or stepless by a friction brake.

Surface treatment: Base coat and textured varnish Standard colour RAL 9011 black



		KST6	-U2	-M1	-F3	-LK	/	KFS 11	/	V64	/	V64.1	/	KL	/	X
B																
Basic uni	With equipment boxes															
K310	with equipment boxes															
Base unit	t															
U1	Swiveling 180° left, 90° right with friction bra	ake														
U2	Swiveling 180° left, 90° right with detent incl release (standard)	. 2-step														
U3	Electric swiveling 180° left, 90° right															
U4	Non swiveling															
U5	Without base frame															
	_															
Attachmo	ents															
M1	Monitor mounting with monitor housing															
M2	Monitor mounting with monitor mounting br	acket														
M3	Monitor mounting without monitor housing/	'-mountir	ng bracke	et												
F3	Footrest KBF/716															
Н	Heater 2 x 2 kW with ventilator															
LK	Plate for horizontal manual adjustment for co	ontrol un	its +/- 25	0 mm												
Driver's S	Seat															
KFS11*	(Included in the delivery!)															
KFS9*																
KFS10*																
KFS12*																
*Descript	tion see Driver's Seat page 251															



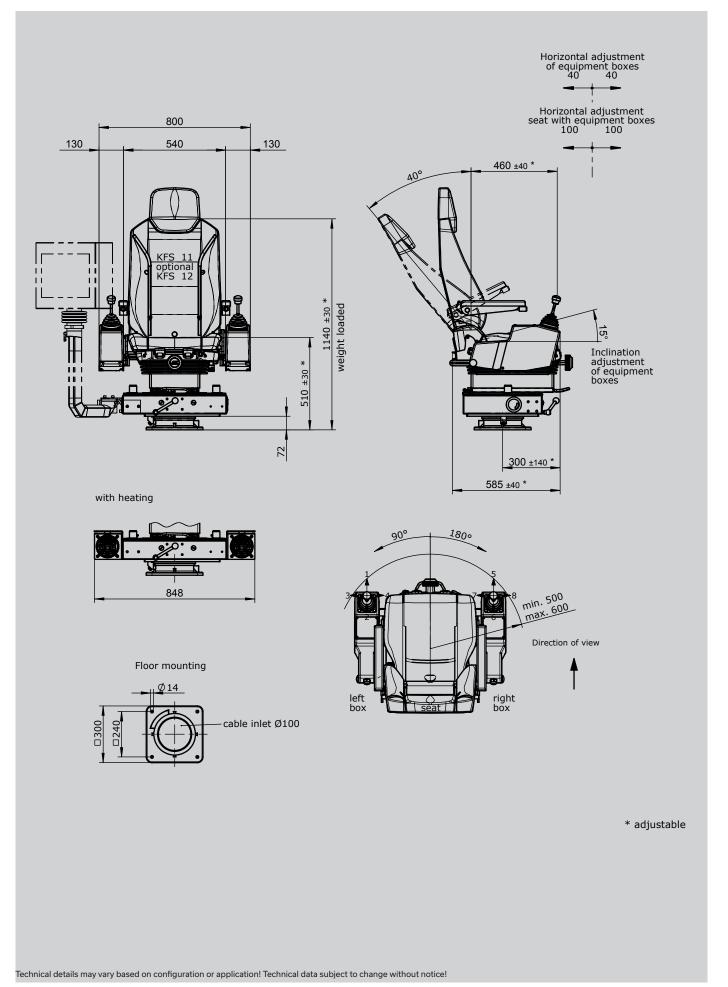


		KST6	-U2	-M1	-F3	-LK	/	KFS 11	/	V64	/	V64.1	/	KL	/	X
Mounti	ng for equipment boxes															
V	Multi-Axis Controller (see section joysticks)															
S	Single-Axis Controller (see section joysticks,	)														
D	Double-Handle Controller (see section joyst	icks)														
N	Control-Switch (see page 113)															
	More command and indicating devices (see	page 13	37 and 2	243)												
Wiring																
KL	Without, but terminal block built each termi	nal														
KLV	On terminal block 4 mm² with single wire 1 r	mm² eac	h termii	nal												
KLV	On SPS (SPS provision) with single wire 1 m	m² each	termin	al												
KLVA	External wiring single wire highly flexible 1,5	mm², 5	m long	each te	rminal											
Special	model															
Х	Special / customer specified															
X <sup>2</sup>	Special painted															

### Option







## **Control Unit** KST 8 swiveling





The KST8 is an ergonomically designed swiveling control chair which provides a high degree of comfort.

#### Equipment boxes:

The equipment boxes are vertically and horizontally adjustable. The arrangement of the joysticks, indicators and control devices is customised according to customer specifications. Cabling is carried out through a cross-member in the traverse. (Terminal block)

Special boxes available upon request.

### Driver's Seat:

As standard the KST8 is fitted with a KFS11 seat. The seat itself is fitted with a hydraulic vibration absorption system complete with weight adjustment to ensure that the comfort level is fitted with armrests and a headrest. There is the option to have the seat covered with air-permeable artificial leather.

### Cross member with swivel base:

The cover of the sheet steel cross-member including the Driver's Seat is forward foldable. Thereby all wirings, terminals and bushings are easily accessible during commissioning and maintenance. The swivel base is zero-clearance bearing and can be locked either by a detent (standard) in 3° steps or stepless by a friction brake.

Surface treatment: Base coat and textured varnish Standard colour RAL 9011 black



Example

KST8 -U1 -M1 -F3 -LK / KFS 11 / V64 / V64.1 / KL / )

### Basic unit KST8 With equipment boxes Base unit U1 Swiveling 180° left, 90° right with friction brake Swiveling 180° left, 90° right with detent incl. 2-step release U2 (standard) U3 Electric swiveling 180° left, 90° right U4 Non swiveling U5 Without base frame Attachments M1 Monitor mounting with monitor housing M2 Monitor mounting with monitor mounting bracket М3 Monitor mounting without monitor housing/-mounting bracket F3 Footrest KBF/716 Н Heater 2 x 2 kW with ventilator Plate for horizontal manual adjustment of control units +/- 250 mm LK **Driver's Seat** KFS11\* (Included in the delivery!) KFS9\* KFS10\* KFS12\* \*Description see Driver's Seat page 251



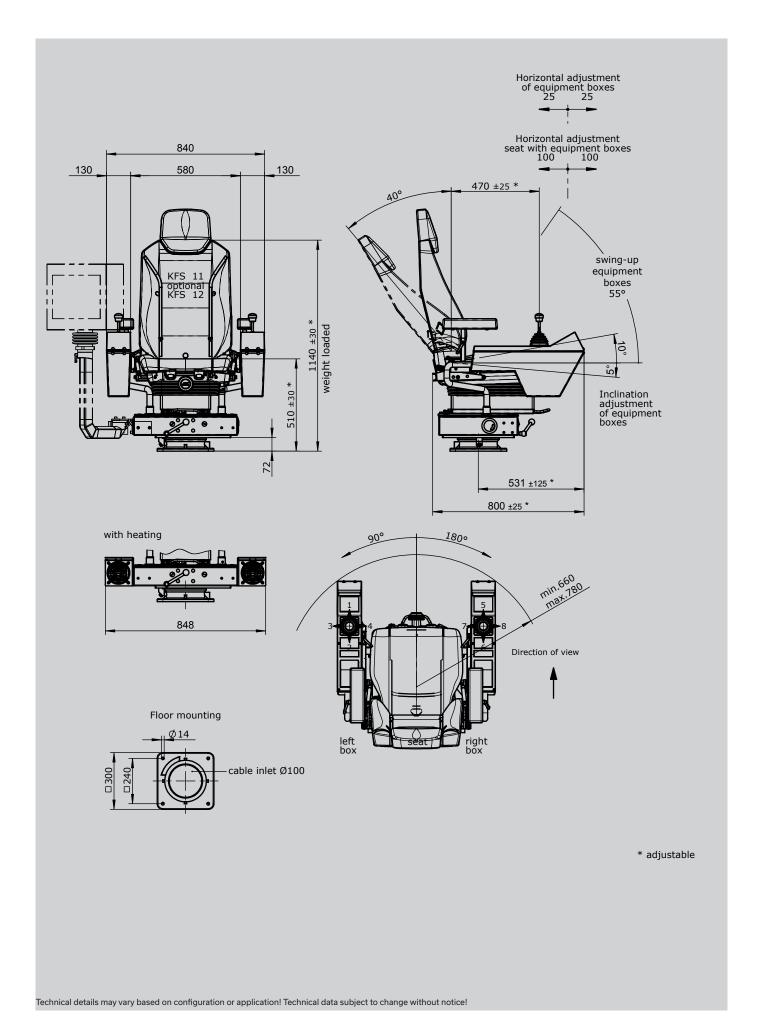


KST8 KFS11 / V64.1 KL -U1 -M1 -F3 -LK V64 Mounting for equipment boxes V... Multi-Axis Controller (see section joysticks) S... Single-Axis Controller (see section joysticks) D... Double-Handle Controller (see section joysticks) N... Control-Switch (see page 113) More command and indicating devices (see page 137 and 243) Wiring KL Without wiring, but terminal block built each terminal KLV On terminal block 4 mm<sup>2</sup> with single wire 1 mm<sup>2</sup> each terminal KLV On SPS (SPS provision) with single wire 1 mm<sup>2</sup> each terminal External wiring single wire highly flexible 1,5 mm $^2$ , 5 m long each terminal KLVA Special model Special / customer specified  $X^2$ Special painted

### Option







### **Control Unit**





The KST85 is an ergonomically designed swiveling control chair which provides a high degree of comfort.

### Equipment boxes:

The equipment boxes are vertically and horizontally adjustable. The arrangement of the joysticks, indicators and control devices is customised according to customer specifications. Cabling is carried out through a cross-member in the traverse. (Terminal block)

Special boxes available upon request.

### Driver's Seat:

The comfortable spring mounted seat KFS14 with roller-bearing swivel systems.

### Heating console:

Cover with 2 steps heating (2x2kW 400V AC) with integrated ventilator. The cover of the heating cover can be tilted forward to reach the terminal block of the heating and cable execution.

### Surface treatment:

Base coat and textured varnish Standard colour RAL 9011 black





		KST85	Example -M1	,	KFS14	,	V64	,	V64.1	,	KL	,	v
		K3103	-IVI I	,	KF314	· /	V04	,	V04.1	,	NL.	,	X
Basic uni	t												
KST85	With heating in the console base												
KST87	With console base without heating												
Attachme	ents												
M1	Monitor mounting with monitor housing												
M2	Monitor mounting with monitor mounting bracket												
МЗ	Monitor mounting without monitor housing/-mounting	ng bracket											
Driver's S	Seat	ı											
KFS14*	(Included in the delivery!)												
Mounting	g for equipment boxes												
V	Multi-Axis Controller (see section joysticks)												
S	Single-Axis Controller (see section joysticks)												
D	Double-Handle Controller (see section joysticks)												
N	Control-Switch (see page 113)												
	More command and indicating devices (see page 137	7 and 243)	)										
Wiring		1											
KL	Without wiring, but with terminal block built each ter	minal											
KLV	On terminal block 4 mm <sup>2</sup> with single wire 1 mm <sup>2</sup> each	terminal											

### Special model

Χ Special / customer specified

 $X^2$ Special painted

### Option

KLV

KLVA

Radio remote control system

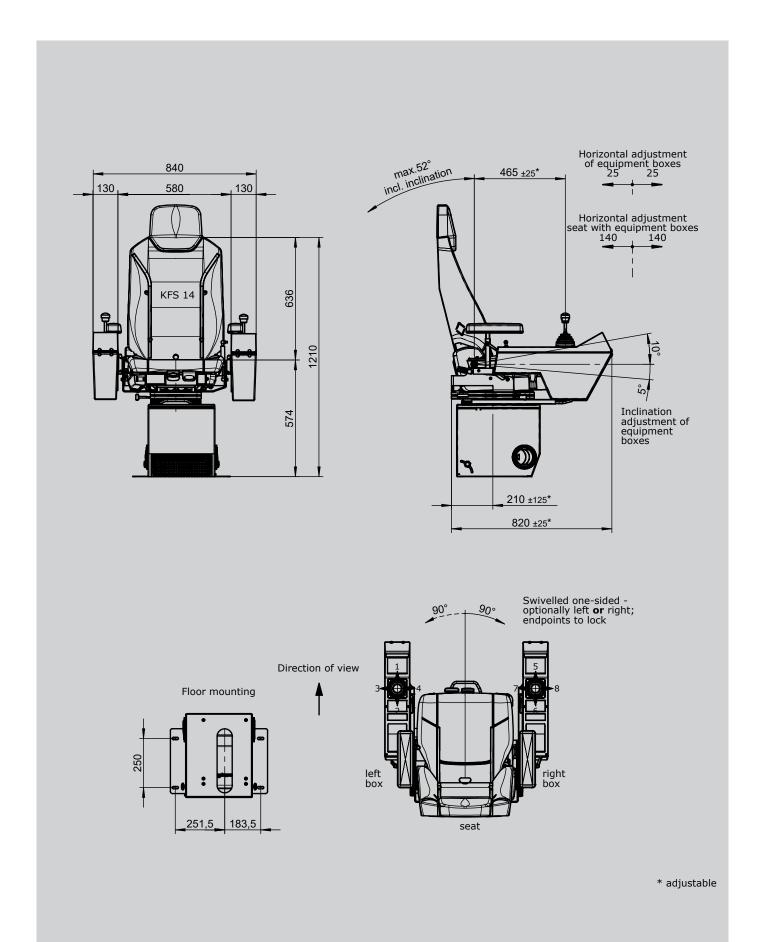
Technical details may vary based on configuration or application! Technical data subject to change without notice!

External wiring single wire highly flexible 1,5 mm<sup>2</sup>, 5 m long each terminal

On SPS (SPS provision) with single wire 1 mm<sup>2</sup> each terminal







### Control Unit





The KST7 is an ergonomically designed swiveling control chair which provides a high degree of comfort.

### Equipment boxes:

The equipment boxes are made from sheet steel and as standard have a hinged lid with locking feature. This allows for easy inspection and maintenance. The side of the equipment boxes is as standard fitted with an inspection plate which again is lockable. The arrangement of the joystick, indicators and control devices is customised according to customer specifications. This combined with the custom sized and profiled equipment boxes that are available means that the KST7 is very flexible and customisable solution.

### Driver's Seat:

The tipped spring mounted seat KFS4 is fit with an hydraulic vibration absorption system incl. weight adjustment. With the folding spring mounted seat you can also arrive your workplace in small cabins.

#### Base plate:

The cran control unit is available with or without base plate.

Surface treatment: Base coat and textured varnish Standard colour RAL 7035 light grey



KST7 KFS11 V64 V64.1 / KL -1 Basic unit KST7 With equipment boxes 290 x 500 mm KST175 With equipment boxes 210 x 500 mm Special boxes for request! Base plate 1 With base plate prepare for Driver's Seat KFS4 2 With base plate prepare for Driver's Seat KFS2 3 With base plate with apron for Driver's Seat KFS9, KFS11... 4 Without base plate **Driver's Seat KFS 4\*** (Included in the delivery!) KFS 2\* **KFS 11\*** KFS 9\* \*Description see Driver's Seat page 251 Mounting for equipment boxes V... Multi-Axis Controller (see section joysticks) S... Single-Axis Controller (see section joysticks) D... Double-Handle Controller (see section joysticks) N... Control-Switch (see page 113) More command and indicating devices (see page 137 and 243)

Example





KST 7 -1 / KFS 11 / V64 / V64.1 / KL / X

wiring	
KL	Without wiring, but terminal block built each terminal
KLV	On terminal block 4 mm² with single wire 1 mm² each terminal
KLV	On SPS (SPS provision) with single wire 1 mm² each terminal
KLVA	External wiring single wire highly flexible 1,5 $\mathrm{mm^2}$ , 5 $\mathrm{m}$ long each terminal

### Special model

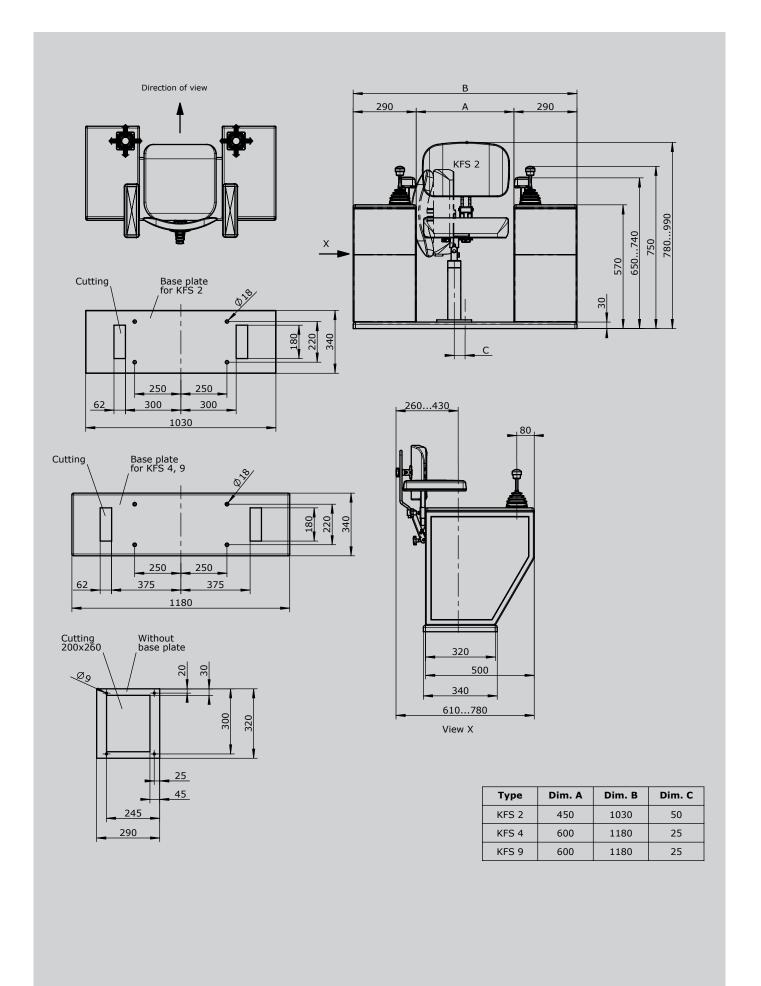
X Special / customer specified

X<sup>2</sup> Special painted

### Option









Dimension outside in mm (BxLxH)	Dimension inside in mm (BxLxH)	Remarks	Weight KG	Form
Steel sheet housing material Protection IP54 painting RAL	thickness 1/1,5 mm . 7032 pebble-grey textured varnish			
200 x 200 x 92	166 x 166 x 90		1,3	B 200
230x 230 x 105	196 x 196 x 102		1,4	B 230
230 x 340 x 105	196 x 306 x 102		1,5	B 230 x 340
230 x 440 x 105	196 x 406 x 102		1,6	B 230 x 440
250 x 250 x 150	216 x 216 x 147		1,6	B 250 x 250
150 x 400 x 105	116 x 366 x 102		3,2	B 150 x 400
150 x 500 x 105	116 x 466 x 102		3,5	B 150 x 500
150 x 600 x 105	116 x 566 x 102		3,8	B 150 x 600
260 x 500 x 105	226 x 466 x 102		3,8	B 260 x 500
260 x 600 x 105	226 x 566 x 102		4,2	B 260 x 600
dimensions special		On enquiry		
Plastic housing polycarbonat Protection IP65 colour RAL 7				
120 x 122 x 105	113 x 115 x 98		0,35	l 120 x 122
120 x 160 x 140	113 x 134 x 133		0,6	I 120 x 160
160 x 240 x 120	153 x 215 x 114		0,8	I 160 x 240
160 x 360 x 100	153 x 352 x 94		1,0	I 160 x 360
230 x 300 x 110	223 x 293 x 103		1,15	I 230 x 300
Plastic housing polyester Protection IP65 colour RAL 7	000 grey			
220 x 335 x 115	200 x 292 x 108	Colour altern. RAL 9011 black	1,65	I 220 x 335
220 x 465 x 115	200 x 432 x 108	Colour altern. RAL 9011 black	2,24	I 220 x 465
250 x 255 x 120	236 x 243 x 110		2,65	I 250 x 255
250 x 400 x 120	236 x 386 x 110		3,65	I 250 x 400
250 x 600 x 120	236 x 586 x 110		5,24	I 250 x 600
Accessory parts				
Hinges each housing (2 pcs.)			0,2	
Armrest with clamp adjustable	straps		0,5	
Cable entry M20 cable 7 - 13 m	nm	With anti-kink predection and strain relief	0,15	
Cable entry M32 cable 11 - 21	mm	With anti-kink predection and strain relief	0,2	
Cable entry M40 cable 19 - 28	mm	With anti-kink predection and strain relief	0,25	
Pillar with flange 100 x 100 x 5	35 mm high	Flange 150 x 150 mm	14,0	
Indicating labels not engraved	for Multi-axis / Single-Axis Controller			
Indicating labels with engraving	g for Multi-axis / Single-Axis Controller	Character		

# Attachment for Control Unit, portable control units and housings

Command and indicating devices 22 m	m (Siemens Typ 3SU) incl. indicating label	Contact- complement	Weight KG	Туре
Push button		1S+1Ö	0,040	D
Selector switch 0-1	2 positions	1S+1Ö	0,050	W
Selector switch 1-0-2	3 positions	2 S + 2 Ö	0,060	W
Key switch 0-1	2 positions	1S+1Ö	0,130	S
Key switch 1-0-2	3 positions	2 S + 2 Ö	0,140	S
Mushroom key switch latching		1S+1Ö	0,080	PS
Mushroom head push button latching		1 Ö	0,060	PV
Illuminated push button diode 24 V DC/A	С	1S+1Ö	0,040	LD
Illuminated push button diode 230 V AC		1S+1Ö	0,040	LD
Indicator light diode 24 V DC/AC			0,040	L
Indicator light diode 230 V AC			0,040	L
Coordinate switch 2 positions horizontal	T-O-T 3SU1030-7AC10	2 S	0,102	К
Coordinate switch 2 positions vertical T-C	P-T 3SU1030-7AD10	2 S	0,102	К
Coordinate switch 4 positions T-O-T / T-O	-T 3SU1030-7AF10	4 S	0,112	К
Switching element in addition		1S + 1Ö	0,010	
Other command and indicating devices				
Summer			0,250	
Knee button FAK-S/KC/I		1 S + 1 Ö	0,350	

1S+1Ö

0,450

### **Attachments**

Foot button

Drilling 22 mm

Blind plug 22 mm

Cutouts for display devices

Microphone with gooseneck

Power supply 230 V/24 V DC for Driver's Seat

### **Ordering information**



Customer Order No. Equipment box left Pos. Туре Colour Plant Desti-Label text (max. Notes No. 2 x 12 characters ref. nation 1 2 3 4 5 6 (1) (8) (9) (10) (15) (20) 8 (21) 9 (22) 10 (18) 23) 11 (14) (24) 12 13 14 15 16 Maximum installation of command and indicating devices 22 (see p.137 & 243) 17 in our control units and housings if our Multi-Axis Controllers V62 (see p.71) are used. Additional command and indicating 18 devices can be installed of Multi-Axis Controllers V64 or V11 (see p.71 or p.88) are 19 used. (please enquire) 20 21 22 23 24 Control unit (see p. 213) No. of pieces max. Type KST3 1 - 6, 8 - 13, 15 - 18 16 KST41/181 1 - 5, 10 - 12 8 KST42/182 1 - 5, 8 - 12, 15 - 17 13 KST51/122 3 - 7, 10 - 14, 15 - 19, 20 - 24 20 KST52/53/54/152/154 1 -24 24 KST6 3 - 4, 10 - 11, 15 - 16 6 KST7 1 - 24 24 KST75 1 - 19 19

### **Ordering information**



Order No. Customer Pos. Colour Label text (max). Plant Desti-Notes Equipment box right Type No. 2 x 12 characters ref. nation 1 2 3 4 5 6 (32) (25) 7 (26) (33) 8 (27) (34) 9 40) (35) 28 10 (41) (36) (29) (37) (30) 12 (38) (31) 13 14 15 16 Maximum installation of command and indicating devices 22 (see p.137 & 243) 17 in our control units and housings if our Multi-Axis Controllers V62 (see p.71) are used. Additional command and indicating 18 devices can be installed of Multi-Axis Controllers V64 or V11 (see p.71 or p.88) are 19 used. (please enquire) 20 21 22 23 Control unit (see p.213) No. of pieces max Type 25 - 30, 32 - 37, 39 - 42 16 KST3 25 - 29, 34 - 36 KST41/181 8 25 - 29, 32 - 36, 39 - 41 KST42/182 13 27 - 31, 34 - 38, 39 - 43, 44 - 48 20 KST51/122 25 - 48 24 KST52/53/54/152/154 27 - 28, 34 - 35, 39 - 40 KST6 6 25 - 48 24 KST7 25 - 43 KST75 19

KST8, 85



Customer Order No.								
Equipment box left		Pos. No.	Туре	Colour	Lable text (max). 2 x 12 characters	Plant ref.	Desti- nation	Notes
	Max. 6 pcs. installation of command	1						
(1) (3) (5) (2) (4) (6)	and indicating devices 22 (see p.137 & 243) or	2						
	1 pcs. monito- ring device 72 x 72mm	4						
1	Multi-Axis Con-	5						
$\begin{pmatrix} 3 & & \\ & & \\ & & \\ & & \\ 2 & & \end{pmatrix}$	troller V64 (see p.71) or V11 (see p.88)	6						
		7 8						
000	Max. 3 pcs.	9						
	installation of command and indicating devices 22 (see	10						
	p.137 & 243)	11						
	Place to put on devices	12						
Equipment box right	Max. 6 pcs.	13						
(13) (15) (17)	installation of command and indicating	14						
14 16 18	devices 22 (see p.137 & 243) or 1 pcs. monito-	15						
	ring device 72 x 72mm	16						
5	Multi-Axis Con- troller V64 (see	17						
7 8	p.71) or V11 (see p.88)	18 19						
		20						
19 20 21	Max. 3 pcs. installation	21						
	of command and indicatin devices 22 (see	22						
	p.137 & 243) Place to put on	23 24						
	devices	4-7						

KST10



Order No. Customer Pos. Equipment box left Type Colour Label text (max. Plant Desti-Notes 2 x 12 characters No. ref. nation 1 Max. 3 pcs. 2 installation of (1) (2) (3) command and 3 indicating devices 22 (see p.137 & 243) 4 5 6 Multi-axis Controller V11, 7 V14, V25, V85 8 9 (6) Max. 3 pcs. installation of command and indicating devices 22 (see p.137 & 243) Equipment box right 13 Max. 3 pcs. 14 installation of (10) (11) (12) command and 15 indicating devices 22 (see p.137 & 243) 16 17 18 Multi-axis Controller V11, V14, V25, V85 (13) (14) (15) Max. 3 pcs. installation of command and indicating devices 22 (see p.137 & 243)





Customer			Order No.				
Equipment box left	Pos. No.	Туре	Colour	Label text (max. 2 x 12 characters	Plant- ref.	Desti- nation	Notes
Multi-Axis Controller V11, V14, V25, V85 see p. 63, 50, 25, 10	1						
	2						
max. 7 installations of command and indicating devices 22 (see p.137 & 243)	3						
*2	4						
	5						
	6						
3 <b>1</b>	7						
10	8						
	9						
Equipment box right							
Multi-Axis Controller V11, V14, V25, V85 see p. 63, 50, 25, 10	25						
	26						
max. 7 installations of command and indicating devices 22 (see p.137 & 243)	27						
** P7	28						
( ) 5 T	29						
	30						
\\\^{\mathref{\sigma}}^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\\\^{\mathref{\sigma}}\\^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\^{\mathref{\sigma}}\\^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\\^{\mathref{\sigma}}\\^{\mathref{\sigma}}\\^{\mathref{\sigma}}\\\^{\mathr	31						
Ψ/							

KST30



KST30



Customer		_	Order No.				
Equipment box right	Pos. No.	Type	Colour	Lable text (max). 2 x 12 characters	Plant ref.	Desti- nation	Notes
5	1 2 3 4						
(7 <b>→</b> 8) 6	5 6 7 8		<u> </u>				
1 3 5 2 4 6	9 10 11 12						
	13 14 15 16						
	17 18 19 20						
	21 22 23 24						
	25 26 27 28						
(7)       (3)       (4)       (2)       (3)       (3)         (8)       (4)       (20)       (26)       (32)       (38)         (9)       (15)       (21)       (27)       (33)       (39)	29 30 31 32						
10 16 22 28 34 40 11 17 23 29 35 41 12 18 24 30 36 42	33 34 35 36						
	37 38 39 40 41						
	42						





The Driver's Seat KFS12 is ergonomically designed and provides a high grade of comfort. The Driver's Seat is equipped with an air-sprung vibration system. The weight adjustment is infinitely. Heated seats 24V, lumbar support, seat cushion adjustment, seat allocation recognition and headrest are included in the standard delivery. All adjustment controls are positioned ergonomically within easy access. The metal parts are protected against corrosion and painted black.

#### Technical data:

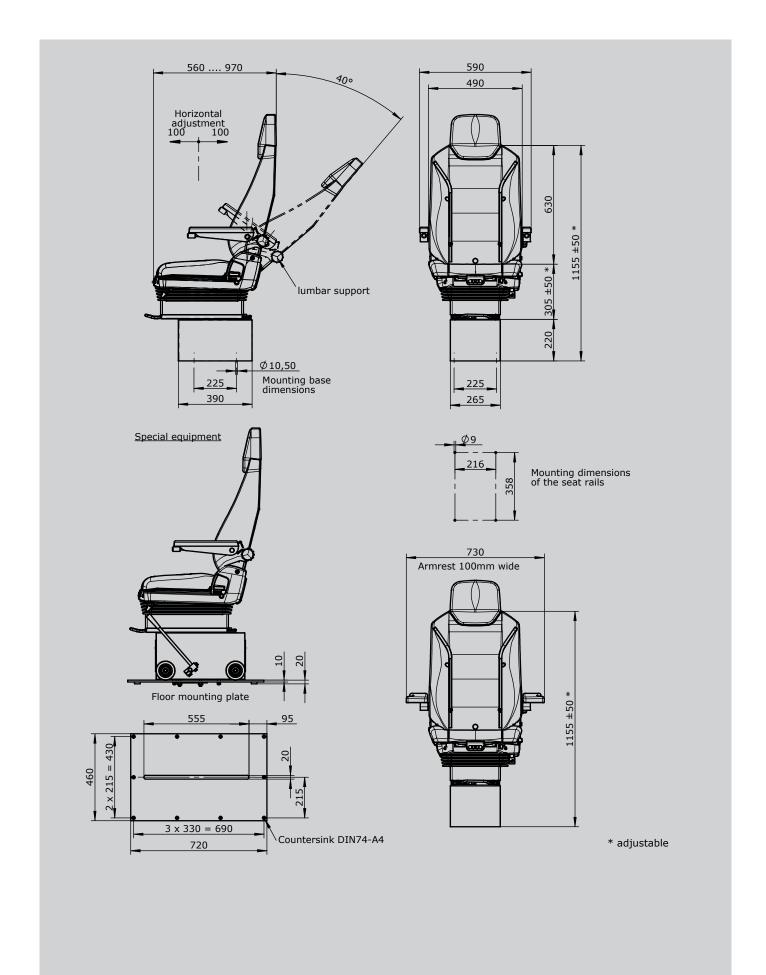
Suspension stoke	80 mm
Weight adjustment	50 - 150 kg
Horizontal adjustment	200 mm
Inclination of the backrest	-12°/+40°
Slope adjustment	-2°/+14°
Height adjustment	100 mm
Seat cushion adjustment	60 mm



Example

		KFS12	-A1	-S1
Driver's	Seat			
KFS12	Driver's Seat with textile cover black			
Attachm	nents			
A1	Armrest adjustable (2 pieces) 50 mm wide			
A2	Armrest continuously adjustable (2 pieces) 100 mm wide			
S1	Safety belt 2 point fixing (automatic)			
S3	Safety belt 2 point fixing (static)			
LK	Plate for horizontal manual adjustment of seat adjustable +/-250 mm			
C4	Loose cover for Driver's Seat KFS 11 / KFS 12			
U	Console (base)			
Z1	Mating connectors with 3 m connection cable			





## **Driver's Seat**





The Driver's Seat KFS11 is ergonomically designed and provides a high grade of comfort. The Driver's Seat is a low level mechanical suspension seat with an oil-hydraulic vibration absorption system with weight adjustment. All adjustment controls are positioned ergonomically within easy access. The metal parts are protected against corrosion and painted black.

#### **Technical data**

Suspension stoke	80 mm
Weight adjustment	50 - 150 kg
Horizontal adjustment	200 mm
Inclination of the backrest	-12°/+40°
Slope adjustment	-10°/+12°
Height adjustment	65 mm



Example

KFS11	-Δ1	-S1

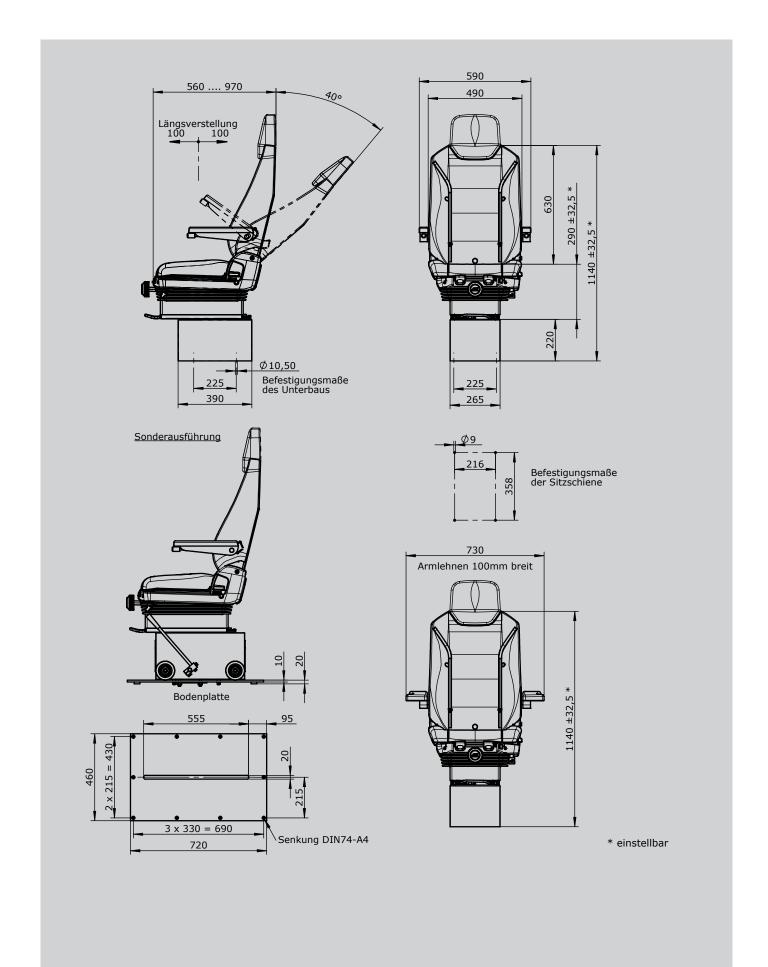
D	 C	a
DIAM	Sea	п

KFS11 Driver's Seat with textile cover black

Α	U	ta	C	ī	m	e	n	Ş

Attachme	ents		
К	Headrest		
A1	Armrest adjustable (2 pieces) 50 mm wide		
A2	Armrest continuously adjustable (2 pieces) 100 m	m wide	
Н	Seat cushion and backrest with heating element 2	4V DC 75W	
S1	Safety belt 2 point fixing (automatic)		
S3	Safety belt 2 point fixing (static)		
LK	Plate for horizontal manual adjustment of seat adj	ustable +/-250	mm
C4	Loose cover for Driver's Seat KFS 11 / KFS 12		
11	Console (hase)		









The Driver's Seat KFS10 is ergonomically designed and provides a high grade of comfort. The Driver's Seat has a pneumatic vibration absorption system with weight adjustment by compressor (24V DC 8 Ampere) and a standard seat cushion V-cut. Through its three horizontal adjustment, it can be flexibly adapted to very many applications. All adjustment controls are positioned ergonomically within easy access. The metal parts are protected against corrosion and painted black.

#### Technical data:

Suspension stoke 80 mm

Weight adjustment 50 - 150 kg (pneumatic)

50 - 130 kg (mechanical)

Horizontal adjustment

Seat with suspension system 160 mm
Seat part individual 240 mm
Seat cushion 160 mm
Inclination of the backrest max. 90°
Height and slope adjustment 40 mm

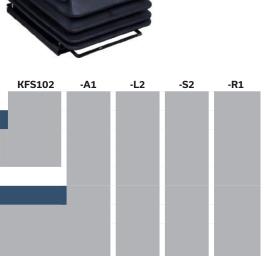


Example

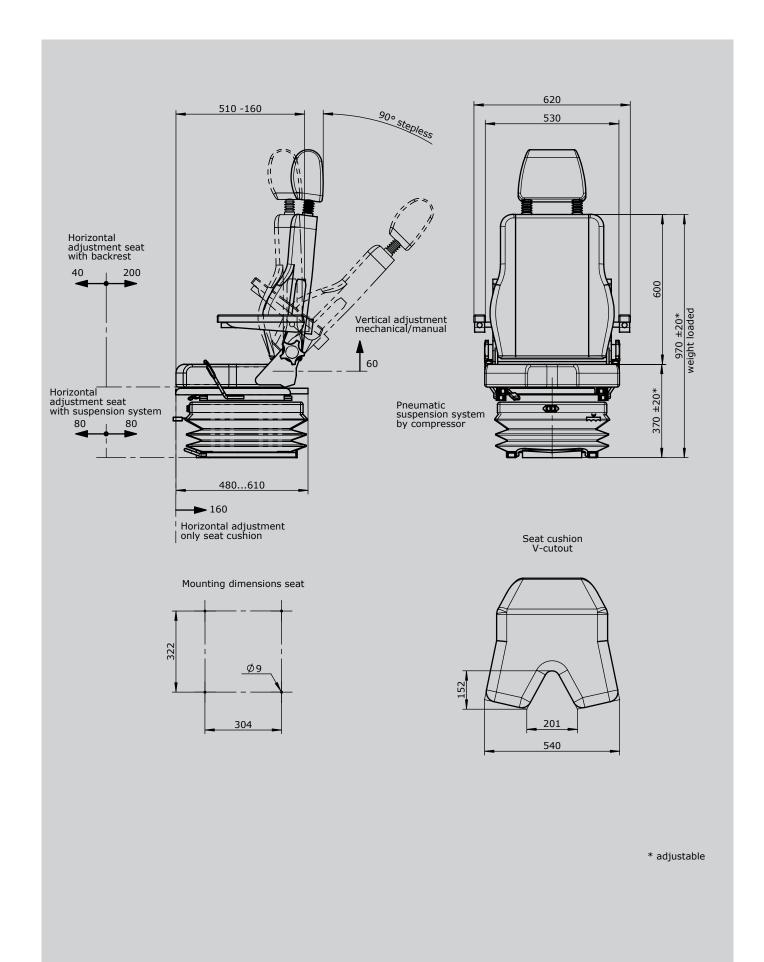
Driver's Se	eat .
KFS101	Driver's Seat with air-permeable artificial leather cover black with V-cut
KFS102	Driver's Seat with textile cover black with V-cut

Atta	ahm		
Alla	CHIL	ш	เอ

/ tetacimic	
К	Headrest
A1	Armrest adjustable (2 pieces) 50 mm wide
A2	Armrest continuously adjustable (2 pieces) 100 mm wide
L1	Lumbar support manual adjustment - 2 movement
L2	Lumbar support manual adjustment - 4 movement
В	Seat allocation recognition
Н	Seat cushion and backrest with heating element 24 V DC 47W
S1	Safety belt 2 point fixing (automatic)
S2	Safety belt 4 point fixing (headrest required)
S3	Safety belt 2 point fixing (static)
U	Console (base)
C3	Loose cover for Driver's Seat KFS10 with V-cut
R1	Price reduction pneumatic vibration absorption system
R2	Seat cushion without V-cut







Technical details may vary based on configuration or application! Technical data subject to change without notice!

### **Driver's Seat**





The Driver's Seat KFS9 is ergonomically designed and provides a high grade of comfort. The Driver's Seat is a low level mechanical suspension seat with an oil-hydraulic vibration absorption system with weight adjustment. Upon request, a pneumatic vibrating system with weight adjustment is available. All adjustment controls are positioned ergonomically within easy access. The metal parts are protected against corrosion and painted black.

#### **Technical data**

Suspension stoke 80 mm

Weight adjustment 50 - 150 kg (pneumatic)

50 - 130 kg (mechanical)

Horizontal adjustment 160 mm Inclination of the backrest max. 90° Height and slope adjustment 60 mm



Example

ט	rı	ve	er'	S	5	ea	at

KFS91 Driver's Seat with air-permeable artificial leather cover black

KFS92 Driver's Seat with textile cover black

#### **Attachments**

K	Headrest rain

A1 Armrest adjustable (2 pieces) 50 mm wide

A2 Armrest continuously adjustable (2 pieces) 100 mm wide

L1 Lumbar support manual adjustment - 2 movement

L2 Lumbar support manual adjustment - 4 movement

В Seat allocation recognition

Н Seat cushion and backrest standard with heating element 24 V DC 47W

Safety belt 2 point fixing (automatic) S1

S2 Safety belt 4 point fixing (headrest required)

S3 Safety belt 2 point fixing (static)

٧ Seat cushion with V-cut (LD required!)

LD Horizontal adjustment dual (seat height +30 mm!)

Pneumatic vibration absorption system with weight adjustment (incl. compressor) Р

LK Plate for horizontal manual adjustment of seat adjustable +/-250 mm

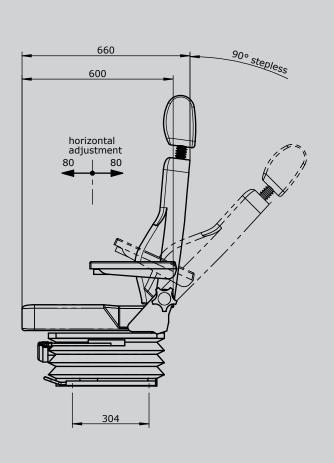
C1 Loose cover for Driver's Seat KFS 9

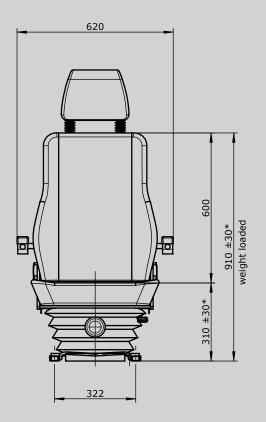
C2 Loose cover for Driver's Seat KFS 9 with V-cut

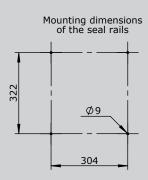
U Console (base)

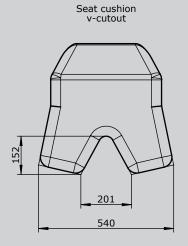












\* adjustable





The Driver's Seat KFS14 is a static seat with ergonomically designed and provides a high grade of comfort. The Driver's Seat is equipped with roller-bearing swivel system. All adjustment controls are positioned ergonomically within easy access. The metal parts are protected against corrosion and painted black.

#### Technical data:

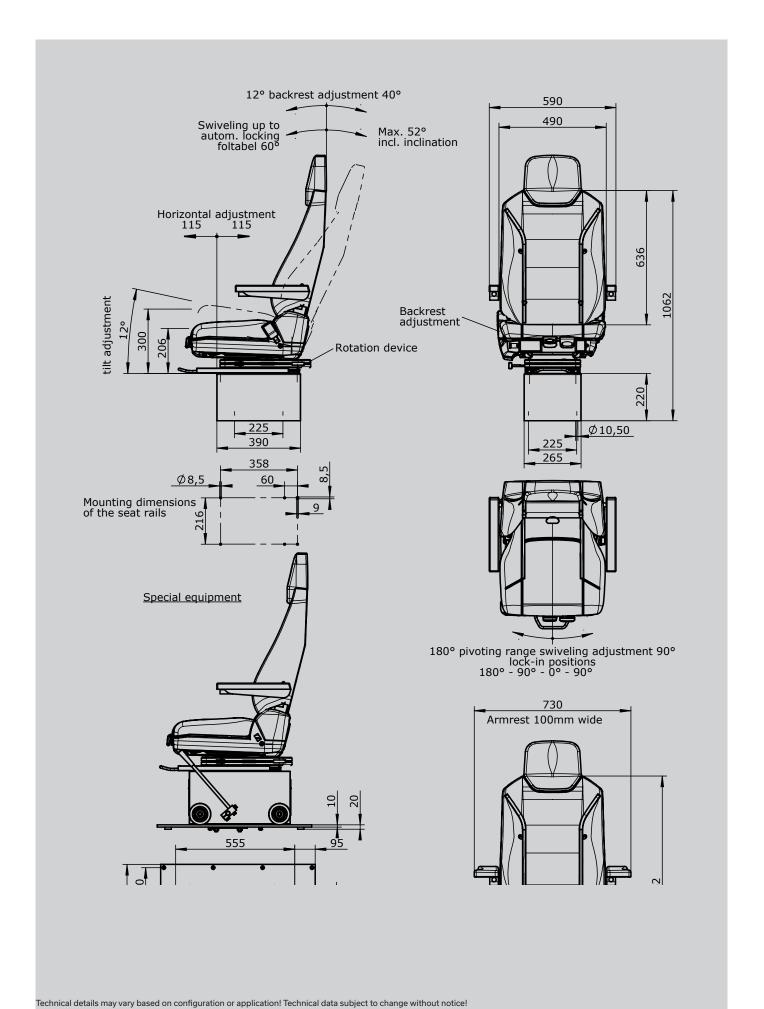
Horizontal adjustment	150 mm
Inclination of the backrest	max. 28°
Height adjustment	65 mm



Example

		KFS 14	-A1	-S1	-U
Driver's	Seat				
KFS14	Driver's Seat with textile cover black				
Attachn	nents				
К	Headrest				
A1	Armrest fully adjustable (2 pieces) 50 mm wide				
A2	Armrest fully adjustable (2 pieces) 100 mm wide				
S1	Safety belt 2-point mounting (automatic)				
S3	Safety belt 2-point mounting (static)				
U	Base frame (Apron)				









The Driver's Seat KFS4 has stepless high adjustment by means of a gas-loaded spring and an oil-hydraulic vibration absorption system with weight adjustment. The backrest can be tilted, forwards into the cushion, which in turn can then be tilted 90° sideways. All functions are performed by a simple lever operation. The metal parts are protected against corrosion and painted black.

#### Technical data:

Suspension stoke 80 mm

Weight adjustment 50 - 130 kg

Horizontal adjustment 100 mm

Inclination of the backrest max. 20°

Height adjustment 100 mm



**KFS 42** 

-A1

#### Driver's Seat

KFS41 Driver's Seat with air-permeable artificial leather cover black

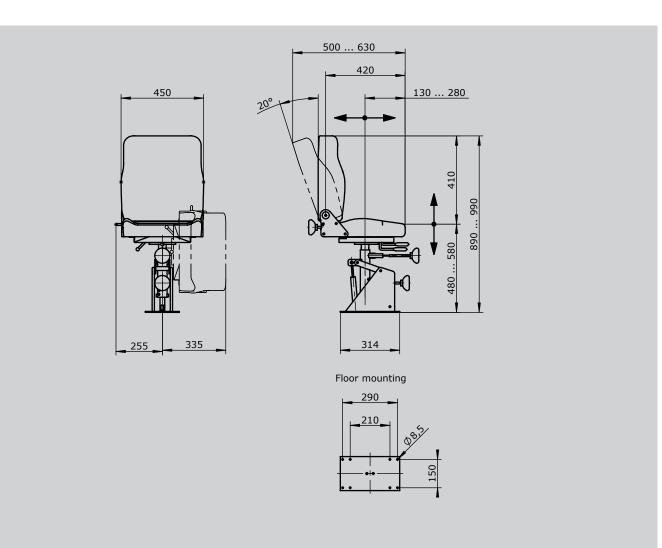
KFS42 Driver's Seat with textile cover grey / black

#### **Attachments**

A1 Armrest fully adjustable (2 pieces) 50 mm wide
A2 Armrest fully adjustable (2 pieces) 100 mm wide











The Driver's Seat KFS2 has stepless high adjustment by means of a gas-loaded spring. The backrest can be tilted, forwards onto the cushion, which in turn can then be tilted  $90^\circ$  sideways. All these functions are performed easily via levers.

#### **Technical data**

Horizontal adjustment 100 mm Inclination of the backrest max. 10° Height adjustment 120 mm



Example

**KFS 22** 

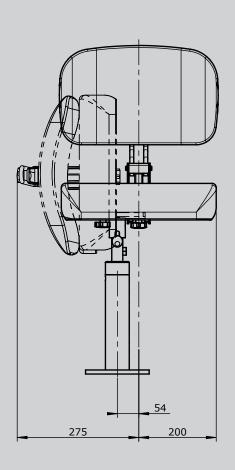
#### Driver's Seat

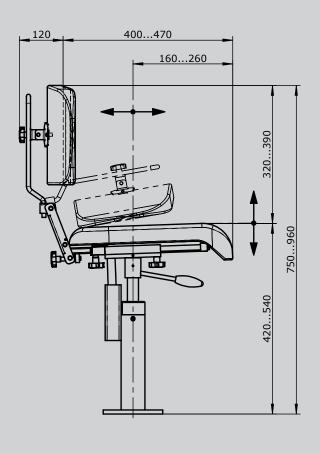
KFS21 With air-permeable artificial leather cover black

KFS22 With textile cover grey / black

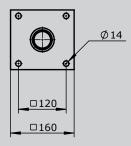








Floor mounting







The Portable Control Unit TS1 is used for controlling and monitoring the necessary equipment. The chest panel and straps enable the operator to carry it without becoming tired. An adjustable carrying strap can also be fitted for use without the chest plate.

Surface treatment:

Priming and structure-finishing paint Standard colour RAL 7032 pepple-grey

#### Technical data:

Operation temperature -40°C to +85°C

Degree of protection IP54



TS1 -SB 1 -RH 1 -K 3 -HS 1 / V... / KLS / X

	ic		

TS1 With chest plate and straps

TS11 With straps

#### Attachment

SB1 Lec	as for co	ntrol unit	t alu-tube	2 pieces
---------	-----------	------------	------------	----------

SB 2 Legs for control unit stainless steel-tube V2 A 2 pieces

RH 1 Reeling hooks for control unit stainless steel V2 A

K 1 Cable entry M32 cable 11 - 21 mm

K 2 Cable entry M40 cable 19-28 mm

K 3 Cable entry 180° swiveling M32 cable 11-21 mm

HS 1 Plug in socket 16-pole male insert HAN 16E without wiring

HB 1 Connector 16-pole female insert
 HAN 16E without wiring
 HS 2 Plug in socket 24-pole female insert
 HAN 24E without wiring

HB 2 Connector 24-pole female insert HAN 24E without wiring

HS 3 Plug in socket 32-pole male insert HAN 32E without wiring

HB 3 Connector 32-pole female insert HAN 32E without wiring Indicating labels not engraved for multi-axis-/ Single-Axis Controller

#### Mounting for equipment boxes

V Multi-Axis Controller (see page 1)

N Control-Switch (see page 113)

More command and indicating devices (see page 137 and 243)

#### Cable and wiring

Cable Ölflex Classic FD 810 P	18 x 1 mm <sup>2</sup>	13,9 mm Ø	-5°C to +70°C	each meter
Cable Ölflex Classic FD 810 P	25 x 1 mm <sup>2</sup>	16,4 mm Ø	-5°C to +70°C	each meter
Cable Ölflex Classic FD 810 P	34 x 1 mm <sup>2</sup>	18,9 mm Ø	-5°C to +70°C	each meter
Cable Ölflex Crane	18 x 1 mm <sup>2</sup>	19,2 mm Ø	-25°C to +80°C	each meter
Cable Ölflex Crane	24 x 1 mm <sup>2</sup>	22,1 mm Ø	-25°C to +80°C	each meter
Cable Ölflex Crane	36 x 1 mm <sup>2</sup>	26,1 mm Ø	-25°C to +80°C	each meter

KLS Wired on connector / plug in socket per core

KLK Wiring for cable per core

#### Special model

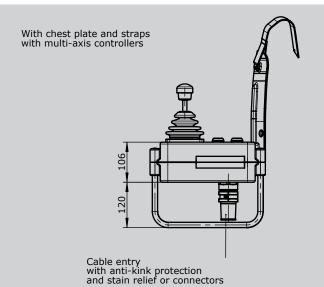
V	Special /	customer	cnacifia
^	Special /	Custoniei	Specified

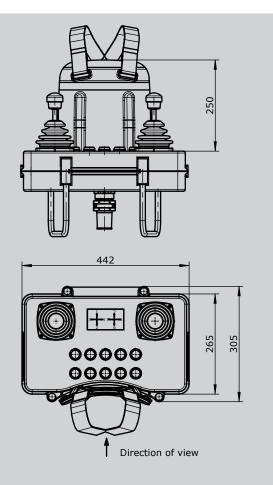
X1 Housing antistatic design < 10° Ohm/cm

X2 Finishing colour yellow RAL 1021

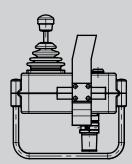


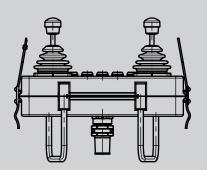






With adjustable carrying strap with multi-axis controllers









The Portable Control Unit TS2 is used for controlling and monitoring the necessary equipment. The chest panel and straps enable the operator to carry it without becoming tired. An adjustable carrying strap can also be fitted for use without the chest plate.

Surface treatment:

Priming and structure-finishing paint Standard colour RAL 7032 pepple-grey

#### Technical data:

Operation temperature -40°C to +85°C

Degree of protection IP65

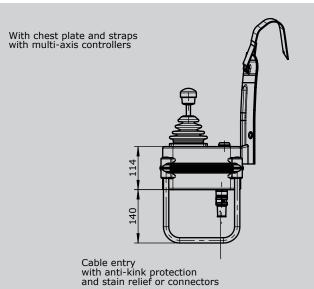


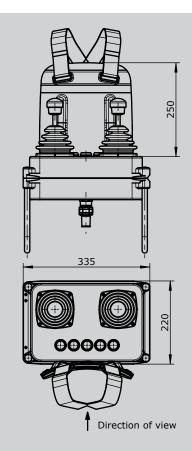
Example TS2 -SB 1 -RH 1 -К 3 -HS 1 V... **KLS** X Basic unit TS2 With chest plate, straps **TS21** With straps **TS22** With bracket and straps **Attachment** SB<sub>1</sub> Legs for control unit alu-tube 2 pieces SB 2 Legs for control unit stainless steel-tube V2 A 2 pieces Reeling hooks for control unit stainless steel V2 A RH1 К1 Cable entry M32 cable 11 - 21 mm К2 Cable entry M40 cable 19 - 28 mm КЗ Cable entry 180° swiveling M32 cable 11-21 mm HS<sub>1</sub> Plug in socket 16-pole male insert HAN 16E without wiring HB1 Connector 16-pole female insert HAN 16E without wiring Plug in socket 24-pole female insert HS<sub>2</sub> HAN 24E without wiring HB<sub>2</sub> Connector 24-pole female insert HAN 24E without wiring HAN 32E without wiring HS<sub>3</sub> Plug in socket 32-pole male insert HB3 Connector 32-pole female insert HAN 32E without wiring Indicating labels not engraved for multi-axis-/ Single-Axis Controller Indicating labels engraved for multi-axis-/ Single-Axis Controller Mounting for equipment boxes ٧ Multi-Axis Controller (see page 1) Control-Switch (see page 113) More command and indicating devices (see page 137 and 243)



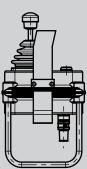
		TS 2	-SB 1	-RH 1	-К 3	-HS 1	/	V	/	KLS	/	X
Cable and wiring												
Cable Oelflex Classic FD 810 P	18 x 1 mm <sup>2</sup>	13,9 mm Ø	-5°C to +7	70°C	each me	ter						
Cable Oelflex Classic FD 810 P	25 x 1 mm <sup>2</sup>	16,4 mm Ø	-5°C to +7	70°C	each me	ter						
Cable Oelflex Classic FD 810 P	34 x 1 mm <sup>2</sup>	18,9 mm Ø	-5°C to +7	70°C	each me	ter						
Cable Ölflex Crane	18 x 1 mm <sup>2</sup>	19,2 mm Ø	-25°C to +	+80°C	each me	ter						
Cable Ölflex Crane	24 x 1 mm <sup>2</sup>	22,1 mm Ø	-25°C to +	+80°C	each me	ter						
Cable Ölflex Crane	36 x 1 mm <sup>2</sup>	26,1 mm Ø	-25°C to +	+80°C	each me	ter						
KLS Wired on connector / plug in s	ocket per core											
KLK Wiring for cable per core												
Special model												
X Special / customer specified												
X1 Housing antistatic design < 10	9 Ohm/cm											
X2 Finishing color yellow RAL 102	21											



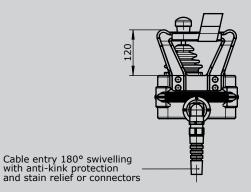


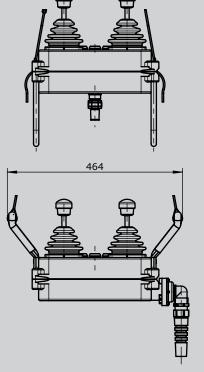






With bracket and cable entry swivelling with multi-axis controllers









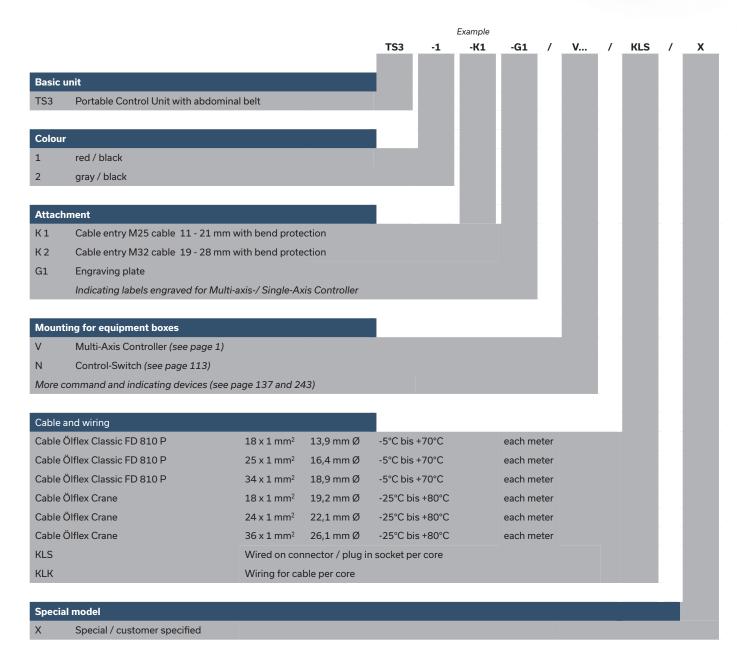
The Portable Control Unit TS3 is used for controlling and monitoring the equipment. The abdominal belt enable the operator to carry it without becoming tired. The equipment can be individually designed.

#### Technical data:

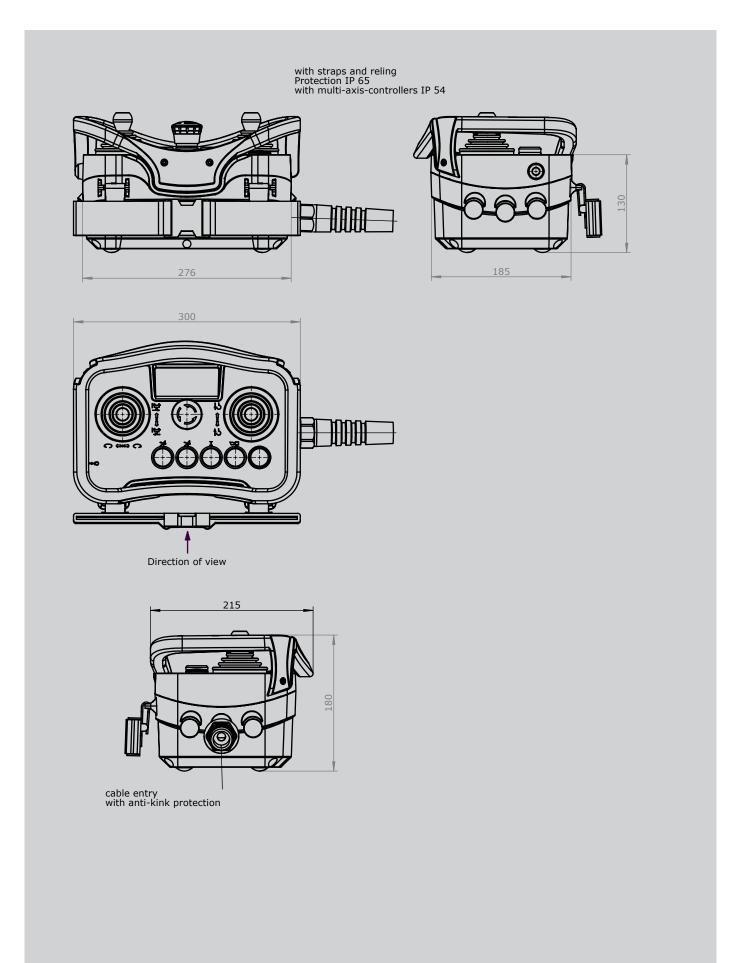
Operation temperature -40°C to +85°C

Degree of protection IP65









# **Signal-Cam Controller** NU1

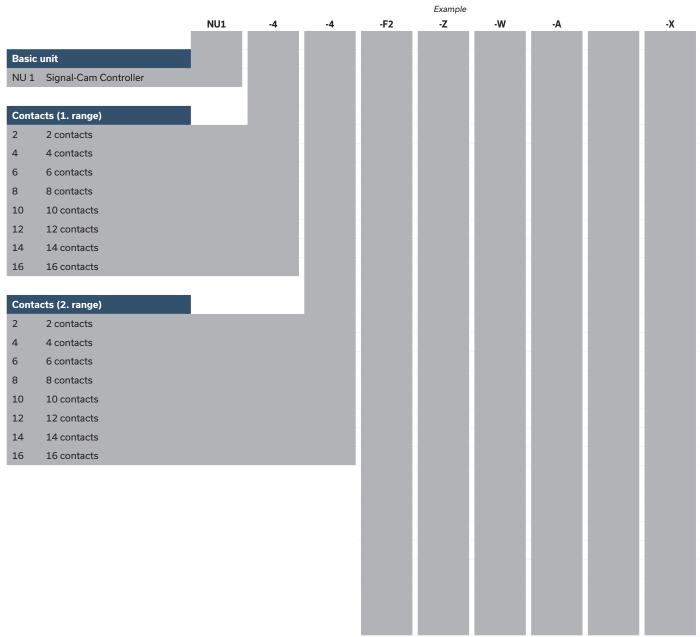


The Signal-Cam Controller NU 1 is used as a signal and annunciation switch in HV systems. This rugged switching device has cam discs made of insulation material that can be set at  $10^{\circ}$  intervals. The Signal-Cam Controllers are designed to permit series assembly, which can be operated simultaneously.

#### **Technical data**

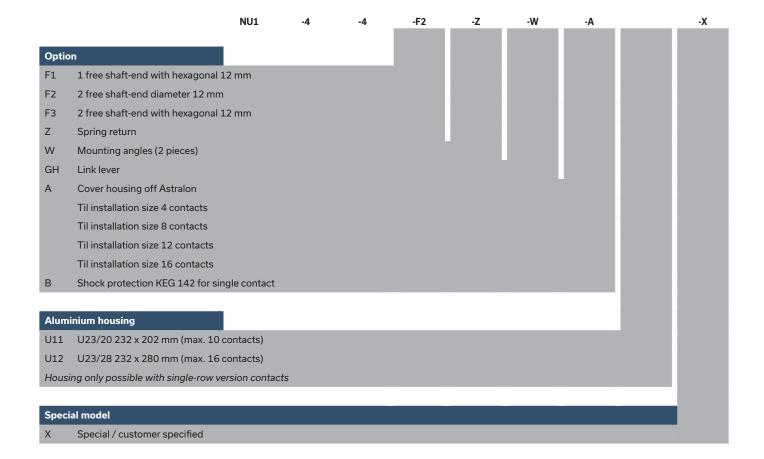
Mechanical life NU1		2 million operati	ing cycles
Operation temperatu	re	-40°C to +85°C	
Degree of protection		IP40 / IP65 with	aluminium housing
Switching capacity	NC	NO	Time constant
Switching Capacity	INC	NO	Time Constant
250 V DC	2A	1A	20 ms
125 V DC	4A	3A	20 ms
50 V DC	6A	6A	20 ms
30 V DC	10A	10A	20 ms
250 V DC15	6A	6A	





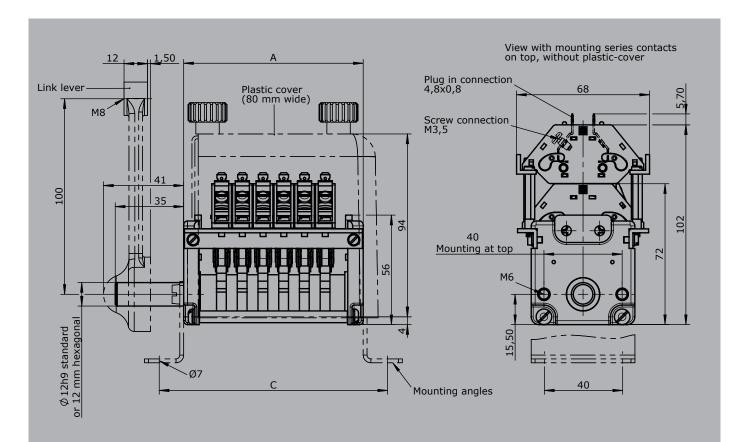
# **Signal-Cam Controller** NU1

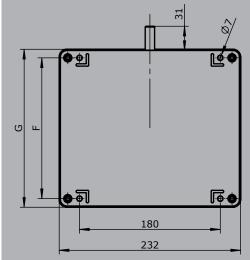


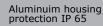


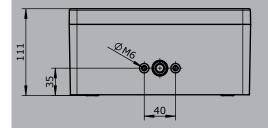
# **Signal-Cam Controller** NU1











Туре	No. of contacts	Dim. A	Dim. C	Housing	Dim. F	Dim. G
2	2	7	74			
4	4	70	95			
6	6	91	117	U 23/20	180	202
8	8	113	138			
10	10	134	159			
12	12	155	180			
14	14	176	201	U 23/28	260	280
16	16	197	222			

Technical details may vary based on configuration or application! Technical data subject to change without notice!

#### **DC Contact** SO 1.10 Normally open (NO) SS 1.10 Normally closed (NC)



The DC Contact is used for signalling and annunciation applications. The snap-action mechanism prevents slow contact opening when the plunger is operated slowly. Quenching of the arc that occurs with DC is supported by two-capacity permanent magnets.

These are arranged so that the polarity can be ignored when connecting +/- cabling. However, the polarity of the quenching magnets must be noted when installing the contacts to prevent the magnets adversely affecting each other. Contacts in four different colours are available for polarity identification of the magnets when fitted.

The contact may only be installed on non-magnetisable materials with screw, etc. made of non-ferrous metal.

The self-cleaning silver contacts are designed for low switching frequency, low currents and voltages. Gold coated contacts can be supplied (approx  $0.2\mu$ ), less than 42 Volt required. The screw connection M3.5 at the side is suitable for 2 conductors max.  $2.5 \text{ mm}^2$ . The plug-in connection at the top  $4.8 \times 0.8 \text{ mm}$  DIN 46247.

Several contacts can be plugged on the top of each other and operated jointly. The plug-type terminals are then only accessible on the top unit. The contacts can be provided with shock protection to DIN VDE 0106 Part 100.



	Switching capacity					
	NC	NO	Time constant			
250 V DC	2A	1A	20 ms			
125 V DC	4A	3A	20 ms			
50 V DC	6A	6A	20 ms			
30 V DC	10A	10A	20 ms			
250 V AC 15	6A	6A				

#### **Technical data**

Mechanical life 2 million operating cycles

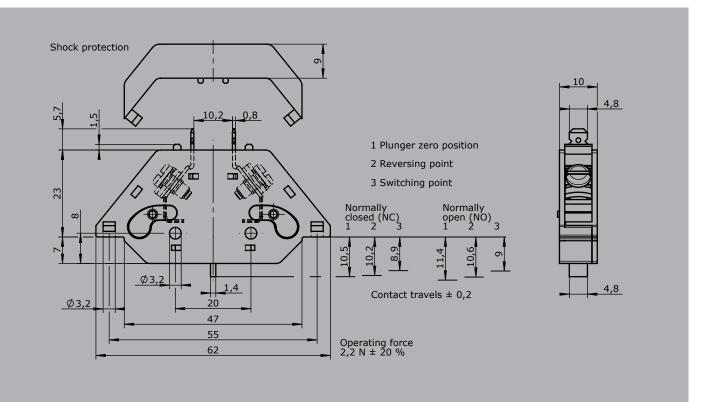
Electrical service life 50.000 operating cycles (at 2A 250 V DC L/R 20 ms)

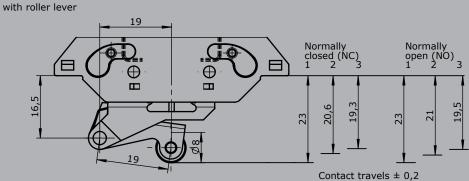
Operation temperature -40°C to +85°C

Degree of protection IP40

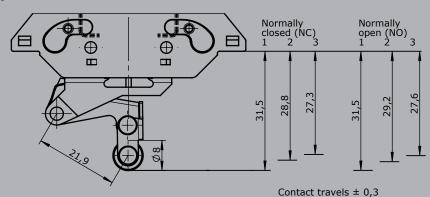
		SO 1.10	-B	-R	-F	-X
Basic un	nit	_				
SO1.10	DC-Contact normally closed (NC)					
	Colour code grey or blue					
SS1.10	DC-Contact normally open (NO)					
	Colour code yellow or green					
Attachment						
В	Shock protection KEG 142 to DIN VDE 0106 part 100					
R	Roller lever					
К	Toggle lever (switching is one direction only)					
F	Plug-in connection at side 4,8 x 0,8 mm (2 pieces)					
AU	Contacts gold-coated approx. 0,5					
Special model						
Χ	Special / customer specified					
X1	Contact without quenching magnets					











### **Gear Limit Switch**





The Gear Limit Switch GE1 / GE2 is a rugged switching device designed for hoisting applications. The modular micro changeover contacts with positive opening operation. The device is programmed by means of stepless adjustment of double cam discs, which can be provided from 18° to 192° contact discs according to the switching program required.

The type GE 1 includes a double cam disc conjointly lockable. The type GE 1 includes a double cam disc conjointly lockable.

#### **Technical data**

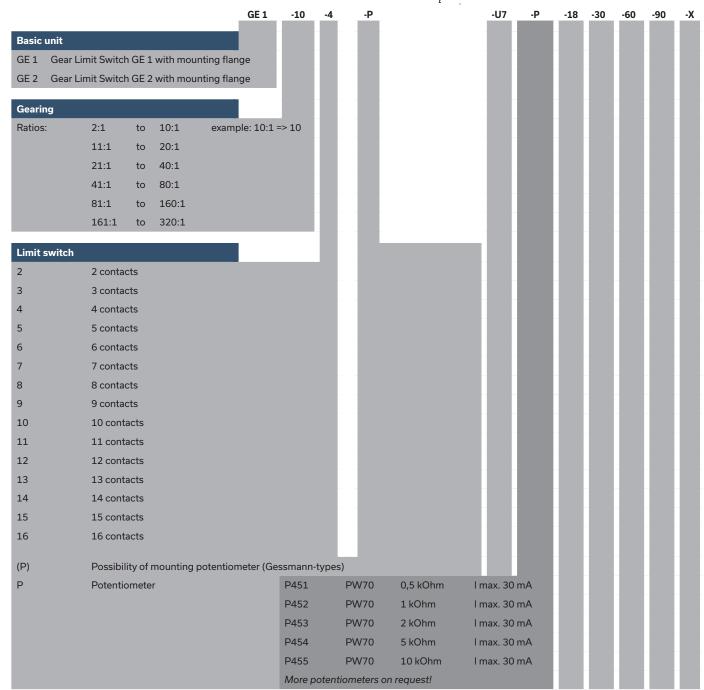
Mechanical life GE1/GE2 10 million operating cycles

Operation temperature -40°C to +85°C

IP65 Degree of protection

RAL 7032 pebble grey Colour





### **Gear Limit Switch GE1 / GE2**



GE 1 -10 -4 -P -U7 -P -18 -30 -60 -90 -X

#### **Aluminium housing**

U5 U17/13 170 x 130 mm (max. 8 contacts GE 1)

U6 U16/16 160 x 160 mm (max. 12 contacts GE 1/ max. 6 contacts GE 2)

U7 U16/20 160 x 200 mm (max. 16 contacts GE 1/max. 10 v GE 2)

U8 U16/26 160 x 260 mm (max. 16 contacts GE2)

U9 U16/35 160 x 350 mm

#### Program-disc

Following program-discs are available:

18°, 24°, 30°, 36°, 45°, 60°, 75°, 90°, 110°, 120°, 176°, 192°

#### Example:

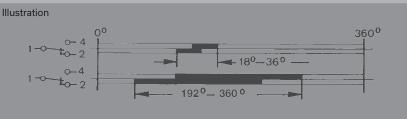
Contact 1: program-discs pair 18° (adjustment range 18°-36°)

Contact 2: program-discs pair 30° (adjustment range 30°-60°)

Contact 3: program-discs pair 60° (adjustment range 60°-120°)

Contact 4: program-discs pair 90° (adjustment range 90°-180°)

#### Contact n:



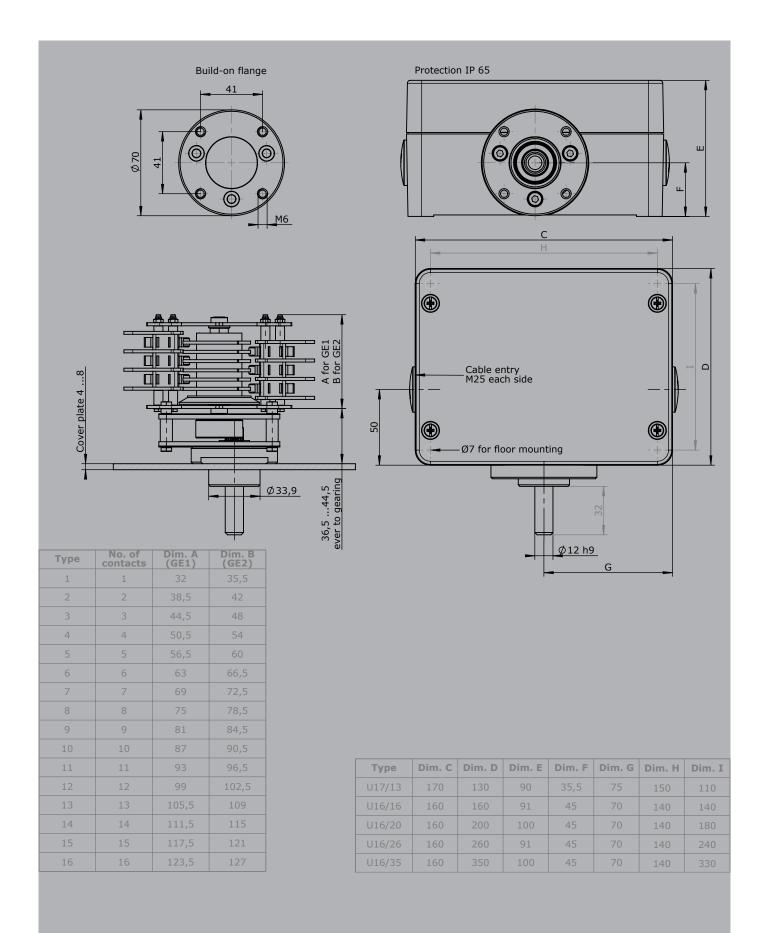
The programm-discs are infinitely adjustable within 360°

#### Special model

X Special / customer specified

# **Gear Limit Switch** GE1 / GE2





## Naval Cruise Controller





The Naval Cruise Controller AZ1 is a rugged switching device. The modular design enables the switching device to be used universally.

The design includes:

The mechanical control-system for the engine speed 0-max. rpm. switching angle 60 degrees with pressure print at 7 degrees and friction brake direction 0-2. The mechanical control-system for the steering left/right direction 13-14, 360 degrees with pressure points 4x90 degrees and friction brake.

The AZ1 is resistant to oil, maritime climate, ozone and UV radiation.

#### **Technical data**

Mechanical life AZ 1 12 million operating cycles

Operation temperature -40°C to +85°C

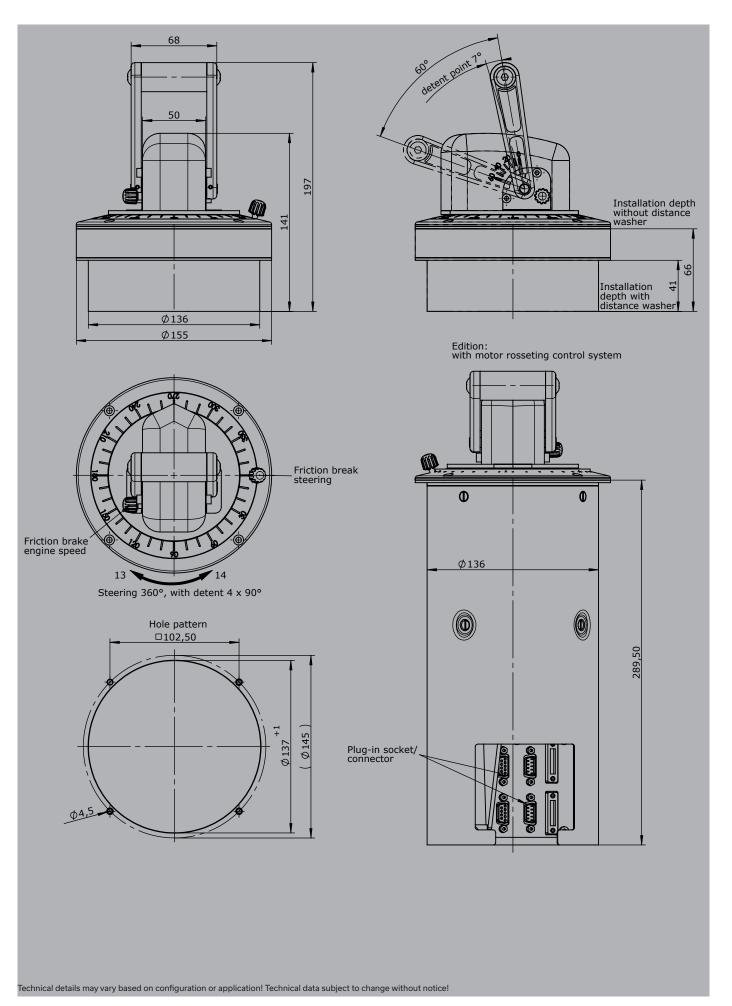
Degree of protection IP66



	AZ1	-L	E2112	
Basic unit				
AZ1 Naval cruise controller				
0.11	_			
Options  L Scale illuminated (LED) 24 V dimmable		_		
Interface				
Voltage output (not stabilized)				
Supply voltage 4,75 - 5,25 V DC				
	Characteristic: 1 = Inver	rse dual, 🛛 = Dual		
0,52,54,5 V redundant per axis		1 axis	E103 1	
		2 axis	2	
Voltage output				
Supply voltage 9 - 32 V DC (*11,5 - 32 V DC)				
	Characteristic: 1 = Inve	rse dual, 2= Dual		
0,52,54,5 V redundant per axis		1 axis	E111 1	
		2 axis	2	
Output power				
Supply voltage 9-32 V DC				
	Characteristic: = Inve	rse dual, <b>∑</b> = Dual		
41220 mA redundant per axis		1 axis	E211 1	
		2 axis	2	
Special model				
X Special / customer specified				

## **Naval Cruise Controller**







The Double-Handle Controller D3 is a robust switching device for nautical navigation applications. The modular design enables the switching device to be used universally. The Double-Handle Controller is resistant to oil, maritime conditions e.g. offshore /vessels, UV radiation typically from the sun.

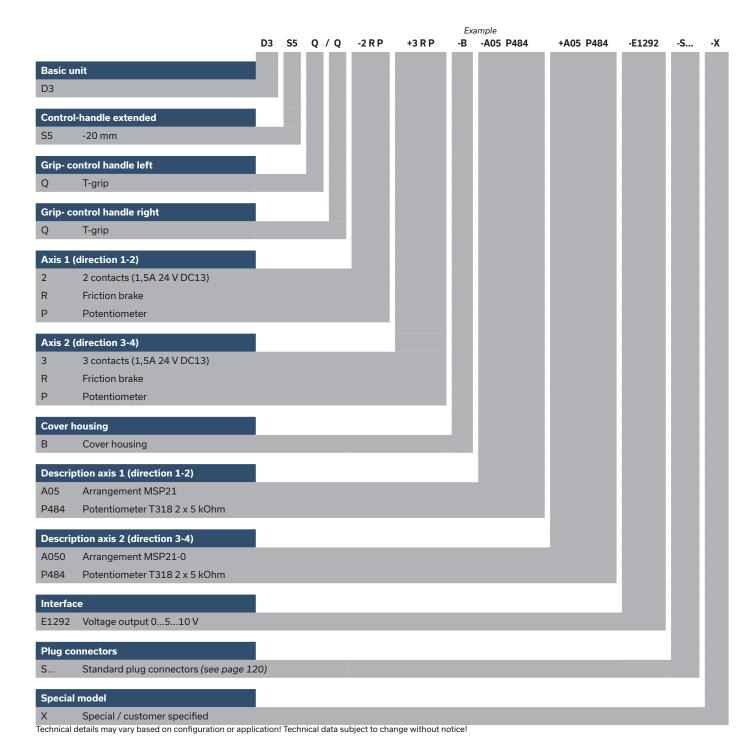
### **Technical data**

Mechanical life D3 12 million operating cycles

Operation temperature -40°C to +85°C

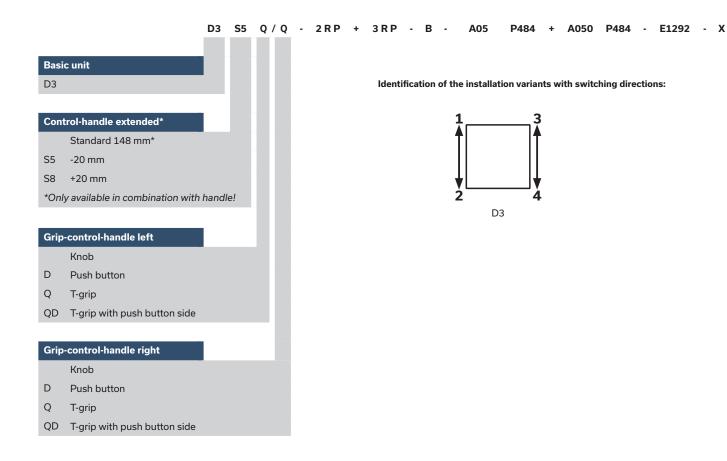
Degree of protection IP66 front







P484 + A050 P484 - E1292 - X



Axis	1: direction 1-2 left	
1	1 contact	Standard contact- arrangement see page 122
2	2 contacts	e.g.
3	3 contacts	A98 MS0
		A05 MS21
		A050 MS21-0
		A99 contact - arrangement according customer request
R	Friction brake	
(P)	Mounting options for potentiometer	er and (Gessmann-types)
Р	Potentiometer	P484 T318 2 x 5 kOhm I max. 1 mA
		More potentiometers on request!
Н	Hall-Potentiometer	E14811 0,52,54,5 V / 4,52,50,5 V

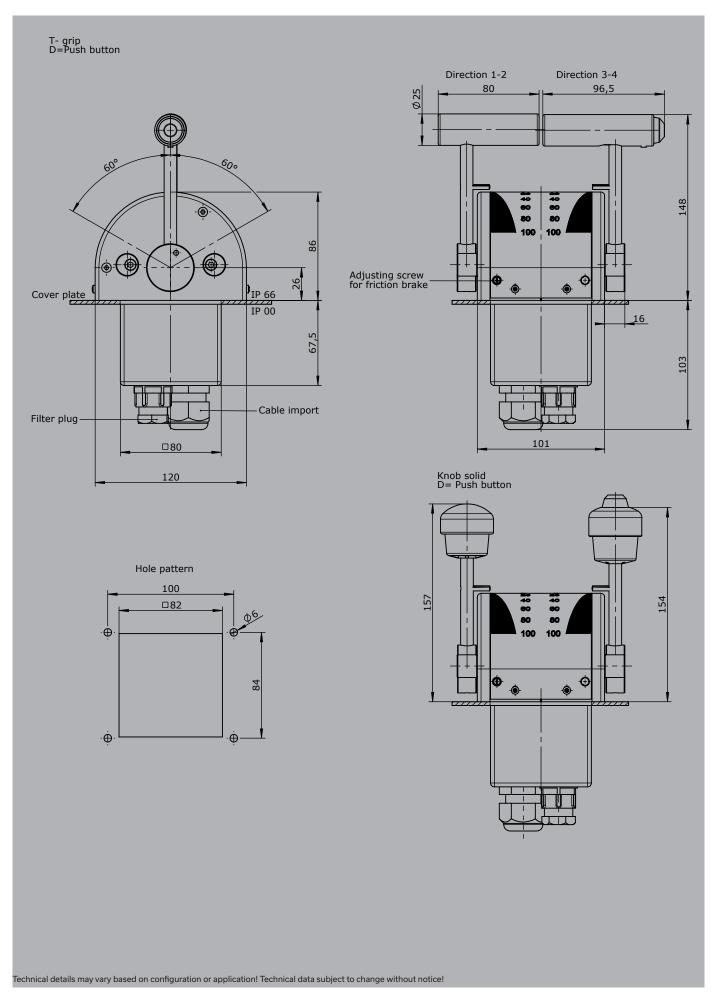
A05

Q/Q - 2RP + 3RP - B -



3 R P - B - A05 P484 S5 Q/Q -2 R P A050 P484 E1292 -Axis 2: direction 3-4 left 1 Standard contact- arrangement see page 122 1 contact 2 2 contacts e.g. 3 contacts MS0 3 A98 A05 MS21 A050 MS21-0 A99 contact - arrangement according customer request R Friction brake (P) Mounting options for potentiometer (Gessmann-types) Ρ Potentiometer P484 T318 2 x 5 kOhm I max. 1 mA More potentiometers on request! 0,5...2,5...4,5 V / 4,5...2,5...0,5 V Hall-Potentiometer E14811 P484 D3 S5 Q/Q 2 R P 3 R P В A05 A050 P484 E1292 -Cover housing В Cover housing Interface (description the following pages) Potentiometer output E1xx Voltage output E2xx Current output Special model Special / customer specified Voltage outputs 11,5-32 V DC Supply voltage Wiring Cable 300 mm long without plug connector S Optional with plug connector (standard plug connectors see page 120) 0...5...10 V per axis E129 1 1 axis 2 2 axis 10...0...10 V per axis 1 axis E141 1 2 axis 2 -10...0...+10 V per axis 1 axis F1401 2 axis 2 Voltage output with other value on request! **Current outputs** Supply voltage 18-36 V DC Wiring Cable 500 mm long without plug connector S Optional with plug connector (standard plug connectors see page 120) 4...12...20 mA per axis E209 1 1 axis 2 axis 2 20...4...20 mA per axis 1 axis E217 1 2 axis









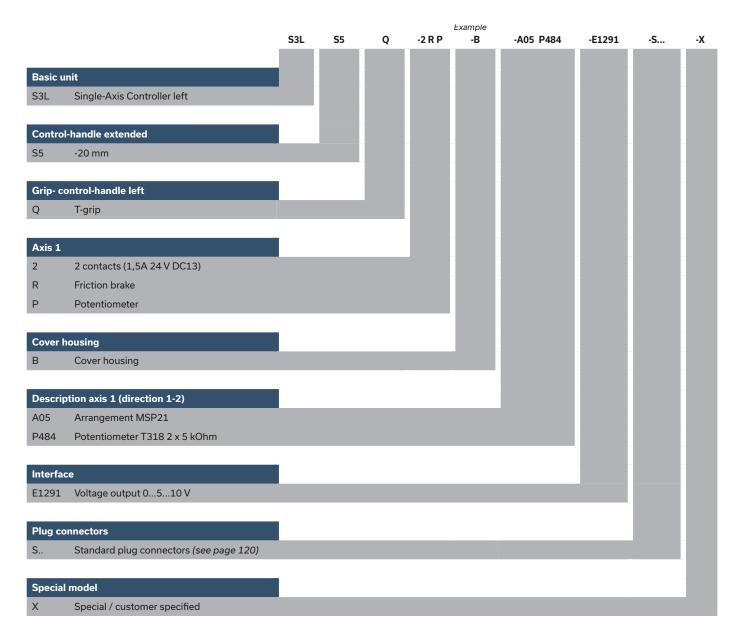
The Single-Axis Controller S3 is a rugged switching device for hoisting applications. The modular design enables the switching device to be used universally. The Single-Axis Controller is resistant to oil, maritime conditions e.g. offshore /vessels, UV radiation typically from the sun

### **Technical data**

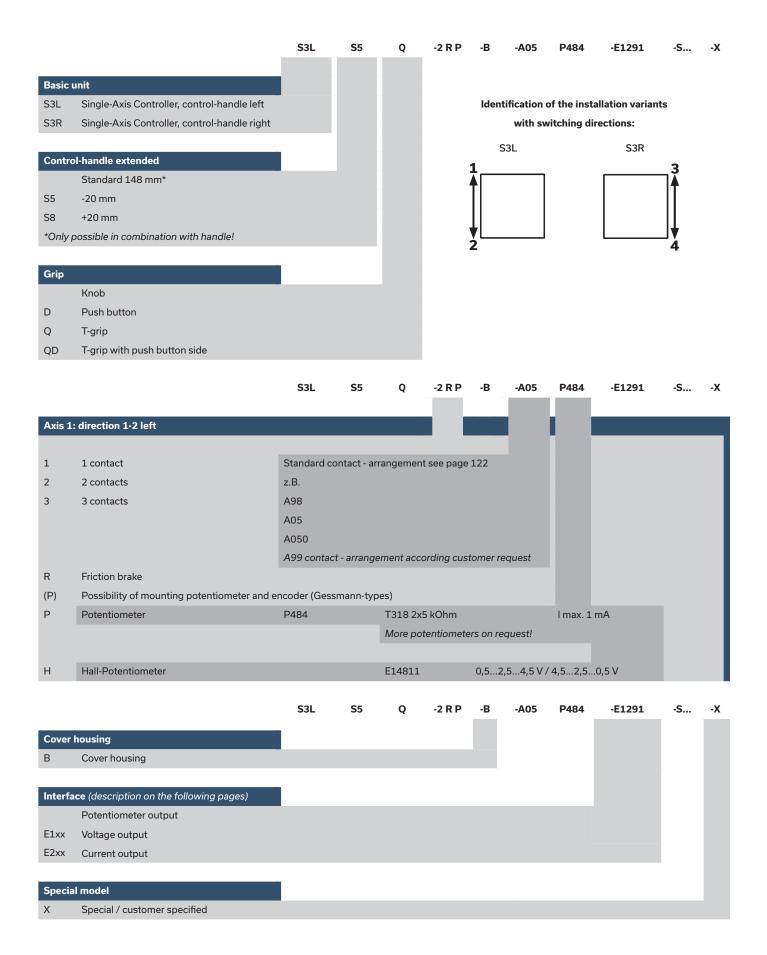
Mechanical life S3 12 million operating cycles

Operating temperature -40°C to +85°C
Degree of protection IP66 front







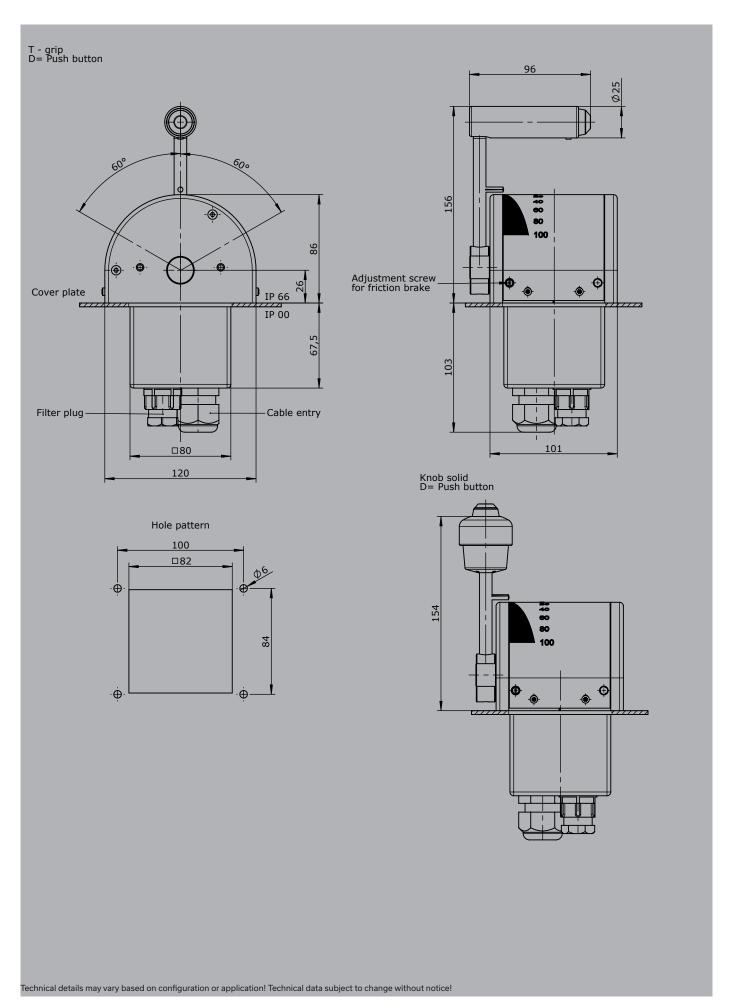




Voltage output								
Supply voltage	11,5-32 V DC							
Wiring	Cable 500 mm long without plug connector							
	Optional with plug connector (standard plug connector	ional with plug connector (standard plug connectors see page 120)						
0510V								
		1 axis	E112 1					
10010V								
		1 axis	E141 1					
-100+10V								
		1 axis	E140 1					
Voltage output with other value	e on request!							

Current output		
Supply voltage	18-36 V DC	
Wiring	Cable 500mm long without plug connector	
	Optional with plug connector (standard plug connectors see page 120)	S
41220 mA		
	1 axis	E209 1
20420 mA		
	1 axis	E217 1









The Single-Axis Controller S23 is a robust switching device for shipbuilding and electro-hydraulic applications. The modular design of the switching device is universally applicable. The Single-Axis Controller is resistant to oil, maritime conditions e.g. offshore /vessels, UV radiation typically from the sun.

### **Technical data**

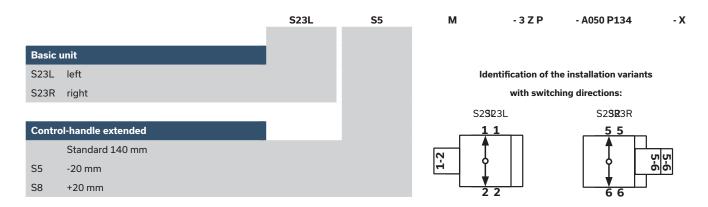
Mechanical life S23 6 million operating cycles

Operating temperature -40°C to +85°C

Degree of protection IP65



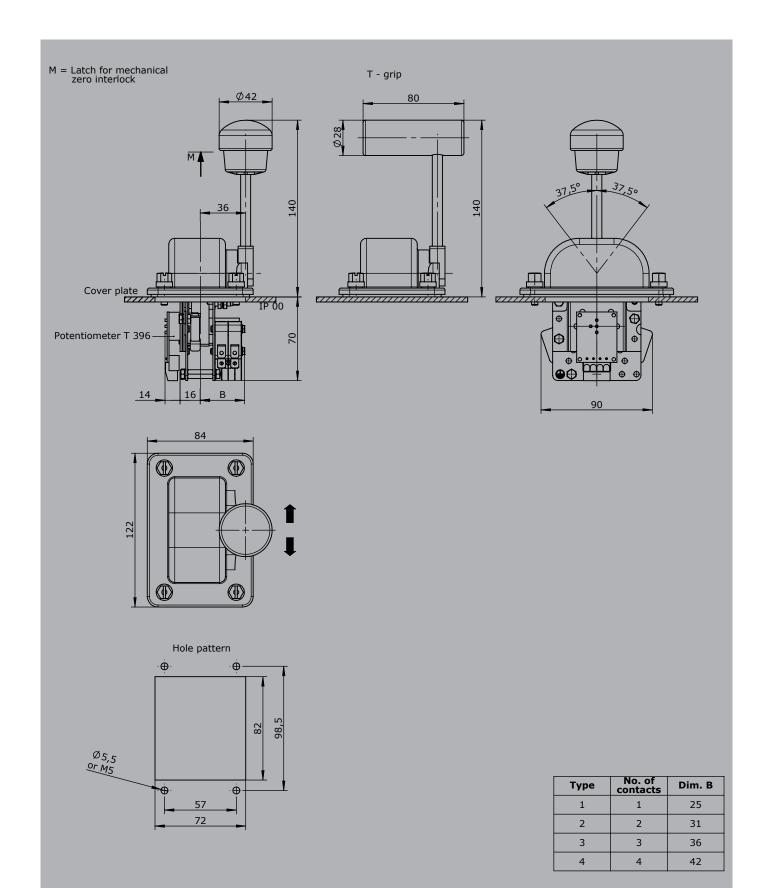
S23L - A050 P134 S5 М - 3 Z P - X Basic unit S23L left Control-handle extended -20 mm Grip / palm grip Mechanical zero interlock Axis 1 (direction 1-2) 3 contacts (2A 250 V AC15) 3 Z Spring return Ρ Potentiometer Description axis 1 (direction 1-2) A050 Arrangement MSP21-0 P134 Potentiometer T396 2 x 5 kOhm Special model Special / customer specified





		S23L	<b>S</b> 5	М	- 3 Z P	- A050 P134	- X
Grip	/ palm grip						
	Knob (standard)						
М	Mechanical zero interlock						
Q	T-grip						
QM	T-grip with mechanical zero interlock						
		S23L	S5	М	- 3 Z P	- A050 P134	- X
Axis	1: direction 1-2 left / direction 5-6 right						
L	1 contact	Standard contac	ct - arrangement	see page 122			
2	2 contacts	z.B.					
3	3 contacts	A98			MS0		
ļ	4 contacts	A05			MS21		
		A0500			MS21-00		
		A99 contact - ar	rangement acco	rding customer re	quest		
_							
7	Spring return						
₹.	Friction brake						
P)	Possibility of mounting potentiometer and encode						
)	Potentiometer	P131		T396 2 x 0,5 kO		I max. 1 mA	
		P132		T396 2 x 1 kOhr		I max. 1 mA	
		P133		T396 2 x 2 kOhr		I max. 1 mA	
		P134		T396 2 x 5 kOhr		I max. 1 mA	
		P135		T396 2 x 10 kOł	ım	l max. 1 mA	
		More potentiom	eters on request	:!			
С	Encoder	C Encoder see	page 130				
		S23L	<b>S</b> 5	М	- 3 Z P	- A050 P134	- X
Spec	ial model						
Κ .	Special / customer specified						





Technical details may	AVOR	based on confid	guration or an	nlication!	Tochnical data sub	iact to chang	o without notical
recililical details may	y vai	, pased on coming	juration or ap	plication:	recillical data sub	Ject to charly	e without notice:



The Single-Axis Controller S27 is a hall sensor switching device designed for electro-hydraulic and remote controlled hydraulic. The modular design of the switching device is universally applicable. The Single-Axis Controller is resistant to oil, maritime conditions e.g. offshore /vessels, UV radiation typically from the sun.

### **Technical data**

Mechanical life S27

Operating temperature

Degree of protection

Functional safety

6 million operating cycles

-40°C to +85°C

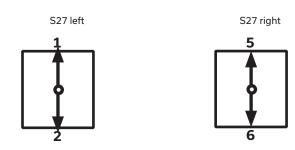
up to IP65, electronic assembly IP67

PLd compatible (EN ISO 13849, complies SIL2 to DIN EN IEC 61508)



S27L - Z М - E... - S... - X Basic unit S27L left S27R right Grip / palm grip Knob (standard) M Mechanical zero interlock Q T-grip Ζ Spring return R Friction brake **Interface** (description on the following pages) E0xx Digital output E1xx Voltage output E2xx Current output Plug connectors Standard plug connectors (see page 120) Special model Special / customer specific

### Identification of the installation variants with switching directions:

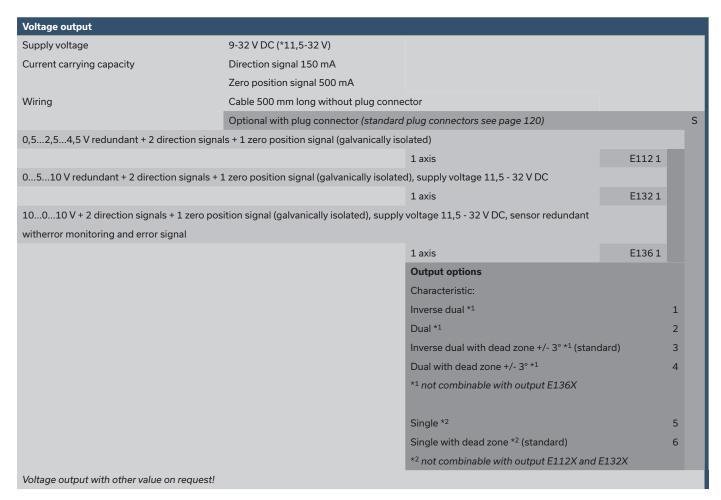


Technical details may vary based on configuration or application! Technical data subject to change without notice!



Digital Output			
Supply voltage	9-32 V DC		
Current carrying capacity	Direction signal 150 mA		
	Zero position signal 500 mA		
Wiring	Cable 500 mm long without plug conne	ector	
	Optional with plug connector (standard	plug connectors see page 120)	S
2 direction signals + 1 zero position signal (g			
		1 axis	E0011

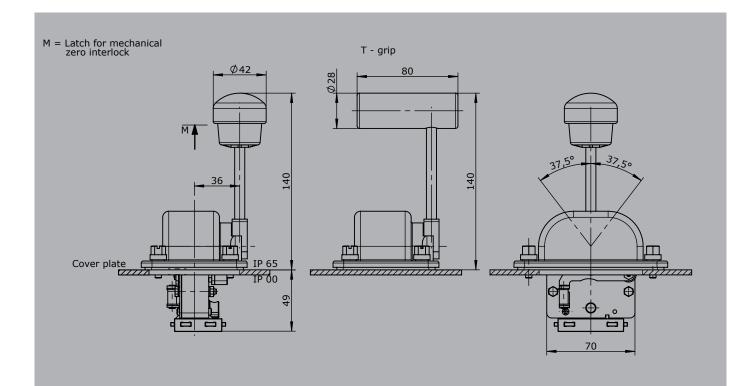
Voltage output (not stabilized)				
Supply voltage	4,75-5,25 V DC			
Current carrying capacity	Direction signal 8 mA			
Wiring	Cable 500 mm long without plug conn	ector		
	Optional with plug connector (standard	d plug connectors see page 120)		S
0,52,54,5 V redundant + 2 direction sig	nals			
		1 axis	E104 1	
		Output options		
		Characteristic:		
		Inverse dual		1
		Dual		2
		Inverse dual with dead zone +/- 3° (standard)		3
		Dual with dead zone +/- 3°		4

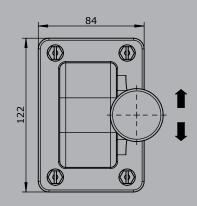


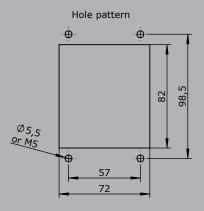


Current output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Wiring	Cable 500 mm long without plug connector			
	Optional with plug connector (standard plug connectors se	e page 120)		S
01020 mA + 2 direction s	ignals + 1 zero position signal (galvanically isolated), sensor rec	dundant with error monitoring a	and error signal	
		1 axis	E206 1	
20020 mA + 2 direction s	ignals + 1 zero position signal (galvanically isolated), sensor rec	dundant with error monitoring a	ind error signal	
		1 axis	E208 1	
41220 mA + 2 direction s	ignals + 1 zero position signal (galvanically isolated), sensor rec	dundant with error monitoring a	and error signal	
		1 axis	E214 1	
20420 mA + 2 direction s	ignals + 1 zero position signal (galvanically isolated), sensor rec	dundant with error monitoring a	and error signal	
		1 axis	E216 1	
		Output options		
		Single		5
		Single with dead zone +/-3° (	standard)	6
Current output with other val	lue on request!			









## **Control Pedestal** (U22/32





The Control Pedestal U22/32 accomodate the devices necessary for control and monitoring. Ready wired, it can be quickly and easily installed on the sea deck. The housing (pedestal head) is made of seawater-resistant aluminium.

Surface treatment: Priming and structure-finishing paint Standard colour RAL 7032 pepple-grey

### Technical data:

Operation temperature -40°C to +85°C

Degree of protection IP66



Example

			U22/32		/	N61/ N62	/	H / PW / 2D	/	PQ	/	KLV	/	Х
Hous	ing													
U22/3	32 With 1 narro	w side-plate with pilla	r-gasket											
FD	Side-plate n	arrow gasket												
HD	Side-plate w (required for	ride gasket r command and indica	ting devices)											
KD	Hinged side	-plate with gasket that	can be locked in posit	ion										
IA	72 x 72 mm	devices cover with gas or 4 monitors 72 x 36 evices pos. 28, 29	ket for max. 2 monitor mm and max. 6	S										
RS	Pillar 108 m	m Ø 670 mm height w	ith flange quadratic or	round										
Maste	erswitch / Contr	ol-Switch												H
N61	HG Masters	witch with ball handle	and indicating labels											
N62	KN Control-	Switch with knob and i	indicating label											
			-HG -01 Z P	-A05		P134 -X			_					
Axis 1	1: direction 3-4								-	-				
	(Standard conta	acts gold-plated 2A 25	0 V AC15)						-					
01	2 contacts	Standard contact - a	rrangement see page :	122										
02	4 contacts	z.B.												
03	6 contacts	A05	MS21						_					
04	8 contacts	A0500	MS21-00											
		A99 contact - arrang	ement according cust	omer reques	t				_					
Z	Spring return													
R	Friction brake													
Р	Potentiometer	P131	T396 2 x 0,5 kOhm	l max. 1 m	ıΑ									
		P132	T396 2 x 1 kOhm	l max. 1 m	ıΑ				-					
		P133	T396 2 x 2 kOhm	l max. 1 m	ıΑ									
		P134	T396 2 x 5 kOhm	l max. 1 m	ıΑ									
		P135	T396 2 x 10 kOhm	l max. 1 m	ıΑ									
		More potentiometers	s on request!											

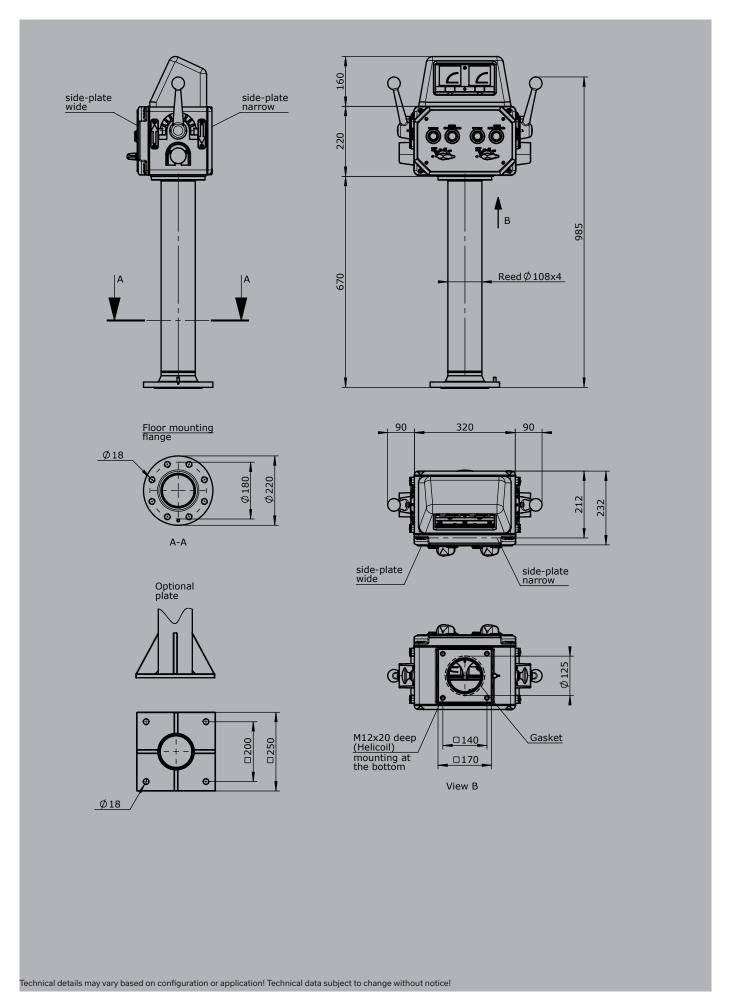
## **Control Pedestal** U22 / 32



		U22/32	/	N61/N62	/	H / PW / 2D	/	PQ	/	KLV	/	X
Com	mand and indicating devices	ı										
Н	Heating	20 Watt 220 or 110V 50/60 Hz	<u> </u>									
PV	Mushroom head push button latching	22 latching with indicating labe	el	1 NC								
Р	Mushroom head push button	22 with indicating label		1 NO								
D	Push button	22 with indicating label		1 NO								
W	Selector switch 0-1	22 with indicating label		1 NO								
L	Indicator light	22 with indicating label		Diode 24 Volt								
L	Indicator light	22 with indicating label		Diode 230 Volt A	С							
	Contact block additional			1 S or 1 Ö								
L	Indicator light	22 with indicating label		Diode 24 Volt pro	tecti	on IP65						
L	Indicator light	10 with indicating label		Diode 24 Volt pro	tecti	on IP65						
Disp	ay devices											
PQ	Powermeter PQ 72 1 mA DC		Eng	raved your instruct	tions							
PQI	Powermeter PQ 72 1 mA DC illuminated	24 Volt	Eng	raved your instruct	tions							
PQ	Powermeter PQ 72 x 36 1 mA DC		Eng	raved your instruct	tions							
PQI	Powermeter PQ 72 x 36 1 mA DC illumin	ated 24 Volt	Eng	raved your instruct	tions							
EQ	Amperemeter EQ 72 100/200/1A		Eng	raved your instruct	tions							
EQI	Amperemeter EQ 72 100/200/1A illumin	nated 24 Volt	Eng	raved your instruct	tions							
EQ	Amperemeter EQ 72 x 36 100/200/1A		Eng	raved your instruct	tions							
EQI	Amperemeter EQ 72 x 36 100/200/1A ill	luminated 24 Volt	Eng	raved your instruct	tions							
		_										
Wirir	ng											
KLV c	on terminal block 2,5mm² with wire line 0,7	5 mm <sup>2</sup>										
Spec	ial model											
X	Special / customer specified											

## **Control Pedestal** U22 / 32





## Control Pedestal



The Control Pedestal U23/23 accomodate the devices necessary for control and monitoring. Ready wired, it can be quickly and easily installed on the sea deck. The housing (pedestal head) is made of seawater-resistant aluminium.

Surface treatment: Priming and structure-finishing paint Standard colour RAL 7032 pepple-grey

### Technical data:

Operation temperature -40°C to +85°C

Degree of protection IP66



U23/23 / N61.../N62... / H / PW / 2D / PQ / KLV / X

E>

Housing	
U23/23	With 1 narrow cover with pillar-gasket
U23/23A	With 1 narrow cover without drilling in the housing
IA	Monitoring devices cover with gasket for max. 2 monitors $72 \times 72$ mm or 4 monitors $72 \times 36$ mm and max. 6 indicating devices pos. 28, 29
RS	Pillar 108mm Ø 670 mm height with flange quadratic or round

### Masterswitch / Control-Switch

N61 HG Masterswitch with ball handle and indicating labels
N62 KN Control-Switch with knob and indicating label

			-HG	-01 Z P	-A05	P134	-X
Axis	1: direction 3-4						
	(Standard conta	cts gold-plated 2A 250 V	AC15)				
01	2 contacts	Standard contact - arran	gement s	ee page 122			
02	4 contacts	z.B.					
03	6 contacts	A05		MS21			
04	8 contacts	A0500		MS21-00			
		A99 contact - arrangeme	ent accord	ling customer	request		
Z	Spring return						
R	Friction brake						
Р	Potentiometer	P131	T396 2	c 0,5 kOhm	l max. 1 mA		
		P132	T396 2	k 1 kOhm	l max. 1 mA		
		P133	T396 2	k 2kOhm	l max. 1 mA		
		P134	T396 2	k 5 kOhm	l max. 1 mA		
		P135	T396 2	k 10 kOhm	l max. 1 mA		
		More potentiometers on	request!				

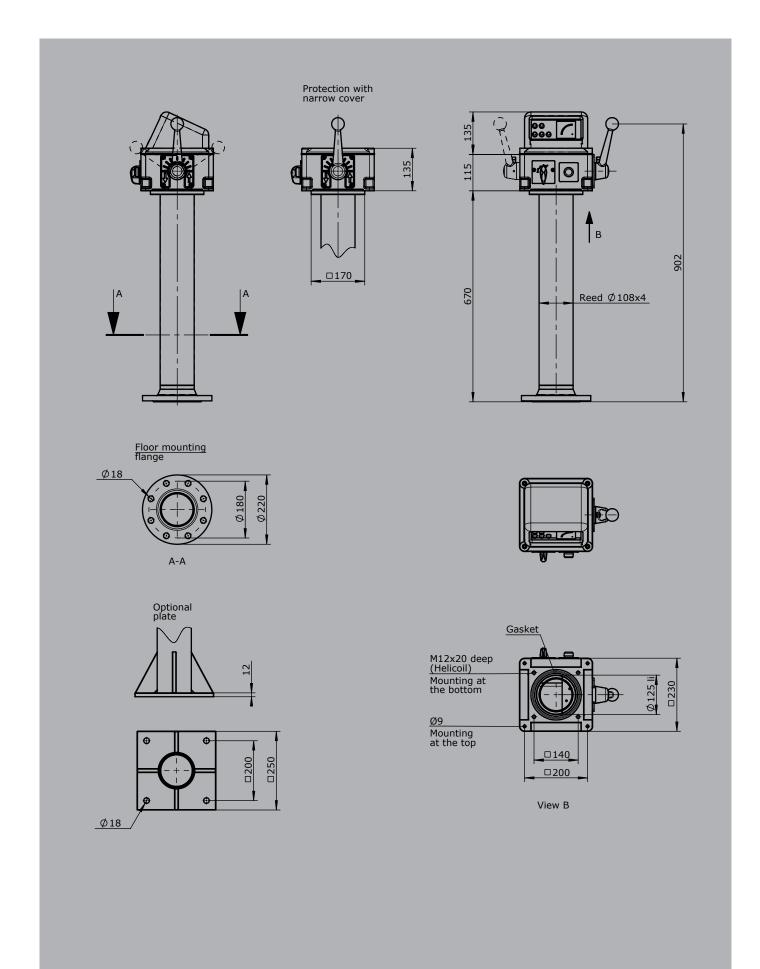
### Control Pedestal



U23/23 N61.../N62... / H / PW / 2D / PQ / KLV Command and indicating devices Н 20 Watt 220 or 110V 50/60 Hz Heating PV Mushroom head push button latching 22 latching with indicating label 1Ö Ρ 22 with indicating label 1 S Mushroom head push button D 1 S Push button 22 with indicating label W Selector switch 0-1 22 with indicating label 1 S L Indicator light 22 with indicating label Diode 24 Volt Indicator light 22 with indicating label Diode 230 Volt AC L Contact block additional 1 S or 1 Ö Diode 24 Volt protection IP65 L Indicator light 22 with indicating label ı Indicator light 10 with indicating label Diode 24 Volt protection IP65 Display devices Powermeter PQ 72 1 mA DC PQ Engraved your instructions PQI Powermeter PQ 72 1 mA DC illuminated 24 Volt Engraved your instructions PQ Powermeter PQ 72 x 36 1 mA DC Engraved your instructions PQI Powermeter PQ 72 x 36 1 mA DC illuminated 24 Volt Engraved your instructions Amperemeter EQ 72 100/200/1A EQ Engraved your instructions EQI Amperemeter EQ 72 100/200/1A illuminated 24 Volt Engraved your instructions EQ Amperemeter EQ 72 x 36 100/200/1A Engraved your instructions EQI Amperemeter EQ 72 x 36 100/200/1A illuminated 24 Volt Engraved your instructions Wiring KLV on terminal block 2,5 mm<sup>2</sup> with wire line 0,75 mm<sup>2</sup> Special model Special / customer specified

## **Control Pedestal** U23 / 23





### **Dealer network** worldwide

Phoenix Engineering Solutions FZ LIF

Al Saaha Offices B

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Dealer

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Phoenix Engineering Solutions FZ

Al Saaha Offices B

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